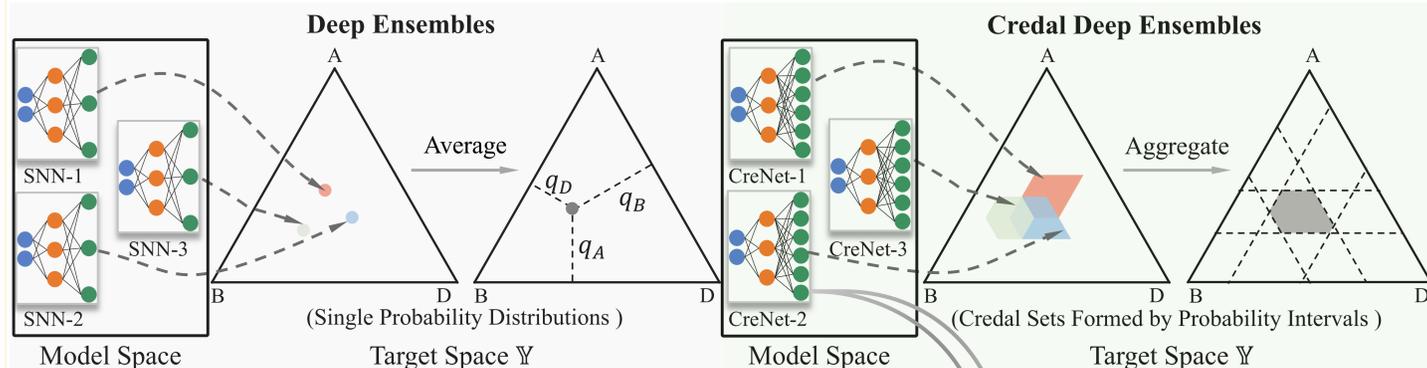


Concept & Methodology



Credal Set Prediction via Probability Intervals

Generating Probability Intervals via Interval SoftMax

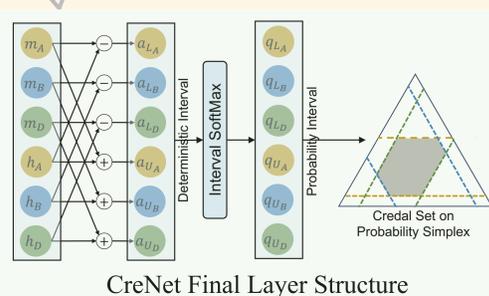
$$q_{L_i} = \frac{\exp(a_{L_i})}{\exp(a_{L_i}) + \sum_{k \neq i} \exp\left(\frac{a_{L_k} + a_{L_k}}{2}\right)}; q_{U_i} = \frac{\exp(a_{U_i})}{\exp(a_{U_i}) + \sum_{k \neq i} \exp\left(\frac{a_{L_k} + a_{L_k}}{2}\right)}$$

Probability interval vector $\mathbf{q} = \{q_{L_i}, q_{U_i}\}_i^C$ satisfies:

$$q_{L_i} \leq q_{U_i} \forall i = 1, \dots, C; \sum_i q_{L_i} \leq 1 \leq \sum_i q_{U_i}$$

Defining a Non-empty Credal Set \mathbb{Q}

$$\mathbb{Q} = \{\mathbf{q} | q_i \in [q_{L_i}, q_{U_i}] \forall i; \sum_i q_i = 1\}$$



Training Procedure

Vanilla Training Strategy

$$\text{minimize}_{\theta \in \Theta} \left\{ \frac{1}{N} \sum_n \mathcal{L}(\mathbf{x}_n, \mathbf{t}_n, \theta) \right\}$$

$\{\mathbf{x}_n, \mathbf{t}_n\}_n^N$: training set; θ trainable model parameter in the space Θ ; $\mathcal{L}(\cdot, \cdot)$: an arbitrary loss function.

Distributionally Robust Optimization (DRO) using Adversarially Reweighted Learning

$$\text{minimize}_{\theta \in \Theta} \left\{ \text{maximize}_{\mathbf{w} \in \mathcal{S}} \frac{1}{N} \sum_n w_n \mathcal{L}(\mathbf{x}_n, \mathbf{t}_n, \theta) \right\}$$

A minimax game between a learner and an adversary.

w_n : an adversarial assignment of weights, collected in \mathbf{w} ; the set \mathcal{S} of weight vectors varies across implementations.

CreNet Loss Design

$$\mathcal{L}_{\text{cre}} = \frac{1}{N} \sum_n \text{CE}(\mathbf{q}_{U_n}, \mathbf{t}_n) + \text{maximize}_{\mathbf{w} \in \mathcal{S}} \frac{1}{N} \sum_n w_n \text{CE}(\mathbf{q}_{L_n}, \mathbf{t}_n)$$

CE: cross-entropy loss.

Vanilla Component

- Take the training distribution at face value.
- Encourage “optimistic/upper-bound” predictions.

DRO Component

- Weigh training outliers to simulate future differences in data distribution at test time.
- Encourage “pessimistic/lower-bound” predictions.

