

# Erasing Undesirable Concepts in Diffusion Models with Adversarial Preservation

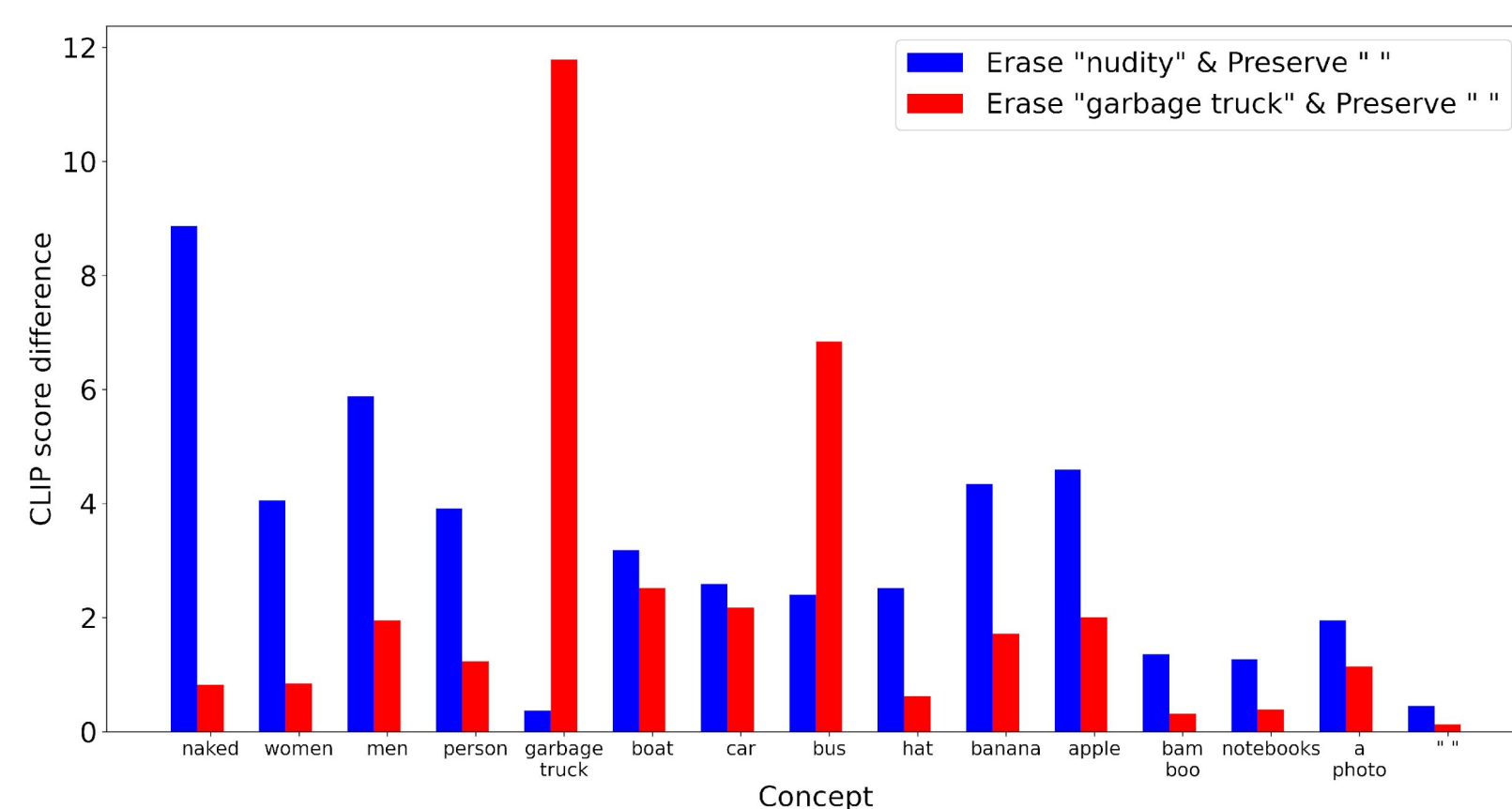
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## KEY OBSERVATIONS

