

TorchSpatial: A Location Encoding Framework and Benchmark for Spatial Representation Learning

NeurIPS 2024

Nemin Wu, Qian Cao*, Zhangyu Wang, Zeping Liu, Yanlin Qi, Jielu Zhang, Joshua Ni, X. Angela Yao,
Hongxu Ma, Lan Mu, Stefano Ermon, Tanuja Ganu, Akshay Nambi, Ni Lao, Gengchen Mait†*

** Both authors contributed equally to this research*

† Corresponding author



UNIVERSITY OF
GEORGIA



SPATIALLY
EXPLICIT AI



TEXAS
The University of Texas at Austin

Motivation

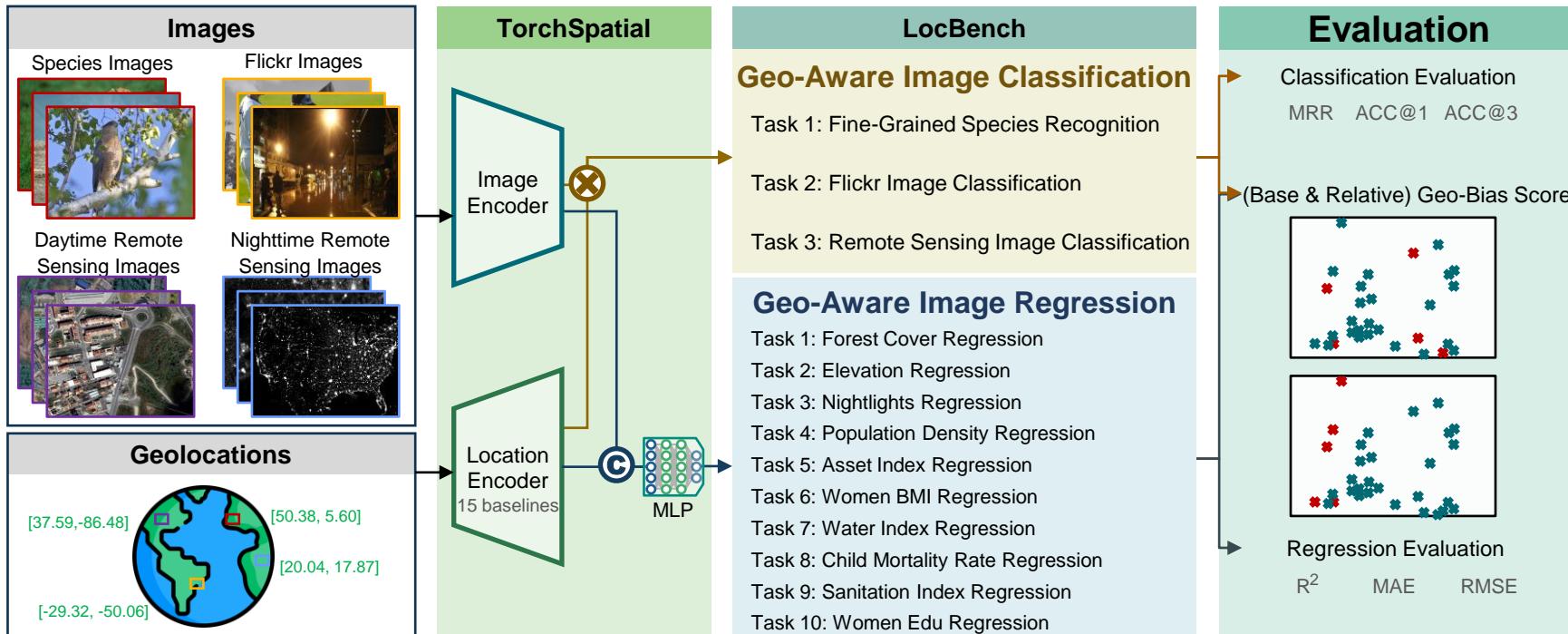
Spatial representation learning (SRL) is a set of techniques learning neural spatial representations from spatial data in their native formats while avoiding manual feature engineering or data conversion.

