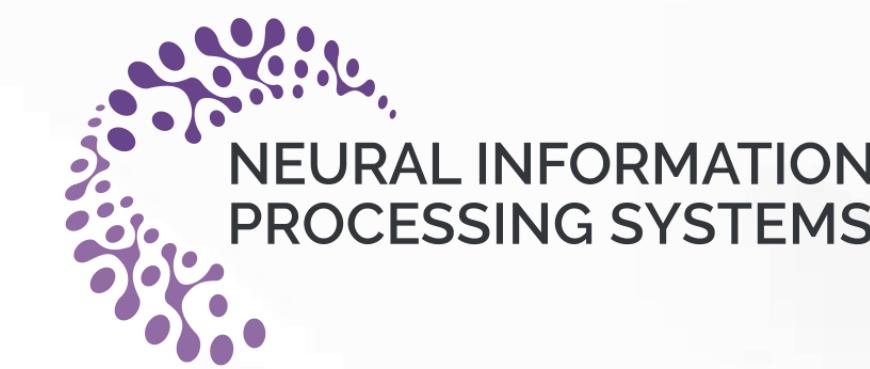


Demystify Mamba in Vision: A Linear Attention Perspective

Dongchen Han Ziyi Wang Zhuofan Xia Yizeng Han Yifan Pu Chunjiang Ge
Jun Song Shiji Song Bo Zheng Gao Huang



清华大学
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Background

Transformers has a **Quadratic Complexity** $\mathcal{O}(N^2d)$ with respect to sequence length.

High Resolution Images



Videos



Mamba: a Powerful Selective State Space Model



Mamba

- ✓ *High expressive capability*
- ✓ *Linear complexity $\mathcal{O}(Nd^2)$*
- ✓ *Global modeling*

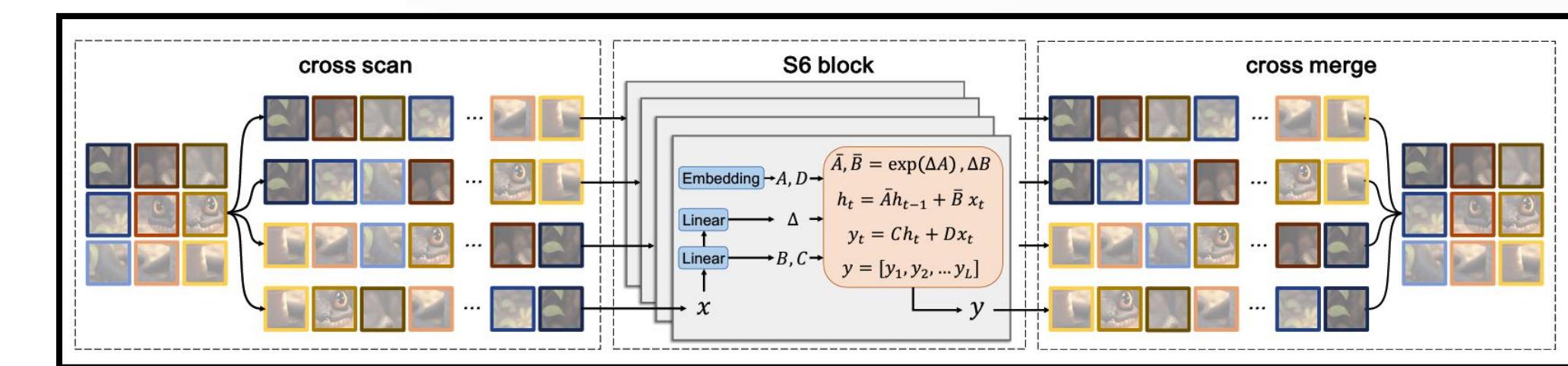
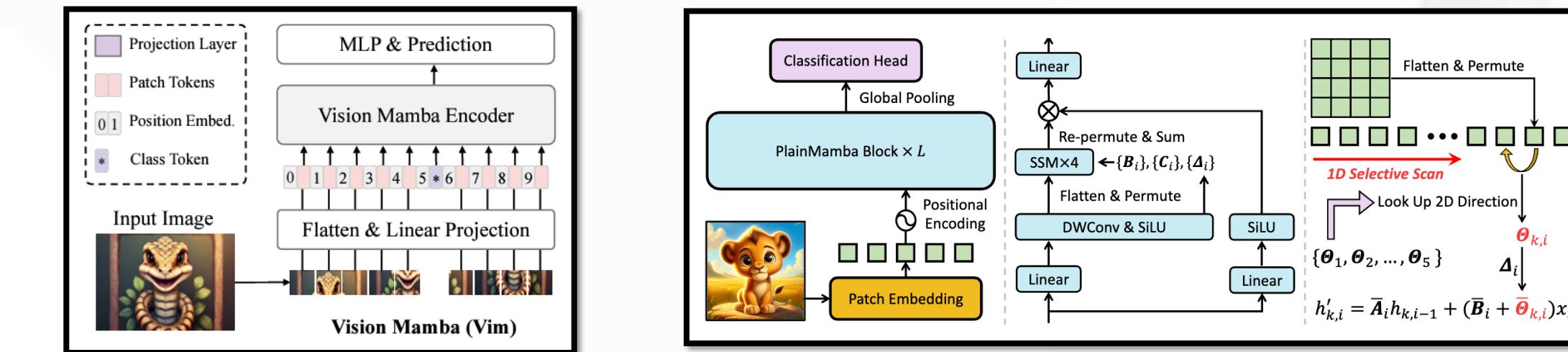
A *promising* method to deal with *high-resolution* images!

Fork 798 Star 10.2k

Mamba: Linear-time sequence modeling with selective state spaces

[A Gu, T Dao - arXiv preprint arXiv:2312.00752, 2023 - arxiv.org](#)

... to million-length **sequences**. As a general **sequence model** backbone, **Mamba** achieves state-... On language **modeling**, our **Mamba-3B model** outperforms Transformers of the same
☆ Save ✉ Cite Cited by 339 Related articles All 4 versions »