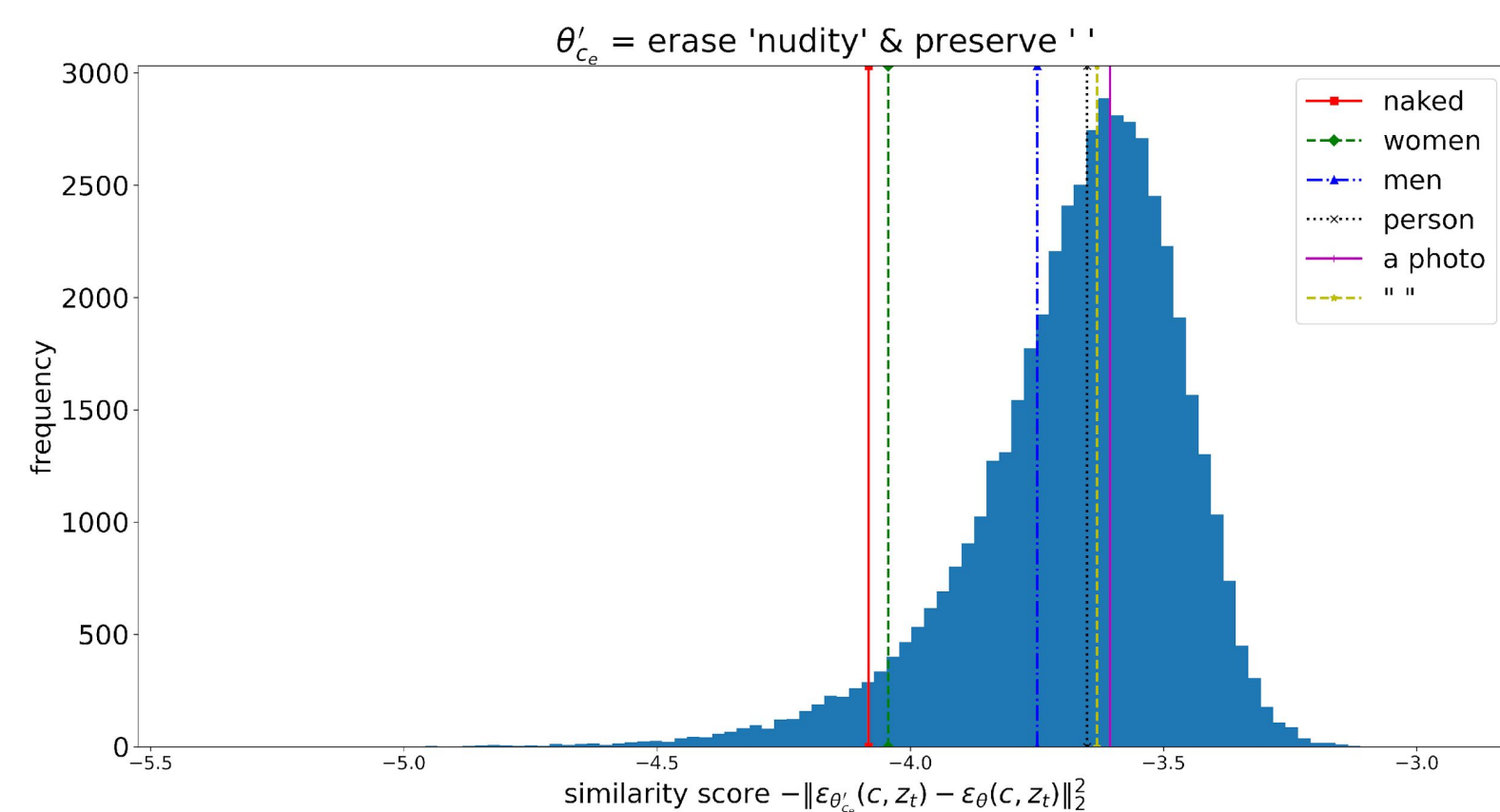
### How to measure the Side-Effect of Concept Erasure