- 1. Lack of a community-shared framework** for SRL model development
- 2. Lack of benchmarks** to systematically evaluate the location encoders' impact on model performance
- 3. Lack of evaluations on the geographic bias** of geo-aware AI approaches

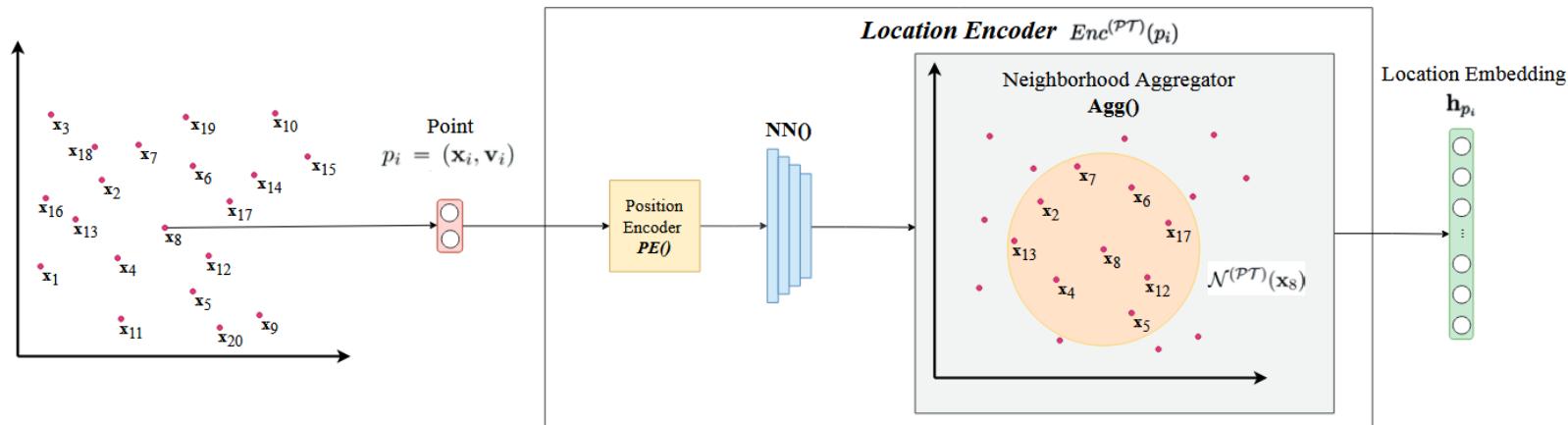
TorchSpatial

- **A model framework** that consolidates **15 location encoders** and necessary model building blocks for future location encoders.
- **A benchmark** which contains 7 geo-aware image classification and 10 image regression datasets.
- **A set of evaluation metrics** to quantify location encoders' overall model performance and their **geographic bias**.