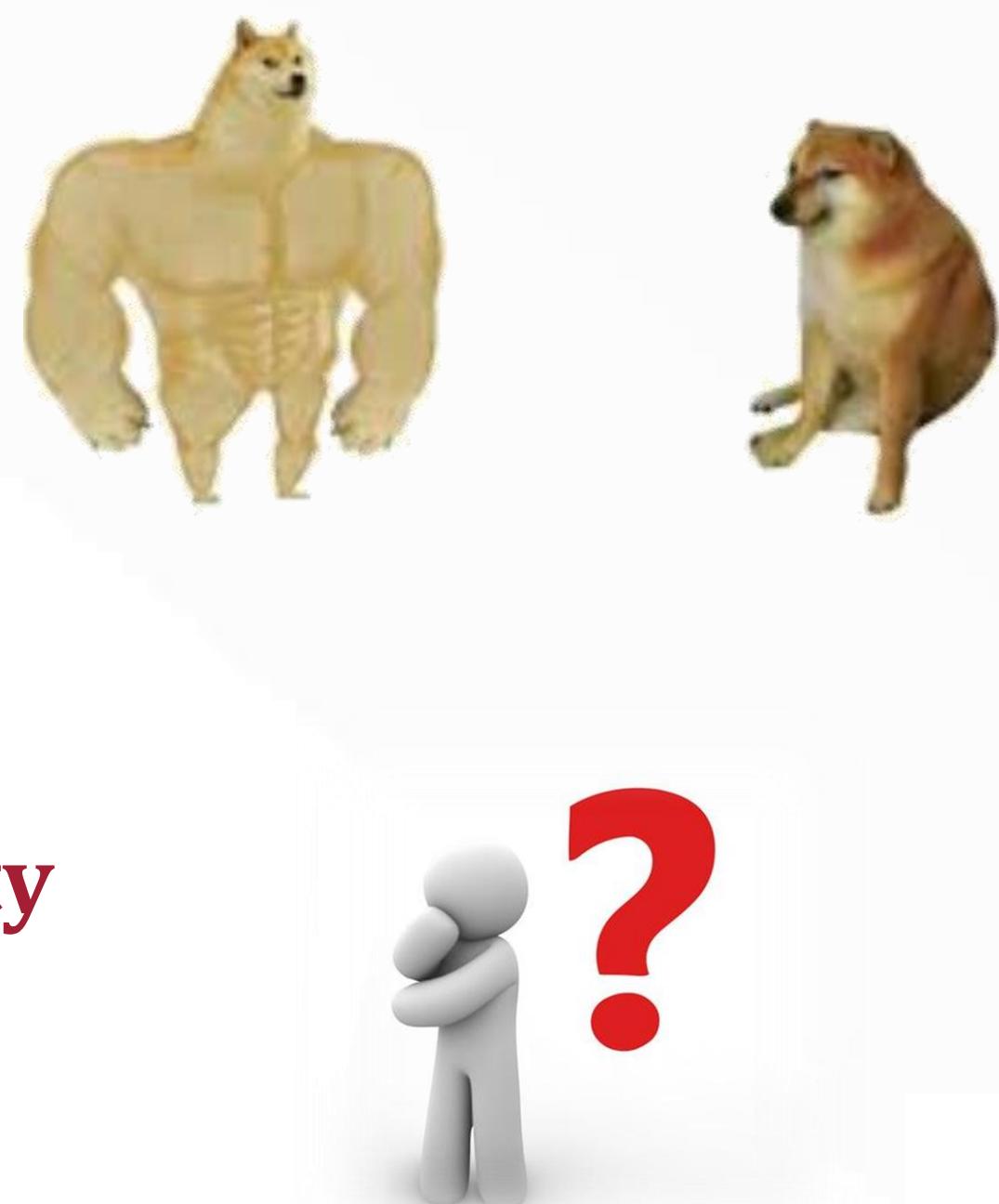


1. Gu A, Dao T. Mamba: Linear-time sequence modeling with selective state spaces[J]. arXiv preprint arXiv:2312.00752, 2023.



Motivation

- ✓ Linear complexity $\mathcal{O}(N)$
- ✓ Global modeling
- ✓ **High expressive capability**



$$\begin{aligned} \mathbf{h}_i &= \tilde{\mathbf{A}}_i \odot \mathbf{h}_{i-1} + \mathbf{B}_i(\Delta_i \odot \mathbf{x}_i), \\ \mathbf{y}_i &= \mathbf{C}_i \mathbf{h}_i / 1 + \mathbf{D} \odot \mathbf{x}_i. \end{aligned}$$

Linear Attention

- ✓ Linear complexity $\mathcal{O}(N)$
- ✓ Global modeling
- ✗ **Inferior performance**

$$\mathbf{y}_i = \sum_{j=1}^N \frac{\mathbf{Q}_i \mathbf{K}_j^\top}{\sum_{j=1}^N \mathbf{Q}_i \mathbf{K}_j^\top} \mathbf{V}_j = \frac{\mathbf{Q}_i \left(\sum_{j=1}^N \mathbf{K}_j^\top \mathbf{V}_j \right)}{\mathbf{Q}_i \left(\sum_{j=1}^N \mathbf{K}_j^\top \right)}$$

1. Gu A, Dao T. Mamba: Linear-time sequence modeling with selective state spaces[J]. arXiv preprint arXiv:2312.00752, 2023.
2. Katharopoulos A, Vyas A, Pappas N, et al. Transformers are rnns: Fast autoregressive transformers with linear attention[C]//International Conference on Machine Learning. PMLR, 2020: 5156-5165.



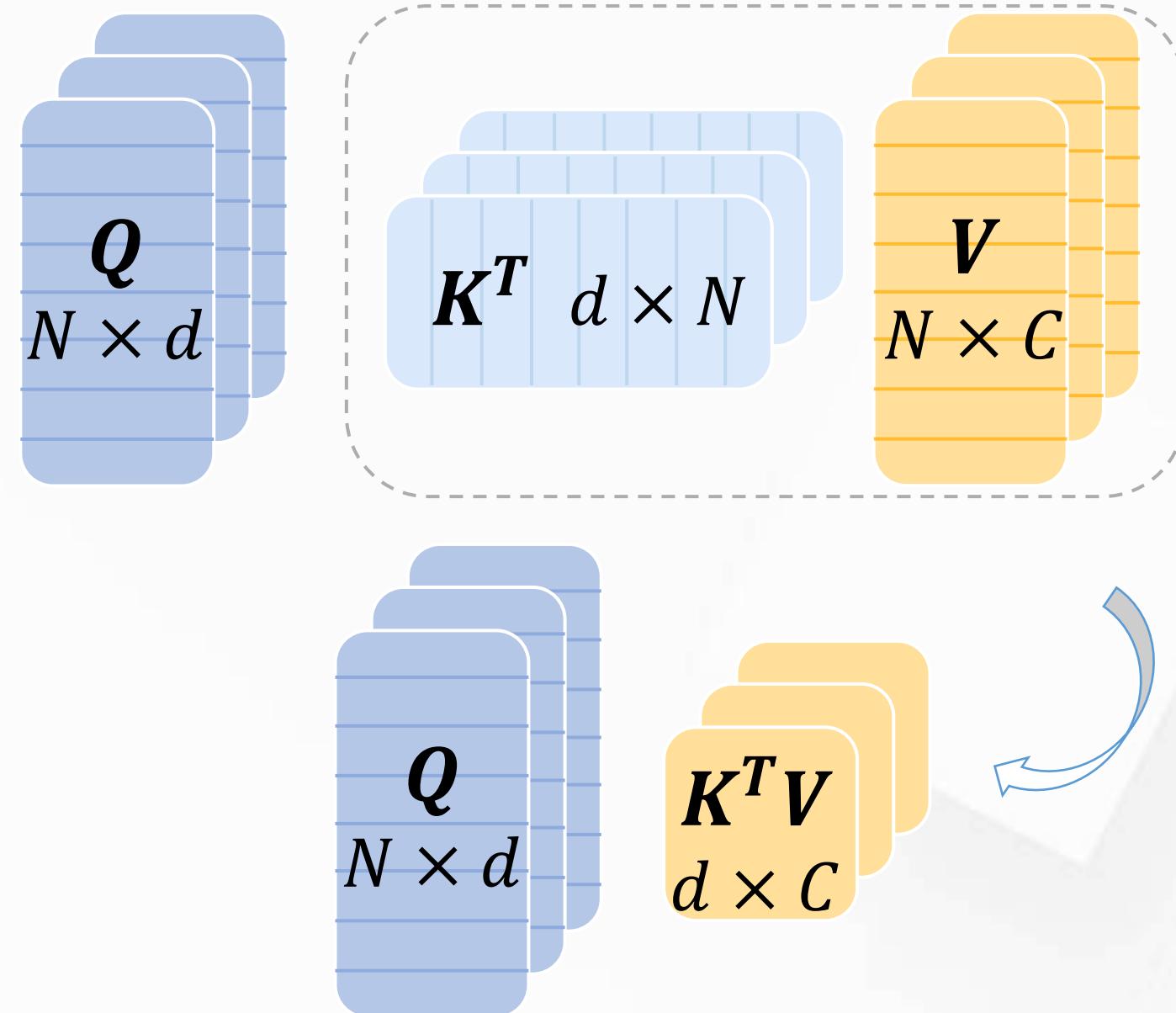
Linear Attention

$$\text{Linear Attention} \quad O = QK^T V$$

Carefully designed kernels are introduced as the approximation of the original similarity function:

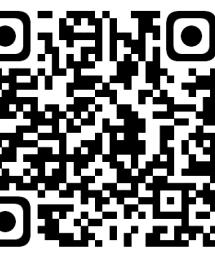
$$Q = \phi(xW_Q), K = \phi(xW_K), V = xW_V$$

$$y_i = \sum_{j=1}^N \frac{Q_i K_j^\top}{\sum_{j=1}^N Q_i K_j^\top} V_j = \frac{Q_i \left(\sum_{j=1}^N K_j^\top V_j \right)}{Q_i \left(\sum_{j=1}^N K_j^\top \right)}$$



- ✗ **Inferior performance**
- ✓ Linear complexity $\mathcal{O}(Nd^2)$

1. Katharopoulos A, Vyas A, Pappas N, et al. Transformers are rnns: Fast autoregressive transformers with linear attention[C]//International Conference on Machine Learning. PMLR, 2020: 5156-5165.



