

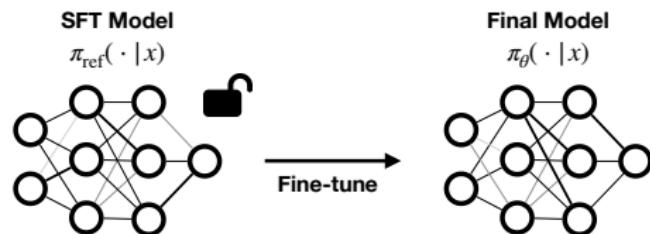
Preference Alignment with Flow Matching

Minu Kim*, Yongsik Lee*, Sehyeok Kang, Jihwan Oh, Song Chong, Se-Young Yun

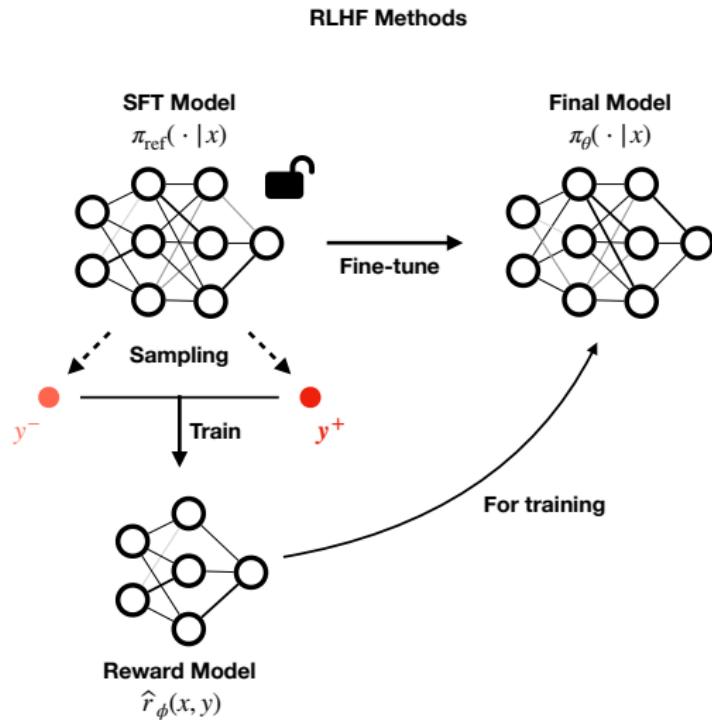
KAIST AI

Aligning Black-Box Models with Preferences

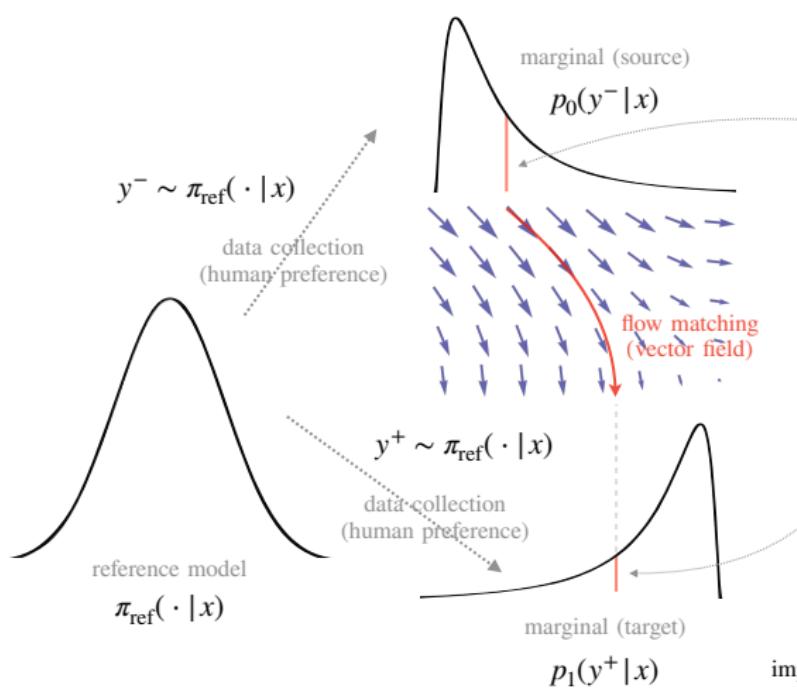
RLHF Methods



Aligning Black-Box Models with Preferences



Flow Matching Transports Probability Distributions



0	1	2	3	4	5	6	7	8	9
0	1	2	3	4	5	6	7	8	9
0	1	2	3	4	5	6	7	8	9
0	1	2	3	4	5	6	7	8	9
0	1	2	3	4	5	6	7	8	9
0	1	2	3	4	5	6	7	8	9
0	1	2	3	4	5	6	7	8	9
0	1	2	3	4	5	6	7	8	9
0	1	2	3	4	5	6	7	8	9
0	1	2	3	4	5	6	7	8	9