TorchSpatial Framework



TorchSpatial Framework – Location Encoder



$$Enc(\mathbf{x}) = \mathbf{NN}(PE(\mathbf{x}))$$

$\mathbf{x} \in \mathbb{R}^L \ (L = 2, 3) : \text{input location}$

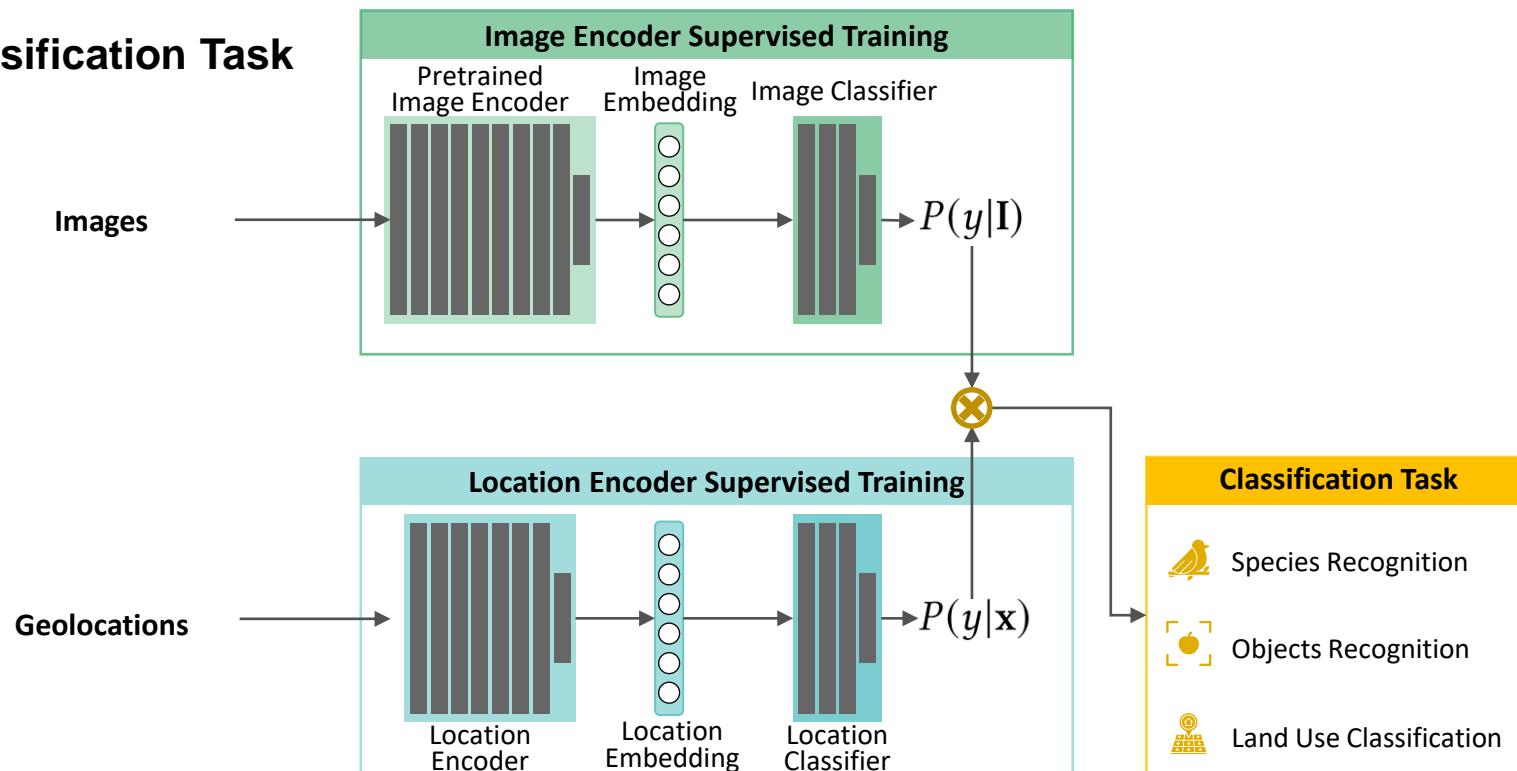
$PE(\mathbf{x}) \in \mathbb{R}^W : \text{position encoder}$

$\mathbf{NN}(\cdot) : \mathbb{R}^W \rightarrow \mathbb{R}^d : \text{learnable neural nets}$

Mai, Gengchen, et al. "A review of location encoding for GeoAI: methods and applications." *International Journal of Geographical Information Science*