Recurrent Linear Attention

Non-causal linear attention (common linear attention):

$$\mathbf{y}_i = \sum_{j=1}^N \frac{\mathbf{Q}_i \mathbf{K}_j^\top}{\sum_{j=1}^N \mathbf{Q}_i \mathbf{K}_j^\top} \mathbf{V}_j = \frac{\mathbf{Q}_i \left(\sum_{j=1}^N \mathbf{K}_j^\top \mathbf{V}_j \right)}{\mathbf{Q}_i \left(\sum_{j=1}^N \mathbf{K}_j^\top \right)}$$

$$\boxed{S_i} = \boxed{S_{i-1}} + \boxed{K_i^\top} \cdot \boxed{V_i}$$

Causal linear attention:

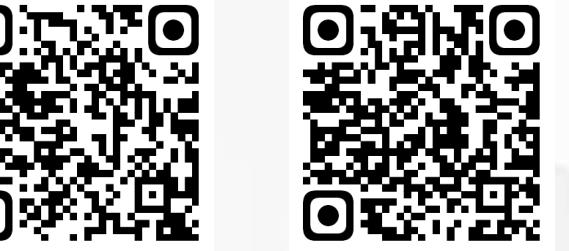
$$\mathbf{y}_i = \frac{\mathbf{Q}_i \left(\sum_{j=1}^i \mathbf{K}_j^\top \mathbf{V}_j \right)}{\mathbf{Q}_i \left(\sum_{j=1}^i \mathbf{K}_j^\top \right)} \triangleq \frac{\mathbf{Q}_i S_i}{\mathbf{Q}_i Z_i}, \quad S_i = \sum_{j=1}^i \mathbf{K}_j^\top \mathbf{V}_j, \quad Z_i = \sum_{j=1}^i \mathbf{K}_j^\top$$

$$\boxed{Z_i} = \boxed{Z_{i-1}} + \boxed{K_i^\top}$$

Recurrent linear attention form:

$$S_i = S_{i-1} + \mathbf{K}_i^\top \mathbf{V}_i, \quad Z_i = Z_{i-1} + \mathbf{K}_i^\top, \quad \mathbf{y}_i = \mathbf{Q}_i S_i / \mathbf{Q}_i Z_i.$$

$$\boxed{y_i} = \frac{\boxed{Q_i} \cdot \boxed{S_i}}{\boxed{Q_i} \cdot \boxed{Z_i}}$$



Selective State Space Model (Scalar Input)

$$\mathbf{h}_i = \overline{\mathbf{A}}_i \mathbf{h}_{i-1} + \overline{\mathbf{B}}_i x_i,$$

$$y_i = \mathbf{C}_i \mathbf{h}_i + D x_i,$$

$x_i \in \mathbb{R}, \quad \overline{\mathbf{A}}_i \in \mathbb{R}^{d \times d}, \quad \overline{\mathbf{B}}_i, \mathbf{h}_{i-1}, \mathbf{h}_i \in \mathbb{R}^{d \times 1},$

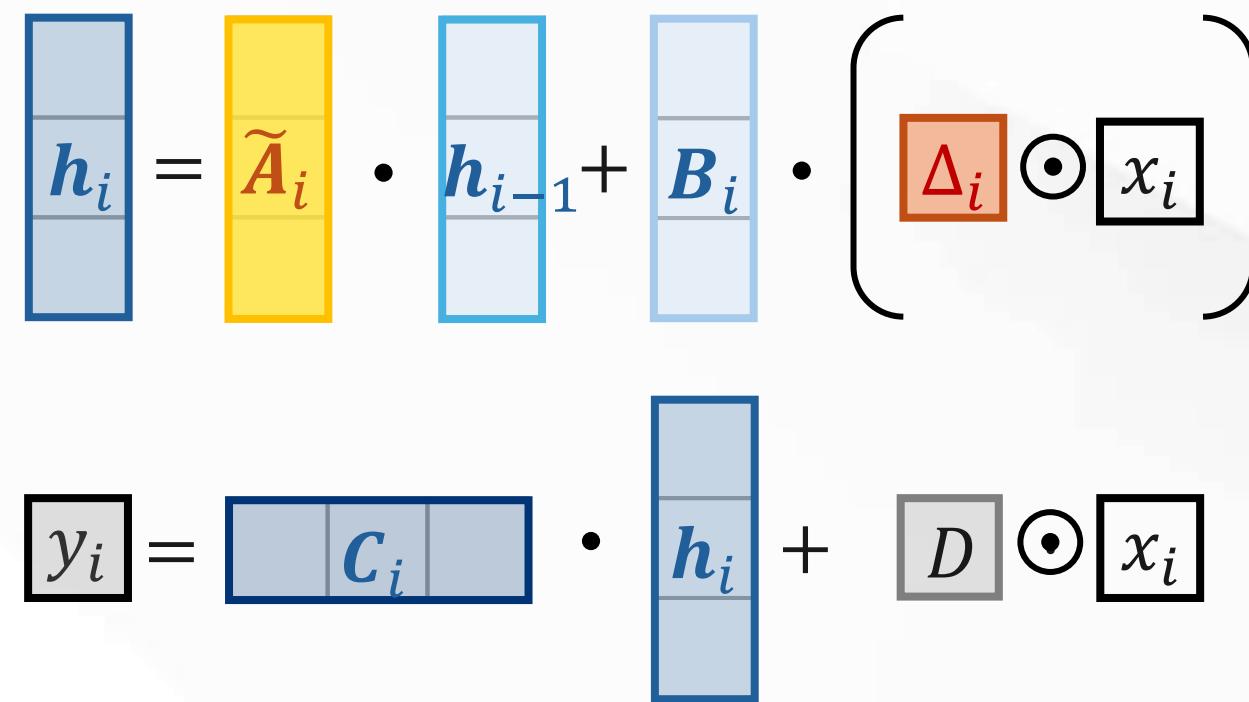
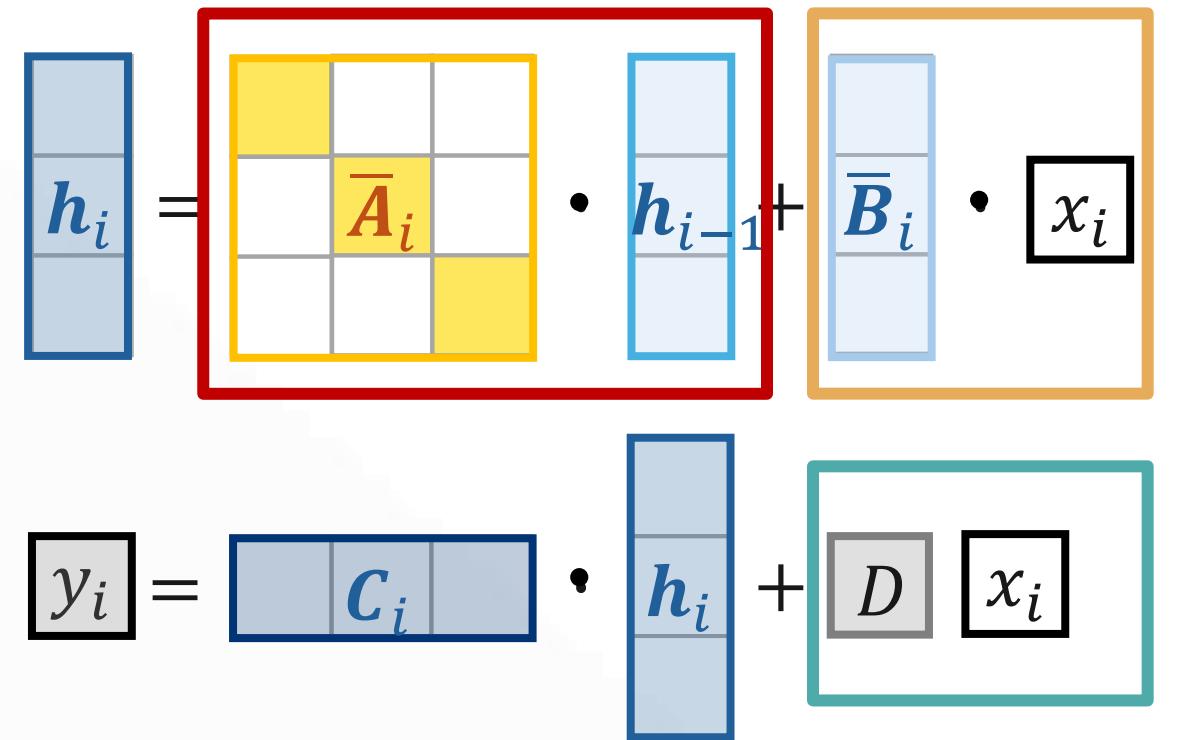
$y_i \in \mathbb{R}, \quad \mathbf{C}_i \in \mathbb{R}^{1 \times d}, \quad D \in \mathbb{R}.$

$$\mathbf{h}_i = \tilde{\mathbf{A}}_i \odot \mathbf{h}_{i-1} + \mathbf{B}_i (\Delta_i \odot x_i),$$

$$y_i = \mathbf{C}_i \mathbf{h}_i + D \odot x_i,$$

$x_i, \Delta_i \in \mathbb{R}, \quad \tilde{\mathbf{A}}_i, \mathbf{B}_i, \mathbf{h}_{i-1}, \mathbf{h}_i \in \mathbb{R}^{d \times 1},$