example of negative samples

$$y^- \sim p_0(\cdot | x)$$

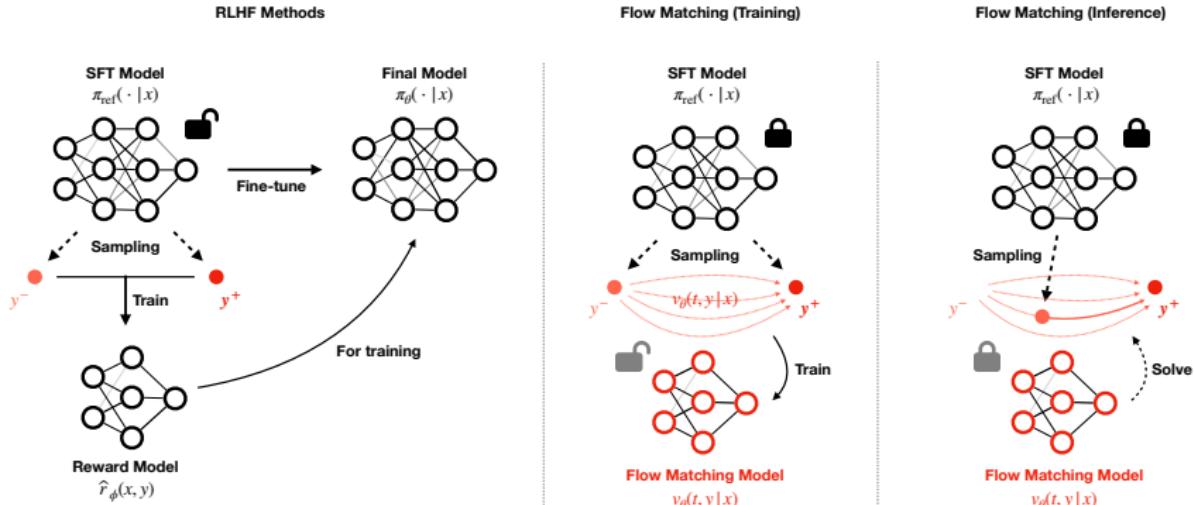
↓

PFM (Ours)

0	1	2	3	4	5	6	7	8	9
0	1	2	3	4	5	6	7	8	9
0	1	2	3	4	5	6	7	8	9
0	1	2	3	4	5	6	7	8	9
0	1	2	3	4	5	6	7	8	9
0	1	2	3	4	5	6	7	8	9
0	1	2	3	4	5	6	7	8	9
0	1	2	3	4	5	6	7	8	9
0	1	2	3	4	5	6	7	8	9
0	1	2	3	4	5	6	7	8	9

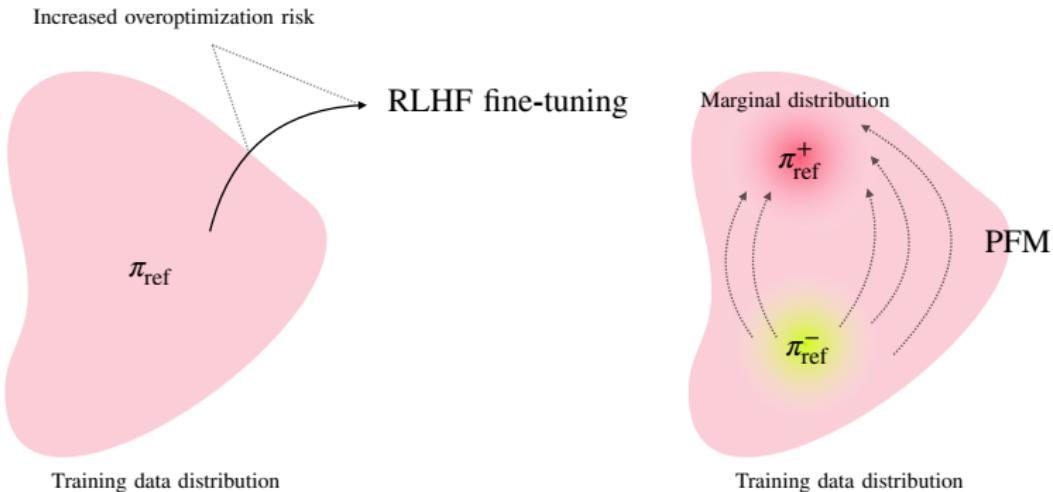
improvement over negative samples

Preference Alignment with Flow Matching

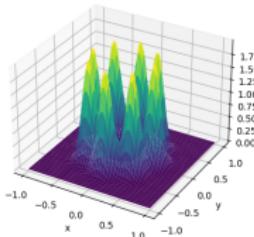


	RLHF	DPO	IPO	Ours
Reward Model Free	✗	✓	✓	✓
No Reward Assumptions (e.g. BT)	✗	✗	✓	✓
Applicable to Black-Box Models	✗	✗	✗	✓