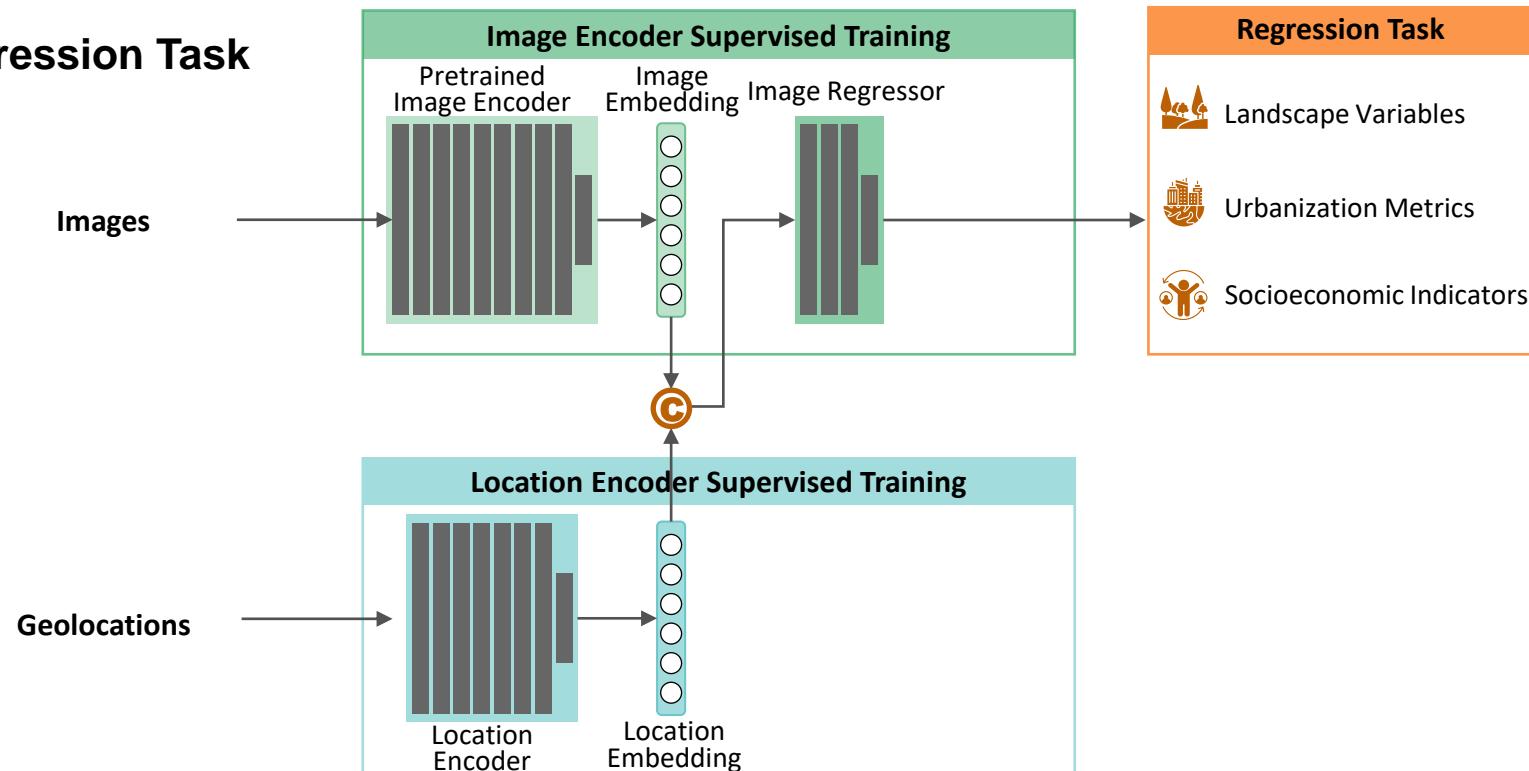
TorchSpatial Framework – Inference Architecture

- Classification Task



TorchSpatial Framework – Inference Architecture

- Regression Task



LocBench

Geo-Aware Image Classification

Classify a given image into its correct category based on the image itself and location metadata.

Task 1: Fine-Grained Species Recognition

BirdSnap	500 categories	19,576 examples
BirdSnapt	500 categories	43,470 examples
NABirds†	555 categories	23,699 examples
iNat2017	5,089 categories	675,170 examples
iNat2018	8,142 categories	461,939 examples

Task 2: Flickr Image Classification

YFCC	100 categories	36,146 examples
------	----------------	-----------------

Task 3: Remote Sensing Image Classification

fMoW	63 categories	416,612 examples
------	---------------	------------------

Geo-Aware Image Regression

Given an image and its location information, predict the continuous target label for the image.

Cat. 1: Landscape Variables Regression

Task 1: Forest Cover	MOSAIKS	498,106 examples
Task 2: Elevation	MOSAIKS	498,115 examples

Cat. 2: Urbanization Metrics Regression

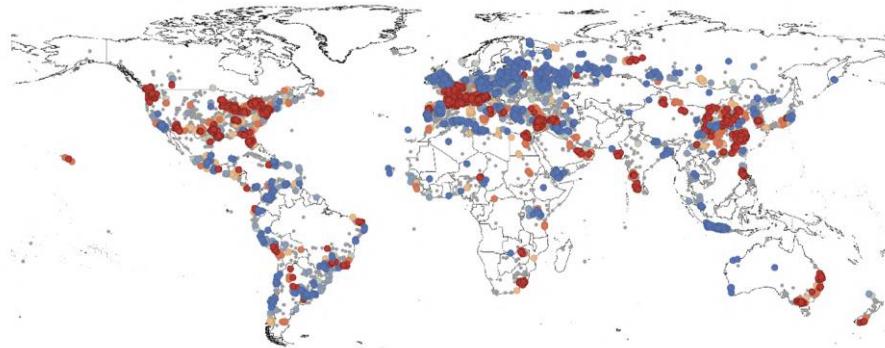
Task 3: Nightlights	MOSAIKS	492,226 examples
Task 4: Population Density	MOSAIKS	425,637 examples

Cat. 3: SDGs Indicators Regression

Task 5: Asset Index	SustainBench	89,936 examples
Task 6: Women BMI	SustainBench	94,866 examples
Task 7: Water Index	SustainBench	86,938 examples
Task 8: Child Mortality Rate	SustainBench	105,582 examples
Task 9: Sanitation Index	SustainBench	89,271 examples
Task 10: Women Edu	SustainBench	117,062 examples

Geo-Bias Score

Geographic bias: a phenomenon in which an AI model **performs differently across geographic regions** and its **predictions are biased** toward some predominated regions.