$y_i \in \mathbb{R}, \quad \mathbf{C}_i \in \mathbb{R}^{1 \times d}, \quad D \in \mathbb{R}.$



(1) $\overline{\mathbf{A}}_i \mathbf{h}_{i-1} = \tilde{\mathbf{A}}_i \odot \mathbf{h}_{i-1}$

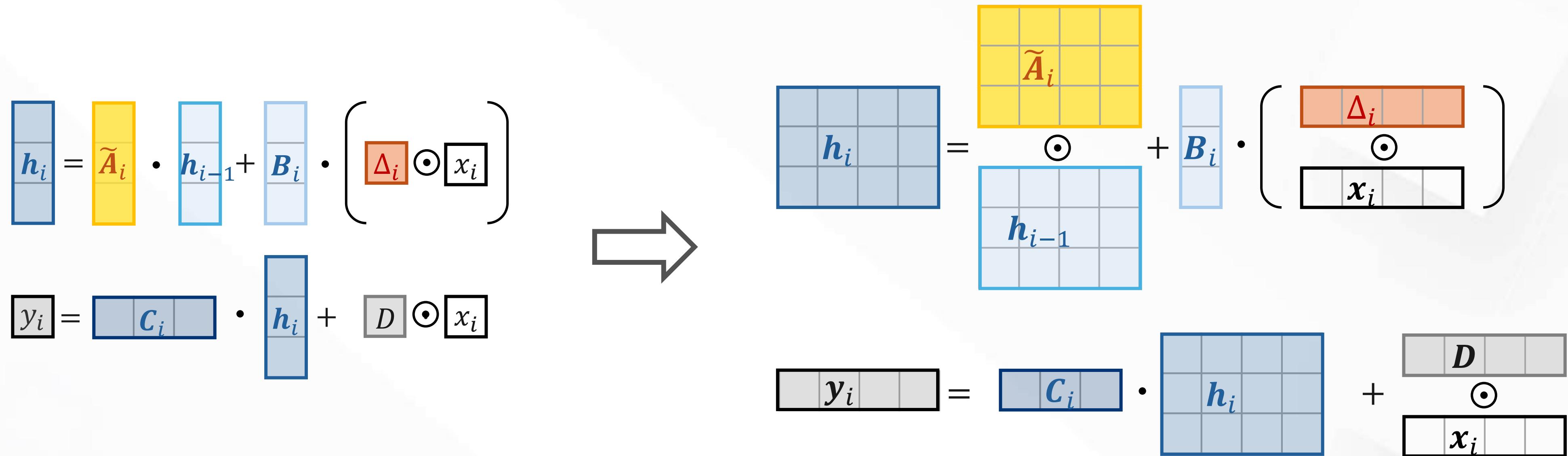
(2) $\overline{\mathbf{B}}_i x_i = \Delta_i \mathbf{B}_i x_i = \mathbf{B}_i (\Delta_i x_i) = \mathbf{B}_i (\Delta_i \odot x_i)$

(3) $D x_i = D \odot x_i$



Selective State Space Model (Vector Input)

$$\begin{aligned} \mathbf{h}_i &= \tilde{\mathbf{A}}_i \odot \mathbf{h}_{i-1} + \mathbf{B}_i(\Delta_i \odot \mathbf{x}_i), & \mathbf{x}_i, \Delta_i &\in \mathbb{R}^{1 \times C}, \quad \tilde{\mathbf{A}}_i, \mathbf{h}_{i-1}, \mathbf{h}_i &\in \mathbb{R}^{d \times C}, \quad \mathbf{B}_i &\in \mathbb{R}^{d \times 1} \\ \mathbf{y}_i &= \mathbf{C}_i \mathbf{h}_i + \mathbf{D} \odot \mathbf{x}_i, & \mathbf{y}_i &\in \mathbb{R}^{1 \times C}, \quad \mathbf{C}_i &\in \mathbb{R}^{1 \times d}, \quad \mathbf{D} &\in \mathbb{R}^{1 \times C}, \end{aligned}$$