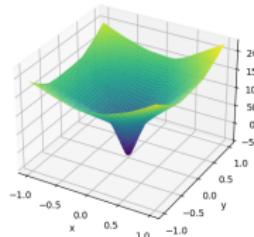
Mitigating Reward Overoptimization from Distribution Shift



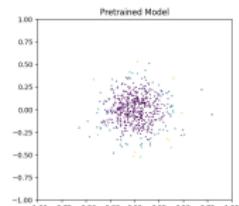
Illustrative Example



(a) True reward



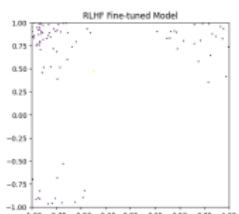
(b) Learned reward



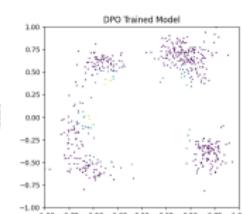
(c) Pre-trained



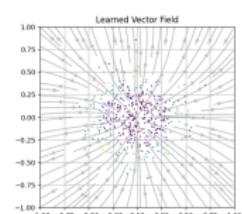
(d) Preferred



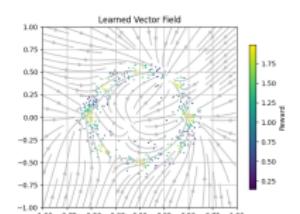
(e) RLHF



(f) DPO



(g) PFM



(h) PFM (5 iter.)

Theoretical Analysis

Theorem 1 (Characterization of the Marginal)

Let p_1 denote the marginal distribution of the positively-labeled samples y^+ . Then the marginal distribution p_1 obtained from the preference model $\mathbb{P}(y > y'|x)$ is an optimizer of the optimization problem

$$p_1 = \operatorname{argmax}_{\pi} \mathbb{E}_{y \sim \pi} \left(\log \mathbb{E}_{y' \sim \pi_{\text{ref}}} (\mathbb{P}(y > y')) \right) - \mathbb{D}_{\text{KL}}(\pi \parallel \pi_{\text{ref}}). \quad (1)$$

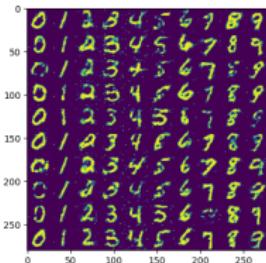
Theorem 2 (Convergence of Iterative Method)

Assume $\pi_{\text{ref}} \in L^2$ and $\mathbb{P}(y > y') \in L^2$. Consider an iterative update of the marginal distribution p_1 . Then, the iteration converges to the uniform distribution of points y where the value $\mathbb{E}_{y^- \sim \pi_{\text{ref}}} (\mathbb{P}(y > y^-))$ is the largest, i.e.,

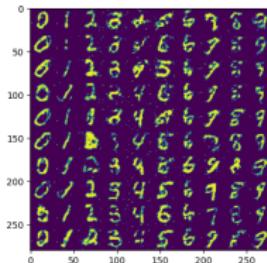
$$p_1^{(\infty)} \rightarrow U \left(\left\{ y : y \in \operatorname{argmax}_y \mathbb{E}_{y^- \sim \pi_{\text{ref}}} (\mathbb{P}(y > y^-)) \right\} \right), \quad (2)$$

where U stands for uniform distribution.