- CLIP alignment score  $S_{\theta,i,c} = S(G(\theta, c, z_T^i), c) \rightarrow$  the higher score, the better model can generate concept  $c$
- $\delta_{c_e}(c) = \frac{1}{k} \sum_{i=1}^k (S_{\theta,i,c} - S_{\theta',i,c}) \rightarrow$  the larger different, the higher side-effect (negatively) to model's capability

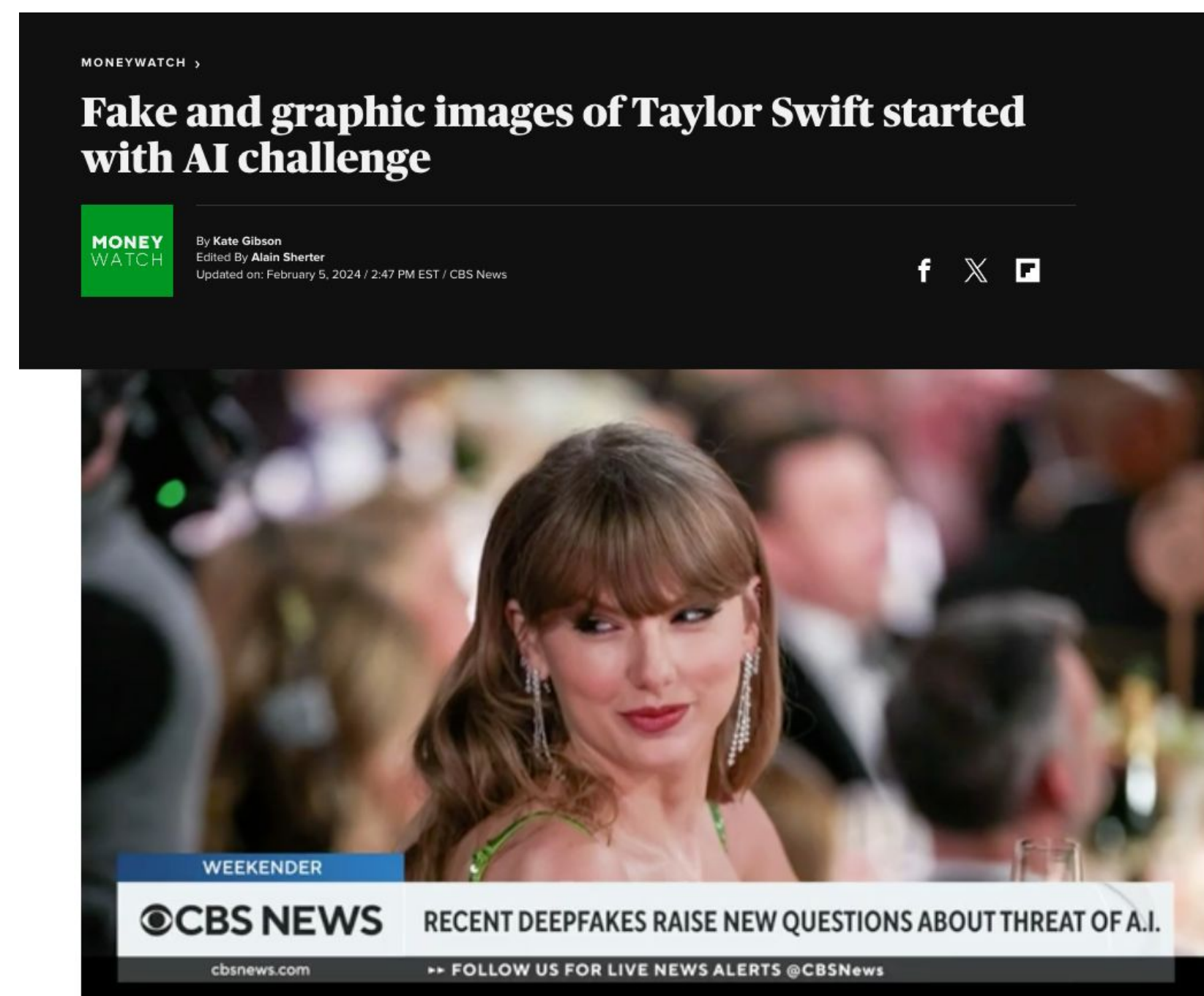
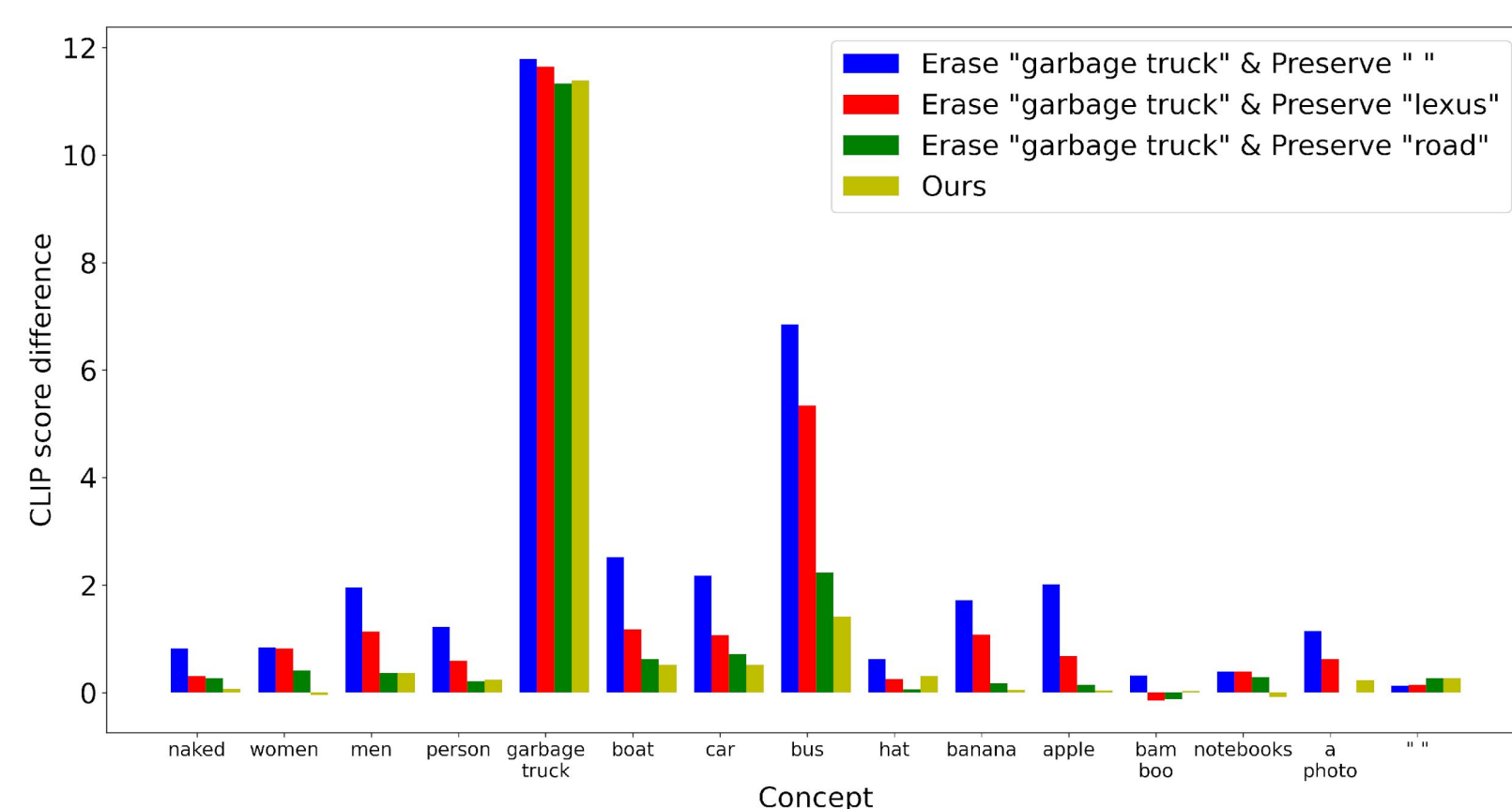
### 1 - Erasing Different Concepts Leads to Different Side-Effects