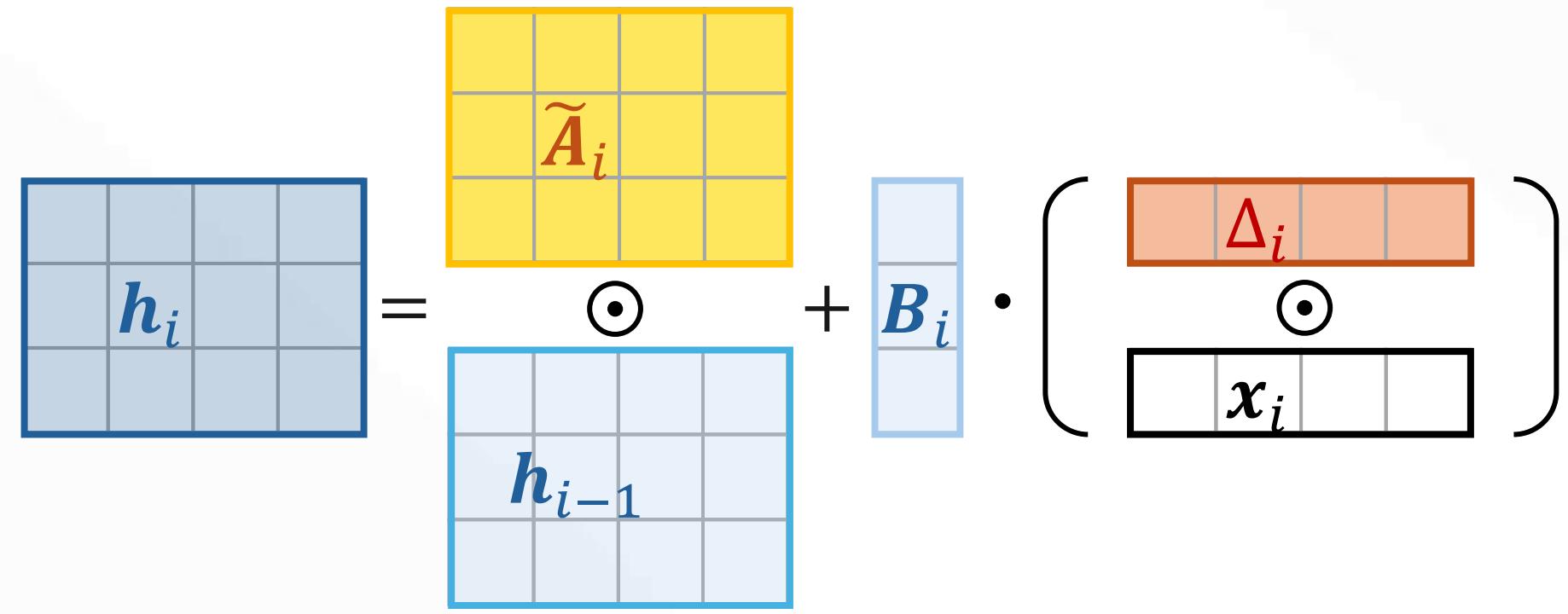




Mamba v.s. Linear Attention Transformer

Selective SSM in Mamba

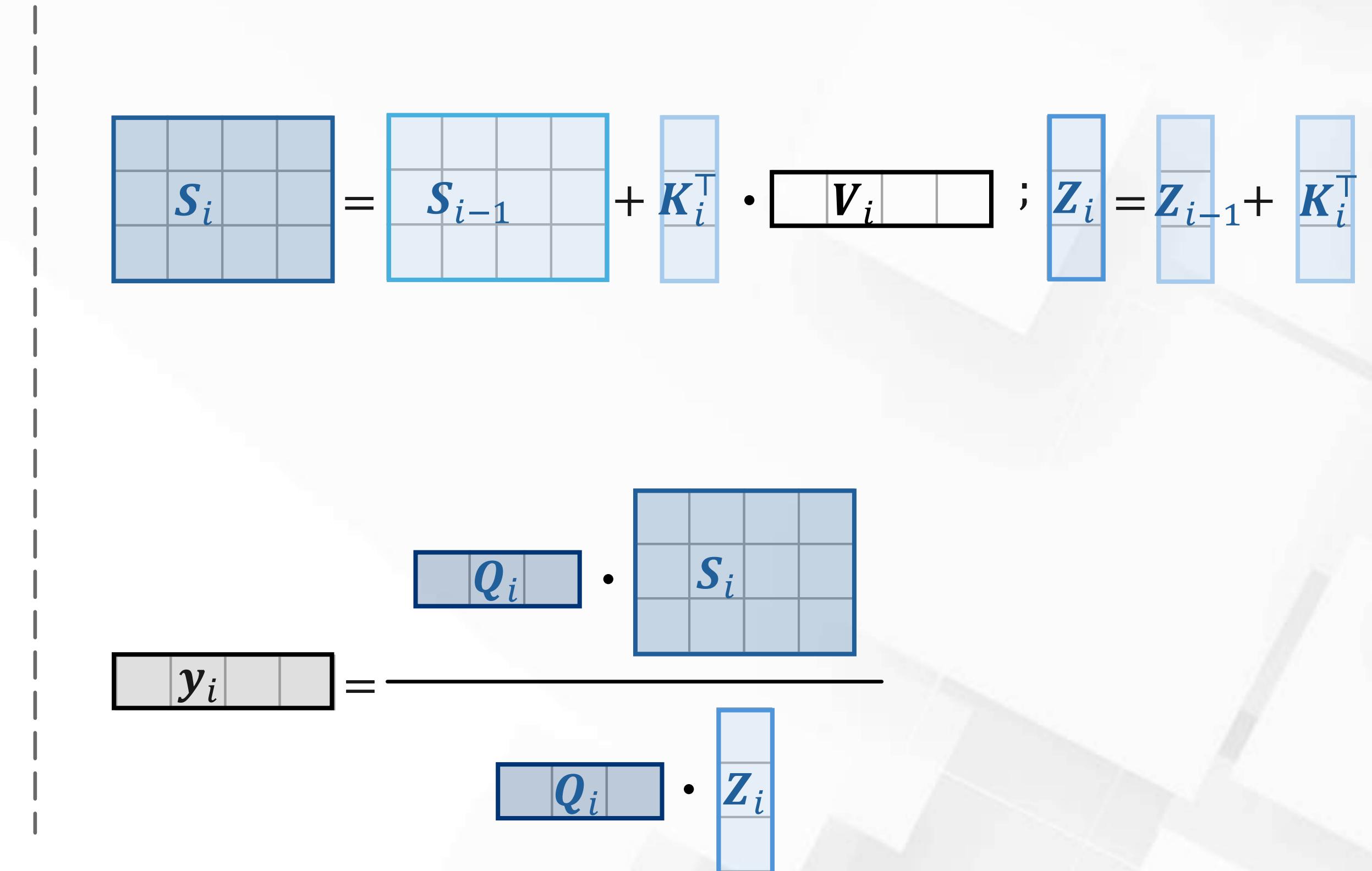
$$\begin{aligned}\mathbf{h}_i &= \tilde{\mathbf{A}}_i \odot \mathbf{h}_{i-1} + \mathbf{B}_i(\Delta_i \odot \mathbf{x}_i), \\ \mathbf{y}_i &= \mathbf{C}_i \mathbf{h}_i / 1 + \mathbf{D} \odot \mathbf{x}_i.\end{aligned}$$

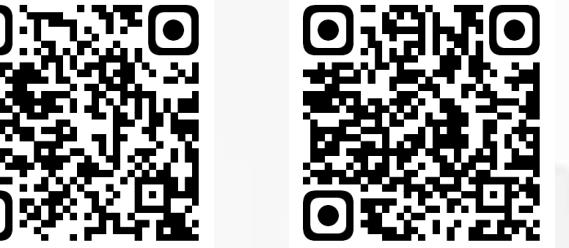


$$\mathbf{y}_i = \mathbf{C}_i \cdot \mathbf{h}_i + \mathbf{D} \odot \mathbf{x}_i$$

Single-head Linear Attention

$$\begin{aligned}\mathbf{S}_i &= \mathbf{1} \odot \mathbf{S}_{i-1} + \mathbf{K}_i^\top (\mathbf{1} \odot \mathbf{V}_i), \\ \mathbf{y}_i &= \mathbf{Q}_i \mathbf{S}_i / \mathbf{Q}_i \mathbf{Z}_i + \mathbf{0} \odot \mathbf{x}_i.\end{aligned}$$





Mamba v.s. Linear Attention Transformer

Four differences:

(1) Δ_i : input gate

$$\begin{matrix} h_i \\ h_{i-1} \end{matrix} = \begin{matrix} \tilde{A}_i \\ \odot \end{matrix} + B_i \cdot \left(\begin{matrix} (1) \\ \Delta_i \\ \odot \\ x_i \end{matrix} \right)$$

$$\begin{matrix} y_i \\ \end{matrix} = \begin{matrix} C_i \\ \cdot \end{matrix} \cdot \begin{matrix} h_i \\ \end{matrix} + \begin{matrix} D \\ \odot \\ x_i \end{matrix}$$

$$\begin{matrix} s_i \\ s_{i-1} \end{matrix} = \begin{matrix} K_i^\top \\ \cdot \end{matrix} \cdot \begin{matrix} V_i \\ \end{matrix} ; \begin{matrix} z_i \\ z_{i-1} \end{matrix} = \begin{matrix} K_i^\top \\ \cdot \end{matrix}$$

$$y_i = \frac{\begin{matrix} Q_i \\ \cdot \end{matrix} \cdot \begin{matrix} s_i \\ \end{matrix}}{\begin{matrix} Q_i \\ \cdot \end{matrix} \cdot \begin{matrix} z_i \\ \end{matrix}}$$



Mamba v.s. Linear Attention Transformer

Four differences:

(1) Δ_i : input gate

(2) \tilde{A}_i : forget gate

$$(2)$$

$$\begin{matrix} h_i \\ h_{i-1} \end{matrix} = \begin{matrix} \textcolor{blue}{\tilde{A}_i} \\ \odot \end{matrix} + B_i \cdot \left(\begin{matrix} \Delta_i \\ \odot \\ x_i \end{matrix} \right)$$

$$\begin{matrix} y_i \\ \textcolor{gray}{D} \\ x_i \end{matrix} = \begin{matrix} C_i \\ \cdot \\ h_i \end{matrix} + \begin{matrix} \odot \end{matrix}$$

$$(2)$$

$$\begin{matrix} s_i \\ s_{i-1} \end{matrix} = \begin{matrix} \textcolor{red}{\tilde{A}_i} \\ \odot \end{matrix} + K_i^\top \cdot \begin{matrix} V_i \\ \odot \end{matrix}; \quad z_i = z_{i-1} + K_i^\top$$

$$y_i = \frac{Q_i \cdot S_i}{Q_i \cdot Z_i}$$



Mamba v.s. Linear Attention Transformer

Four differences:

(1) Δ_i : input gate

(2) \tilde{A}_i : forget gate

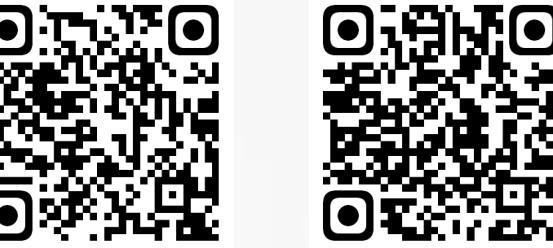
(3) $D \odot x_i$: shortcut

$$\begin{matrix} h_i \\ h_{i-1} \end{matrix} = \begin{matrix} \tilde{A}_i \\ \odot \end{matrix} + B_i \cdot \left(\begin{matrix} \Delta_i \\ \odot \\ x_i \end{matrix} \right)$$

$$\begin{matrix} y_i \\ \odot \\ x_i \end{matrix} = \begin{matrix} C_i \\ \cdot \\ h_i \end{matrix} + \begin{matrix} D \\ \odot \end{matrix}$$

$$\begin{matrix} s_i \\ s_{i-1} \end{matrix} = \begin{matrix} K_i^\top \\ \cdot \\ V_i \end{matrix} + \begin{matrix} \tilde{s}_i \\ \odot \end{matrix}; \quad \begin{matrix} z_i \\ z_{i-1} \end{matrix} = \begin{matrix} K_i^\top \\ \cdot \end{matrix}$$

$$y_i = \frac{\begin{matrix} Q_i \\ \cdot \\ S_i \end{matrix}}{\begin{matrix} Q_i \\ \cdot \\ Z_i \end{matrix}} + \begin{matrix} \tilde{y}_i \\ \odot \end{matrix}$$