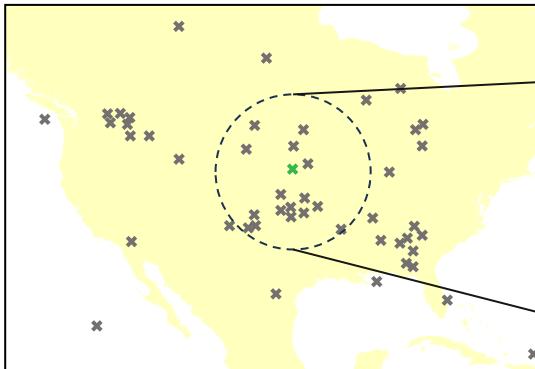


Hot spot analysis of HIT@1 of space2vec-theory on fMoW

- We employ the **spatial self-information (SSI)**, using a Gaussian distribution to approximate the probability of observing certain types of spatial patterns.

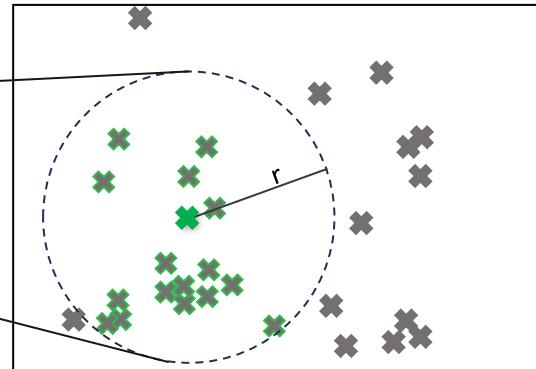
The lower the SSI, the more likely the current spatial patterns arise randomly, namely less geo-baised.

Geo-Bias Score



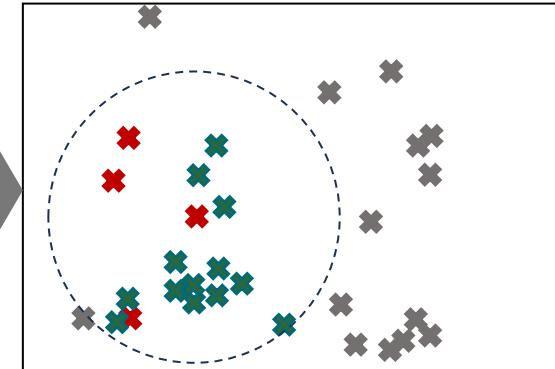
sample point

Extract a low-performance observation's neighborhood by radius r .



- **Base Geo-Bias Score**

The SSI of low-performance observations **if they are completely randomly distributed**



- **Relative Geo-Bias Score**

Difference between the SSI of the low-performance observations (red crosses) and the SSI of completely random low-performance observations (cyan-blue crosses).

Zhangyu Wang, Krzysztof Janowicz, **Gengchen Mai**, Ivan Majic. [Probing the Information Theoretical Roots of Spatial Dependence Measures](#), In: *Proceedings of the 16th Conference on Spatial Information Theory (COSIT 2024)*, Sep 17 - 20, Québec City, Canada. [\[ArXiv\]](#)