### 2 - Neutral Concepts lie in the Middle of the Sensitivity Spectrum



### 3 - What Concept Should be Kept to Minimize the Side-Effect



How to prevent AI-generated "po\*n" content?

## CONCEPT ERASURE

### Naïve Approach

$$\min_{\theta'} \mathbb{E}_{c_e \in E} [\|\epsilon_{\theta'}(c_e) - \epsilon_{\theta}(c_n)\|_2^2] + L_2$$

Where:

- $\theta, \theta'$ : original and sanitized models
- $c_e \in E$ : concept to-be-erased (e.g., 'nudity')
- $c_n$ : neutral/generic concept (e.g., 'a photo')
- $\epsilon_{\theta}(c)$ : noise-prediction function
- $L_2$ : preservation loss

$$L_2 = \|\epsilon_{\theta'}(c_n) - \epsilon_{\theta}(c_n)\|_2^2 \text{ or } \|\theta' - \theta\|_2^2$$

From Observations to Motivation:

- Observation 2  $\rightarrow$  Preserving a neutral/generic concept  $c_n$  is sub-optimal.
- Observation 1  $\rightarrow$  to-be-preserved concept should be adaptive.
- Observation 3  $\rightarrow$  to-be-preserved concept should be related to the to-be-erased concepts.

## ADVERSARIAL PRESERVATION

$$\min_{\theta'} \max_{c_a \in \mathcal{R}} \mathbb{E}_{c_e \in E} \left[ \underbrace{\|\epsilon_{\theta'}(c_e) - \epsilon_{\theta}(c_n)\|_2^2}_{L_1} + \lambda \underbrace{\|\epsilon_{\theta'}(c_a) - \epsilon_{\theta}(c_a)\|_2^2}_{L_2} \right]$$

Where:

- $\theta, \theta'$ : original and sanitized models
- $c_a$ : 'Adversarial' concept, i.e., the concept will be affected most by the erasure
- $\mathcal{R}$ : Concept space to search  $c_a$

Interpretation:

- Inner-Max: Find adversarial concept that is affected most by the erasure
- Outer-Min: Update model to erasure  $E$  and preserve  $c_a$ , simultaneously.

### Finding Adversarial Concept with PGD

- Init  $c_{a,t=0} = c_e$ , e.g.,  $\triangleq \tau(\text{'garbage truck'})$
- Iteratively update  $c_{a,t+1} = c_a + \eta \nabla_{c_a} L_2$

However,  $c_a$  quickly converges to background noise/non-sense type of concept



### Relaxation with Gumbel-Softmax

$$\min_{\theta'} \max_{\pi \in \Delta_{\mathcal{R}}} \mathbb{E}_{c_e \in E} \left[ \underbrace{\|\epsilon_{\theta'}(c_e) - \epsilon_{\theta}(c_n)\|_2^2}_{L_1} + \lambda \underbrace{\|\epsilon_{\theta'}(G(\pi) \odot \mathcal{R}) - \epsilon_{\theta}(G(\pi) \odot \mathcal{R})\|_2^2}_{L_2} \right]$$

- Modelling  $c_a$  as a distribution over the concept space  $\mathcal{R}$
- Searching  $\pi$  on the simplex  $\Delta_{\mathcal{R}}$

EXPERIMENTAL RESULTS AND MORE