Mamba v.s. Linear Attention Transformer

Four differences:

(1) Δ_i : input gate

(2) \tilde{A}_i : forget gate

(3) $D \odot x_i$: shortcut

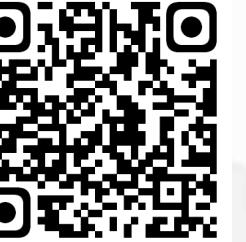
(4) $Q_i Z_i$: attention normalization

$$\begin{matrix} h_i \\ h_{i-1} \end{matrix} = \begin{matrix} \tilde{A}_i \\ \odot \end{matrix} + B_i \cdot \left(\begin{matrix} \Delta_i \\ \odot \\ x_i \end{matrix} \right)$$

$$\begin{matrix} y_i \\ \odot \\ \boxed{(4)} \end{matrix} = \frac{\begin{matrix} C_i \\ \cdot \\ h_i \end{matrix}}{\boxed{(4)}} + D \odot x_i$$

$$\begin{matrix} s_i \\ s_{i-1} \end{matrix} = \begin{matrix} \boxed{(4)} \\ + K_i^\top \cdot V_i \end{matrix}; \quad z_i = z_{i-1} + K_i^\top$$

$$\begin{matrix} y_i \\ \odot \\ \boxed{(4)} \end{matrix} = \frac{\begin{matrix} Q_i \\ \cdot \\ S_i \end{matrix}}{\boxed{(4)}} + Q_i \cdot Z_i$$

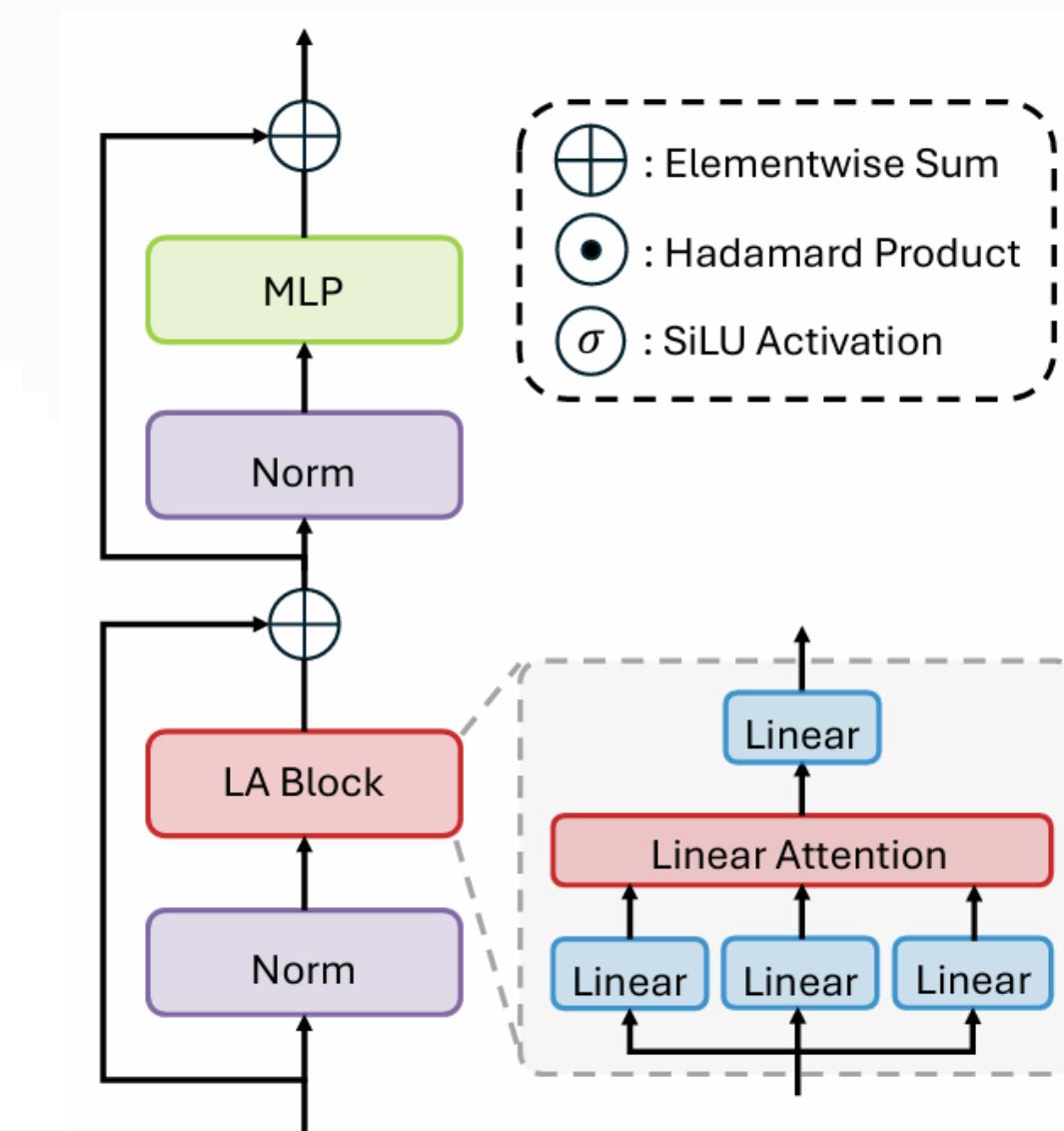


Mamba v.s. Linear Attention Transformer

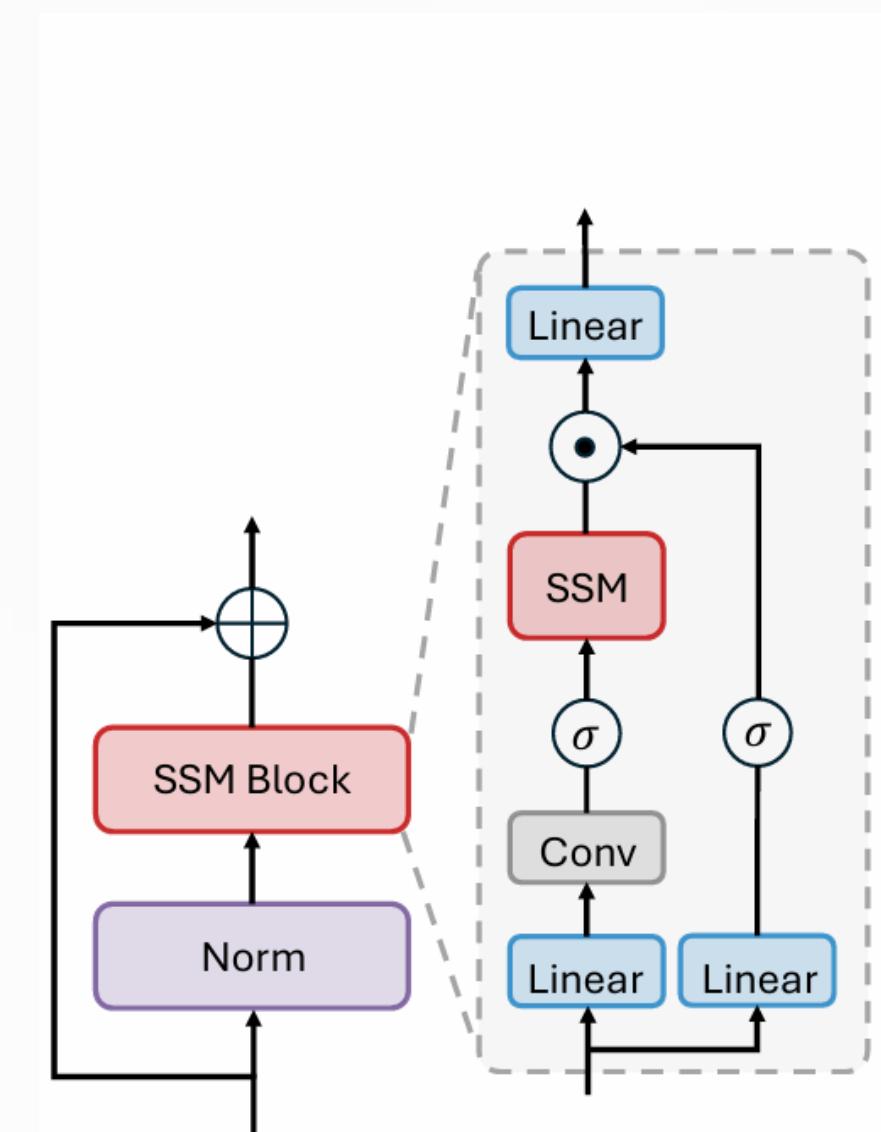
(5) Multi-head design:

- Selective SSM resembles single-head attention
- Linear attention commonly employ multi-head design

(6) Different macro design:



Linear Attention Transformer



Mamba



Mamba v.s. Linear Attention Transformer

Mamba can be viewed as
linear attention Transformer
with **six special designs**:

- (1) *input gate*
- (2) *forget gate*
- (3) *shortcut*
- (4) *no attention normalization*
- (5) *single-head design*
- (6) *modified block structure*

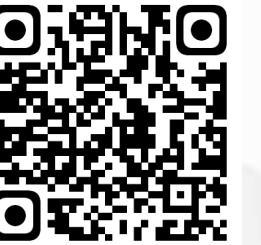
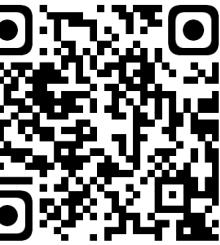




Empirical Study

	#Params	FLOPs	Throughput	Top-1
Baseline	28M	4.5G	1152	77.6
(1) + Input Gate	29M	4.5G	1069	77.8
(2) + Forget Gate	29M	4.8G	743	78.4
(3) + Shortcut	28M	4.5G	1066	77.8
(4) – Normalization	28M	4.5G	1215	72.4
(5) – Multi-head Design	24M	3.9G	1540	73.5
(6) + Block Design	31M	4.8G	1010	80.9

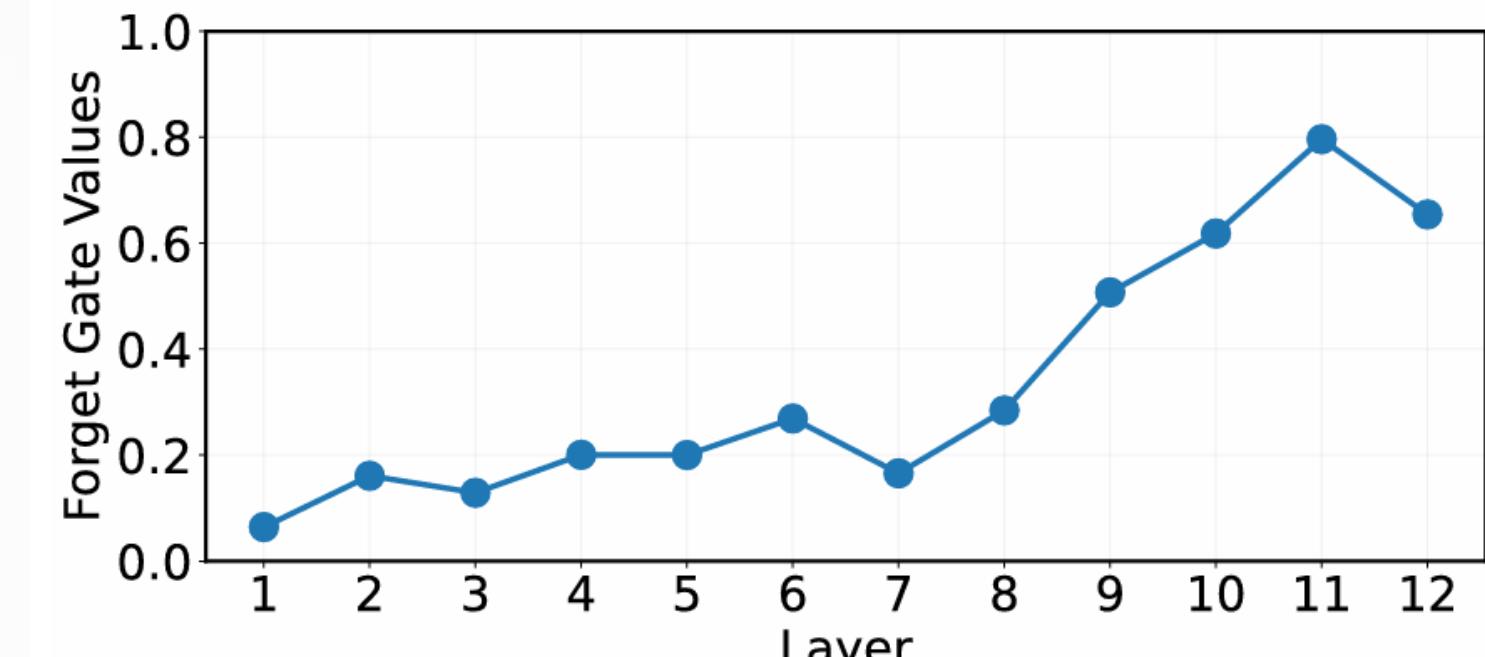
The **forget gate** and **block design** tend to be the core contributors!



Empirical Study

- The **forget gate** needs *recurrent calculation*, which is not ideal for vision models.
- Proper **positional encoding** can function as the forget gate in vision tasks, while preserving *parallelizable computation*.

	#Params	FLOPs	Throughput	Top-1
Baseline	28M	4.5G	1152	77.6
+ Forget Gate	29M	4.8G	743	78.4
+ APE [8]	30M	4.5G	1132	80.0
+ LePE [7]	28M	4.5G	1074	81.6
+ CPE [4]	28M	4.5G	1099	81.7
+ RoPE [33]	28M	4.5G	1113	80.0



(a) Forget Gate Average



$\tilde{A}_i = 0.2 \quad \tilde{A}_i = 0.6 \quad \tilde{A}_i = 0.8$

(b) Forget Gate Illustration

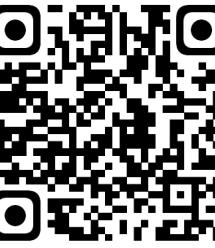


Empirical Study

Based on these findings, we propose a

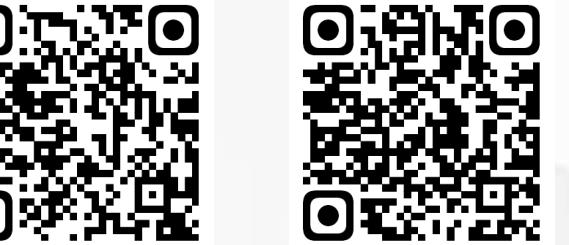
Mamba-Inspired Linear Attention (MILA) model

by incorporating the merits of Mamba's two key designs
into linear attention.