Experiments - Image Classification - Top1Acc

	Task	Species Recognition						Flickr	RS
	Image Classification Dataset	BirdSnap	BirdSnap†	NABirds†	iNat2017	iNat2018	avg	YFCC	fMOW
	$P(y x)$ - Prior Type	Test	Test	Test	Val	Val	-	Test	Val
A	No Prior (i.e. image model)	70.07	70.07	76.08	63.27	60.20	67.94	50.15	69.83
B	<i>tile</i> (Tang et al., 2015)	70.20	70.56	75.78	62.54	56.30	67.08	50.01	69.86
	<i>wrap</i> (Mac Aodha et al., 2019)	72.06	79.35	81.78	68.16	73.11	74.89	51.03	70.34
	<i>wrap + ffn</i> (Mai et al., 2020)	71.93	79.05	81.40	69.52	72.29	74.84	50.71	70.11
	<i>rbf</i> (Mai et al., 2020)	71.79	79.58	81.74	68.24	70.03	74.28	51.22	70.68
	<i>rff</i> (Rahimi et al., 2007)	71.84	78.91	81.61	68.86	72.32	74.71	50.81	70.24
	Space2Vec- <i>grid</i> (Mai et al., 2020)	71.75	80.24	81.70	68.23	73.06	75.00	51.25	70.67
C	Space2Vec- <i>theory</i> (Mai et al., 2020)	71.79	80.11	81.65	68.30	73.52	75.07	51.24	70.49
	<i>xyz</i> (Mai et al., 2023)	71.88	78.96	81.15	68.65	71.44	74.42	50.87	70.16
	<i>NeRF</i> (Mildenhall et al., 2020)	72.10	79.93	81.62	68.74	72.91	75.06	51.27	70.60
	Sphere2Vec- <i>sphereC</i> (Mai et al., 2023)	72.10	79.97	81.91	69.34	72.93	75.25	51.35	70.85
	Sphere2Vec- <i>sphereC+</i> (Mai et al., 2023)	72.15	80.90	82.13	68.29	73.45	75.38	51.31	70.93
	Sphere2Vec- <i>sphereM</i> (Mai et al., 2023)	71.88	79.93	81.86	68.51	72.94	75.02	51.18	70.93
	Sphere2Vec- <i>sphereM+</i> (Mai et al., 2023)	72.06	79.09	81.67	69.18	72.06	74.81	51.27	70.19
	Sphere2Vec- <i>dfs</i> (Mai et al., 2023)	71.79	78.69	81.44	69.42	72.16	74.70	50.65	70.27
D	Siren(SH) (Russwurm et al., 2024)	71.88	78.82	81.72	67.68	71.33	74.29	50.57	70.20
D	GPT-4V	55.02	48.89	73.00*	28.00*	18.00*	44.00*	34.00*	17.00*

Experiments - Image Regression - R2

	Image Regression Dataset	Population Density	Forest Cover	Nightlight Luminosity	Elevation
A	No Prior (i.e. image model)	0.38	0.52	0.33	0.27
B	<i>tile</i> (Tang et al., 2015)	0.04	0.46	0.18	0.76
	<i>wrap</i> (Mac Aodha et al., 2019)	0.57	0.72	0.31	0.79
	<i>wrap + ffn</i> (Mai et al., 2020)	0.47	0.67	0.28	0.73
	<i>rbf</i> (Mai et al., 2020)	0.25	0.54	0.32	0.39
	<i>rff</i> (Rahimi et al., 2007)	0.57	0.73	0.23	0.77
	Space2Vec- <i>grid</i> (Mai et al., 2020)	0.65	0.69	0.22	0.76
	Space2Vec- <i>theory</i> (Mai et al., 2020)	0.57	0.73	0.21	0.78
C	<i>xyz</i> (Mai et al., 2023)	0.49	0.58	0.28	0.72
	<i>NeRF</i> (Mildenhall et al., 2020)	0.60	0.68	0.23	0.76
	Sphere2Vec- <i>sphereC</i> (Mai et al., 2023)	0.63	0.73	0.28	0.82
	Sphere2Vec- <i>sphereC+</i> (Mai et al., 2023)	0.64	0.75	0.27	0.82
	Sphere2Vec- <i>sphereM</i> (Mai et al., 2023)	0.62	0.71	0.23	0.82
	Sphere2Vec- <i>sphereM+</i> (Mai et al., 2023)	0.53	0.67	0.32	0.74
	Sphere2Vec- <i>dfs</i> (Mai et al., 2023)	0.52	0.62	0.35	0.66
	Siren(SH) (Russwurm et al., 2024)	0.62	0.72	0.34	0.80

* (A) No Prior indicates image-only models; (B) geo-aware models with 2D location encoders; (C) geo-aware models with 3D location encoders.