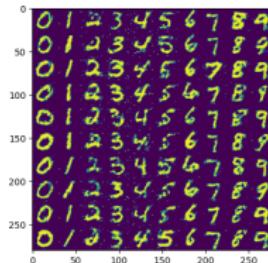
Experimental Results: Conditional Image Generation



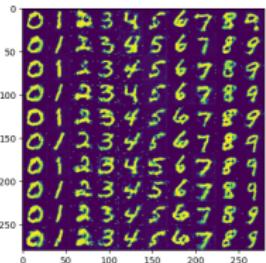
(a) $y \sim \pi_{\text{ref}}$ (0.8389)



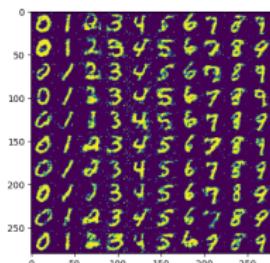
(b) y^- (0.3951)



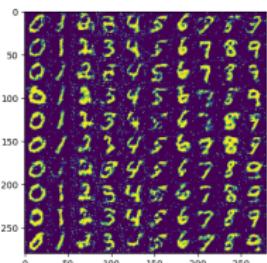
(c) y^+ (0.9976)



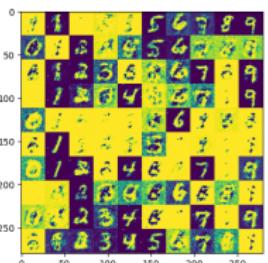
(d) PFM (0.9841)



(e) RLHF (0.9171)



(f) DPO (0.8936)



(g) DPO $\beta \downarrow$ (0.5397)



(h) PFM $\times 2$ (0.9996)

Experimental Results: Controlled Text Generation

Table 1: Average preference scores of 100 IMDB test instances.

Reference	PFM	PFM×5
-0.3607	0.6399	2.7469
RLHF fine-tuned	RLHF + PFM	RLHF + PFM×5
2.0156	2.178	2.7894

Table 2: GPT-4 win rate vs. RLHF (PPO) fine-tuned policy.

PFM	PFM×5	RLHF + PFM	RLHF + PFM×5
2%	85%	99%	100%

Experimental Results: Offline RL

Dataset	Behavior Cloning	DPO Fine-tuned	PFM (Ours)	Marginal BC
ant-random-v2	31.59 ± 0.05	31.52 ± 0.08	31.62 ± 0.13	25.01 ± 4.64
ant-medium-v2	90.16 ± 21.48	95.04 ± 13.93	96.73 ± 2.47	99.67 ± 1.57
ant-expert-v2	125.83 ± 24.07	134.96 ± 3.76	132.20 ± 2.69	99.29 ± 34.74
hopper-random-v2	3.17 ± 0.25	3.23 ± 0.25	7.69 ± 0.08	5.48 ± 4.46
hopper-medium-v2	52.83 ± 5.03	53.47 ± 3.92	58.76 ± 2.62	40.44 ± 1.69
hopper-expert-v2	111.27 ± 0.48	111.51 ± 0.92	111.70 ± 0.77	32.39 ± 0.1
halfcheetah-random-v2	2.25 ± 0.01	2.26 ± 0.01	2.26 ± 0.0	2.21 ± 0.02
halfcheetah-medium-v2	40.97 ± 0.89	41.94 ± 0.68	43.49 ± 0.88	38.79 ± 1.27
halfcheetah-expert-v2	91.02 ± 1.24	92.15 ± 0.76	90.05 ± 0.83	4.77 ± 2.5
walker2d-random-v2	1.47 ± 0.1	1.38 ± 0.08	1.77 ± 0.13	2.45 ± 0.38
walker2d-medium-v2	60.35 ± 18.16	74.05 ± 12.05	72.59 ± 15.8	65.29 ± 12.58
walker2d-expert-v2	108.62 ± 0.39	108.38 ± 0.28	108.36 ± 0.21	15.8 ± 0.54
Random Average	9.62	9.60	10.84	8.79
Medium Average	61.08	66.13	67.89	61.05
Expert Average	109.19	111.75	110.58	38.06
D4RL Average	59.97	62.49	63.10	35.97

Source Code Available

```
● ● ●

from flow import OptimalTransportConditionalFlowMatching

reference_policy = ... # Any base (reference) model or your interest
preference_dataset = ... # Your preference dataset, yielding pairs (x, y^+, y^-).
# Flow matching model. (e.g., UNet, MLP)
flow_model = ...

# For training PFM, simply call 'fit' method.
flow_matching = OptimalTransportConditionalFlowMatching(flow_model)
flow_matching.fit(
    dataset,
    conditional=True # Set to 'True' if contexts x are given.
)

# For evaluation, simply modify the generated output from the reference policy
# using the 'compute_target' method.
context = ... # e.g. a prompt
generated_sample = reference_policy(context) # e.g. a response
improved_sample = flow_matching.compute_target(
    generated_sample,
    context=context
)
```

<https://github.com/jadehaus/preference-flow-matching>

Source Code Available



jadehaus / [preference-flow-matching](#)

7



Official code implementation for the work
Preference Alignment with Flow Matching
(NeurIPS 2024)



jadehaus

<https://github.com/jadehaus/preference-flow-matching>