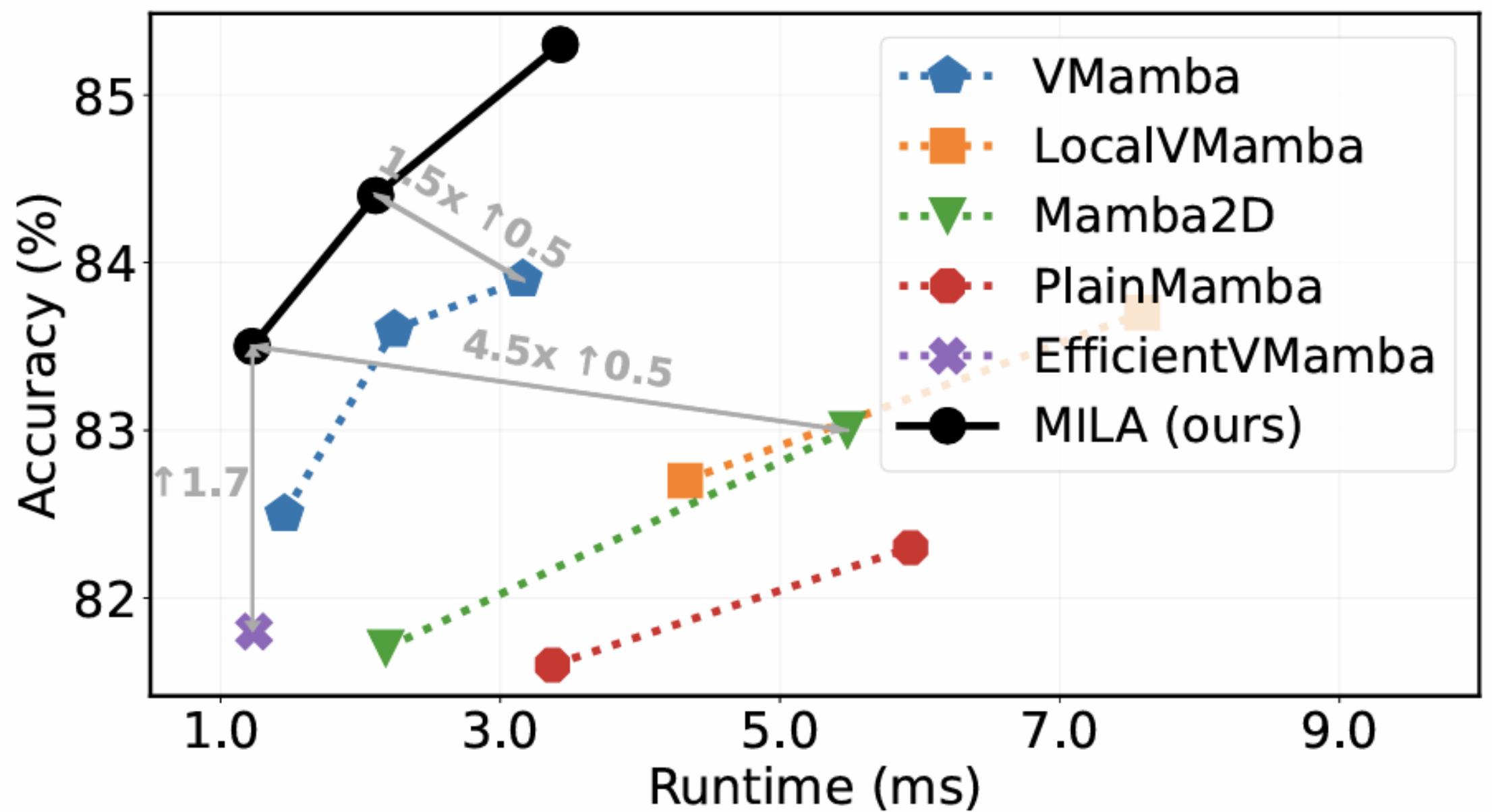


Empirical Study: ImageNet Classification

Method	Type	#Params	FLOPs	Top-1	Method	Type	#Params	FLOPs	Top-1
ConvNeXt-T [33]	CNN	29M	4.5G	82.1	ConvNeXt-S [33]	CNN	50M	8.7G	83.1
MambaOut-T [51]	CNN	27M	4.5G	82.7	MambaOut-S [51]	CNN	48M	9.0G	84.1
Swin-T [32]	Transformer	29M	4.5G	81.3	PVTv2-B3 [44]	Transformer	45M	7.9G	83.2
PVTv2-B2 [44]	Transformer	25M	4.0G	82.0	CSwin-S [9]	Transformer	35M	6.9G	83.6
Focal-T [50]	Transformer	29M	4.9G	82.2	Focal-S [50]	Transformer	51M	9.4G	83.6
MViTv2-T [28]	Transformer	24M	4.7G	82.3	MViTv2-S [28]	Transformer	35M	7.0G	83.6
CSwin-T [9]	Transformer	23M	4.3G	82.7	VMamba-S [31]	Mamba	50M	8.7G	83.6
DiNAT-T [19]	Transformer	28M	4.3G	82.7	LocalVMamba-S [25]	Mamba	50M	11.4G	83.7
NAT-T [20]	Transformer	28M	4.3G	83.2	MILA-S	MILA	43M	7.3G	84.4
PlainMamba-L1 [49]	Mamba	7M	3.0G	77.9	ConvNeXt-B [33]	CNN	89M	15.4G	83.8
Vim-S [57]	Mamba	26M	5.1G	80.3	MambaOut-B [51]	CNN	85M	15.8G	84.2
LocalVim-S [25]	Mamba	28M	4.8G	81.2	PVTv2-B5 [44]	Transformer	82M	11.8G	83.8
PlainMamba-L2 [49]	Mamba	25M	8.1G	81.6	Focal-B [50]	Transformer	90M	16.4G	84.0
Mamba2D-S [27]	Mamba	24M	—	81.7	CSwin-B	Transformer	78M	15.0G	84.2
EfficientVMamba-B [38]	Mamba	33M	4.0G	81.8	NAT-B [20]	Transformer	90M	13.7G	84.3
VMamba-T [31]	Mamba	31M	4.9G	82.5	PlainMamba-L3 [49]	Mamba	50M	14.4G	82.3
LocalVMamba-T [25]	Mamba	26M	5.7G	82.7	Mamba2D-B [27]	Mamba	94M	—	83.0
MILA-T	MILA	25M	4.2G	83.5	VMamba-B [31]	Mamba	89M	15.4G	83.9
					MILA-B	MILA	96M	16.2G	85.3



Empirical Study: Efficiency





Empirical Study: Object Detection

(b) Mask R-CNN 3x on COCO									
Method	Type	#Params	FLOPs	AP ^b	AP ^b ₅₀	AP ^b ₇₅	AP ^m	AP ^m ₅₀	AP ^m ₇₅
ConvNeXt-T [33]	CNN	48M	262G	46.2	67.9	50.8	41.7	65.0	44.9
Swin-T [32]	Transformer	48M	267G	46.0	68.1	50.3	41.6	65.1	44.9
PVTv2-B2 [44]	Transformer	45M	309G	47.8	69.7	52.6	43.1	66.8	46.7
FocalNet-T [50]	Transformer	49M	268G	48.0	69.7	53.0	42.9	66.5	46.1
Vmamba-T [31]	Mamba	50M	270G	48.9	70.6	53.6	43.7	67.7	46.8
LocalVMamba-T [25]	Mamba	45M	291G	48.7	70.1	53.0	43.4	67.0	46.4
MILA-T	MILA	44M	255G	48.8	71.0	53.6	43.8	68.0	46.8
ConvNeXt-S [33]	CNN	70M	348G	47.9	70.0	52.7	42.9	66.9	46.2
Swin-S [32]	Transformer	69M	354G	48.2	69.8	52.8	43.2	67.0	46.1
PVTv2-B3 [44]	Transformer	65M	397G	48.4	69.8	53.3	43.2	66.9	46.7
FocalNet-S [50]	Transformer	72M	365G	49.3	70.7	54.2	43.8	67.9	47.4
CSWin-S [9]	Transformer	54M	342G	50.0	71.3	54.7	44.5	68.4	47.7
Vmamba-S [31]	Mamba	70M	384G	49.9	70.9	54.7	44.2	68.2	47.7
LocalVMamba-S [25]	Mamba	69M	414G	49.9	70.5	54.4	44.1	67.8	47.4
MILA-S	MILA	63M	319G	50.5	71.8	55.2	44.9	69.1	48.2



Take-away Messages

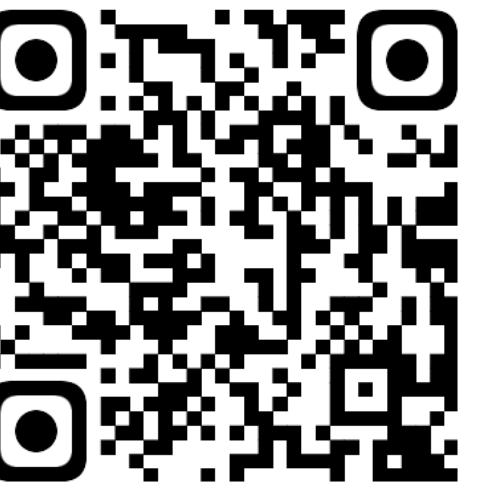
- ✓ We reveal the *surprisingly close relationship* between the powerful Mamba and subpar linear attention Transformer
- ✓ We identify that the *forget gate* and *block design* are the core factors behind Mamba's success
- ✓ We propose ***Mamba-Inspire Linear Attention (MILA)*** model, enjoying *high performance* while maintaining *parallel computation* and *fast inference speed*.



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paper



code



Thank you!

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