Experiments - Image Regression - R2

	Image Regression Dataset	Asset Index	Women BMI	Water Index	Child Mortality Rate	Sanitation Index	Women Edu
A	No Prior (i.e. image model)	0.40	0.27	0.26	0.02	0.33	0.22
B	<i>tile</i> (Tang et al., 2015)	0.00	0.00	0.00	0.00	0.00	0.00
	<i>wrap</i> (Mac Aodha et al., 2019)	0.47	0.64	0.31	0.33	0.42	0.50
	<i>wrap + ffn</i> (Mai et al., 2020)	0.45	0.63	0.29	0.32	0.39	0.49
	<i>rbf</i> (Mai et al., 2020)	0.56	0.66	0.40	0.36	0.56	0.51
	<i>rff</i> (Rahimi et al., 2007)	0.50	0.64	0.33	0.34	0.46	0.53
	Space2Vec- <i>grid</i> (Mai et al., 2020)	0.66	0.66	0.49	0.32	0.59	0.64
	Space2Vec- <i>theory</i> (Mai et al., 2020)	0.70	0.65	0.52	0.33	0.61	0.66
C	<i>xyz</i> (Mai et al., 2023)	0.44	0.62	0.28	0.31	0.38	0.48
	<i>NeRF</i> (Mildenhall et al., 2020)	0.65	0.68	0.50	0.34	0.60	0.64
	Sphere2Vec- <i>sphereC</i> (Mai et al., 2023)	0.69	0.69	0.52	0.37	0.62	0.66
	Sphere2Vec- <i>sphereC+</i> (Mai et al., 2023)	0.69	0.68	0.53	0.37	0.64	0.66
	Sphere2Vec- <i>sphereM</i> (Mai et al., 2023)	0.67	0.68	0.52	0.37	0.63	0.66
	Sphere2Vec- <i>sphereM+</i> (Mai et al., 2023)	0.45	0.62	0.29	0.31	0.39	0.48
	Sphere2Vec- <i>dfs</i> (Mai et al., 2023)	0.45	0.63	0.30	0.32	0.40	0.49
	Siren(SH) (Russwurm et al., 2024)	0.52	0.65	0.35	0.35	0.47	0.54

Experiments - Image Classification - Geo-Bias

Task	Species Recognition												Flickr	RS	
	Image Classification Dataset		BirdSnap		BirdSnap†		NABirds†		iNat2017		iNat2018				
$P(y x)$ - Prior Type		Test		Test		Test		Val		Val		Test		Val	
Geo-Bias Score		base	rel	base	rel	base	rel	base	rel	base	rel	base	rel	base	rel
A	No Prior (i.e. image model)	28.22	33.11	8.22	7.06	39.71	31.33	26.60	20.37	18.20	13.38	8.05	4.45	375.73	319.66
B	<i>tile</i> (Tang et al., 2015)	27.65	32.10	8.53	7.37	38.43	30.26	26.08	19.91	16.80	12.22	8.41	4.77	375.43	319.77
	<i>wrap</i> (Mac Aodha et al., 2019)	27.76	32.98	17.17	16.60	57.37	41.99	34.83	27.50	30.78	24.31	7.99	4.41	380.20	323.67
	<i>wrap + ffn</i> (Mai et al., 2020)	29.50	34.99	8.25	7.07	57.03	42.43	35.73	28.20	27.68	21.57	7.77	4.21	377.41	321.20
	<i>rbf</i> (Mai et al., 2020)	17.24	19.75	9.37	8.52	58.05	43.05	34.05	26.80	20.48	15.28	7.37	3.86	380.64	324.46
	<i>rff</i> (Rahimi et al., 2007)	28.03	33.61	13.70	12.80	57.71	42.63	34.45	27.21	28.63	22.45	7.87	4.29	377.94	317.65
	<i>Space2Vec-grid</i> (Mai et al., 2020)	22.26	25.10	16.27	15.42	58.96	43.38	34.10	26.87	31.12	24.71	7.99	4.43	380.23	323.17
	<i>Space2Vec-theory</i> (Mai et al., 2020)	36.78*	42.98*	15.27	14.36	59.62	44.38*	34.12	26.87	31.68*	24.92	7.99	4.41	382.49	324.52
C	<i>xyz</i> (Mai et al., 2023)	29.64	35.02	14.22	13.38	220.96*	34.09	34.89	27.53	26.33	20.44	7.79	4.24	379.84	323.12
	<i>NeRF</i> (Mildenhall et al., 2020)	29.66	35.16	16.13	15.53	57.86	42.61	34.93	27.62	30.46	23.90	7.81	4.26	375.81	320.30
	<i>Sphere2Vec-sphereC</i> (Mai et al., 2023)	28.84	34.02	14.78	13.94	59.26	43.68	35.77*	28.21*	31.61	24.96*	7.67	4.16	377.07	320.78
	<i>Sphere2Vec-sphereC+</i> (Mai et al., 2023)	30.43	36.48	19.99*	19.24*	59.13	43.47	33.14	26.02	31.55	24.85	8.22	4.66	379.92	323.04
	<i>Sphere2Vec-sphereM</i> (Mai et al., 2023)	31.49	37.02	16.75	16.70	58.68	43.10	33.97	26.75	31.66	24.95	8.06	4.51	377.26	321.56
	<i>Sphere2Vec-sphereM+</i> (Mai et al., 2023)	27.55	33.04	14.35	13.46	53.71	40.03	35.44	27.97	26.88	20.83	8.13	4.56	376.64	321.21
	<i>Sphere2Vec-dfs</i> (Mai et al., 2023)	26.39	30.93	13.57	12.50	55.43	40.75	35.52	28.05	26.00	20.13	7.87	4.30	380.82	323.78
	<i>Siren(SH)</i> (Russwurm et al., 2024)	27.67	32.91	14.87	14.50	57.57	42.60	35.47	28.07	26.24	20.26	7.68	4.15	377.23	321.15
D	GPT-4V	28.58	34.01	7.06	6.21	-	-	-	-	-	-	-	-	-	

Experiments - Image Regression - Geo-Bias

	Image Regression Dataset	Population Density	Forest Cover	Nightlight Luminosity	Elevation				
	Geo-Bias Score	base	rel	base	rel	base	rel	base	rel
A	No Prior (i.e. image model)	5.93*	2.53	6.71	2.73	7.47	0.71	6.71	2.92
B	<i>tile</i> (Tang et al., 2015)	5.40	2.34	5.73	2.38	7.60	0.54	6.62	2.87
	<i>wrap</i> (Mac Aodha et al., 2019)	4.86	2.01	5.17	2.27	7.36	1.08	5.71	2.74
B	<i>wrap + ffn</i> (Mai et al., 2020)	5.04	1.90	5.55	2.40	7.61	0.27	6.12	2.90
	<i>rbf</i> (Mai et al., 2020)	5.39	2.02	5.83	2.28	7.69	0.42	7.28	3.37
	<i>rff</i> (Rahimi et al., 2007)	5.09	2.27	5.13	2.04	7.55	0.50	5.51	2.61
	<i>Space2Vec-grid</i> (Mai et al., 2020)	5.48	2.42	5.25	2.11	7.64	0.80	6.22	2.65
	<i>Space2Vec-theory</i> (Mai et al., 2020)	5.00	1.97	5.46	2.33	7.55	0.75	5.07	2.24
C	<i>xyz</i> (Mai et al., 2023)	5.64	2.38	5.65	2.37	7.55	0.54	5.96	2.97
	<i>NeRF</i> (Mildenhall et al., 2020)	5.90	2.80*	5.64	2.60	7.70	0.54	4.94	2.03
	<i>Sphere2Vec-sphereC</i> (Mai et al., 2023)	5.69	2.35	6.72*	2.24	7.73*	0.36	8.83*	4.16*
	<i>Sphere2Vec-sphereC+</i> (Mai et al., 2023)	5.34	2.37	5.08	2.18	7.50	0.74	5.49	2.51
	<i>Sphere2Vec-sphereM</i> (Mai et al., 2023)	5.21	2.39	5.12	2.31	7.58	0.78	5.01	2.21
	<i>Sphere2Vec-sphereM+</i> (Mai et al., 2023)	5.20	2.51	5.45	2.31	7.54	0.67	6.55	3.13
	<i>Sphere2Vec-dfs</i> (Mai et al., 2023)	5.45	2.59	6.08	2.94*	7.53	1.10	6.03	2.58
	<i>Siren(SH)</i> (Russwurm et al., 2024)	5.10	2.29	5.82	2.46	7.48	1.21*	5.39	2.35

Bold numbers indicate that the scores that are significantly larger (>30%) than the No Prior model; * indicates the scores that are the largest among all models for this dataset.

Thank You

Contact:

Nemin Wu

Nemin.Wu@uga.edu

Qian Cao

Qian.Cao1@uga.edu



UNIVERSITY OF
GEORGIA
1785



SPATIALLY
EXPLICIT AI



TEXAS
The University of Texas at Austin