CreNet Loss Implementation

Algorithm 1 CreNet Training Procedure

Input: Training dataset $\mathbb{D} = \{\mathbf{x}_n, \mathbf{t}_n\}_{n=1}^N$; Portion of samples per batch $\delta \in [0.5, 1)$; Batch size η

while enable training do

1. Compute $\text{CE}(\mathbf{q}_{U_n}, \mathbf{t}_n)$ and $\text{CE}(\mathbf{q}_{L_n}, \mathbf{t}_n)$ for each sample
2. Sort the sample indices (m_1, \dots, m_η) in descending order of $\text{CE}(\mathbf{q}_{L_n}, \mathbf{t}_n)$
3. Define $\eta_\delta = \lfloor \delta \eta \rfloor$
4. Minimize $\mathcal{L}_{\text{CreNet}} = \frac{1}{\eta} \sum_{n=1}^{\eta_\delta} \text{CE}(\mathbf{q}_{U_n}, \mathbf{t}_n) + \frac{1}{\delta \cdot \eta} \sum_{j=1}^{\eta_\delta} \text{CE}(\mathbf{q}_{L_{m_j}}, \mathbf{t}_{m_j})$

end while

Class Prediction & Uncertainty Quantification

Maximax and Maximin Criteria for Class Prediction

$$\hat{l}_{\min} := \text{argmax}_i q_{L_i}^*; \hat{l}_{\max} := \text{argmax}_i q_{U_i}^*$$

Output the class indices with the highest lower and upper reachable probability, respectively.

$$q_{L_i}^* = \max(q_{L_i}, 1 - \sum_{j \neq i} q_{U_j}); q_{U_i}^* = \min(q_{U_i}, 1 - \sum_{j \neq i} q_{L_j})$$

Generalized Shannon Entropy for Uncertainty Quantification

$$\bar{H}(\mathbb{Q}) = \text{maximize} \sum_i^C -q_i \log_2 q_i \text{ s.t. } \sum_i^C q_i = 1; q_{L_i}^* \leq q_i \leq q_{U_i}^*$$

For $\underline{H}(\mathbb{Q})$, replace maximize by minimize.

Aleatoric uncertainty (AU) and epistemic uncertainty (EU) are measured by $\underline{H}(\mathbb{Q})$ and $\bar{H}(\mathbb{Q}) - \underline{H}(\mathbb{Q})$, respectively.

Experimental Validation

Table 1. OOD detection performance (% , \uparrow) using EU between on ResNet50 architecture.

	CIFAR10 (ID)		CIFAR100 (ID)		ImageNet (ID)					
	SVHN (OOD)	Tiny-ImageNet (OOD)	SVHN (OOD)	Tiny-ImageNet (OOD)	ImageNet-O (OOD)	ImageNet-O (OOD)				
	AUROC	AUPRC	AUROC	AUPRC	AUROC	AUPRC				
DEs	89.58 \pm 0.93	92.29 \pm 1.00	86.87 \pm 0.20	83.02 \pm 0.16	73.83 \pm 1.97	84.96 \pm 1.25	78.80 \pm 0.20	74.68 \pm 0.27	65.03 \pm 0.53	62.77 \pm 0.38
CreDEs	96.55\pm0.25	98.17\pm0.17	88.10\pm0.26	87.85\pm0.35	78.55\pm1.15	86.57\pm0.65	82.54\pm0.26	77.60\pm0.44	67.82\pm0.06	62.80\pm0.12

Table 2. OOD detection performance (% , \uparrow) using EU between on different architecture.

	CIFAR10 (ID) [VGG16]		CIFAR10 (ID) [ViT Base]	
	SVHN (OOD)	Tiny-ImageNet (OOD)	SVHN (OOD)	Tiny-ImageNet (OOD)
	AUROC	AUPRC	AUROC	AUPRC
DEs	82.19 \pm 0.82	87.52 \pm 0.81	78.58 \pm 0.15	73.28 \pm 0.23
CreDEs	87.68\pm0.73	93.47\pm0.67	82.56\pm0.28	80.81\pm0.52

	CIFAR10 (ID) [VGG16]		CIFAR10 (ID) [ViT Base]	
	SVHN (OOD)	Tiny-ImageNet (OOD)	SVHN (OOD)	Tiny-ImageNet (OOD)
	AUROC	AUPRC	AUROC	AUPRC
DEs	82.19 \pm 0.82	87.52 \pm 0.81	77.71 \pm 1.97	88.73 \pm 0.32
CreDEs	87.68\pm0.73	93.47\pm0.67	88.57\pm2.08	93.24\pm1.25

Figure 1. OOD detection (CIFAR10 vs CIFAR10-C) over increased corruption intensity on distinct architecture.

Table 3. Test ACC (% , \uparrow) and ECE (\downarrow) on ResNet50 architecture.

	CIFAR10		CIFAR100		ImageNet	
	ACC (%)	ECE	ACC (%)	ECE	ACC (%)	ECE
DEs	93.32 \pm 0.13	0.013 \pm 0.001	73.83 \pm 1.97	0.039 \pm 0.003	77.92 \pm 0.02	0.242 \pm 0.001
CreDEs	\hat{l}_{\min} 93.73\pm0.11	0.009\pm0.002	\hat{l}_{\min} 79.54\pm0.21	0.027\pm0.002	\hat{l}_{\min} 78.41\pm0.02	0.593\pm0.001
	\hat{l}_{\max} 93.74\pm0.11	0.011\pm0.002	\hat{l}_{\max} 79.65\pm0.19	0.027\pm0.002	\hat{l}_{\max} 78.51\pm0.02	0.169\pm0.000

Additional Findings

- Uncertainty quantification performance robust against training hyper parameter δ
- Improved total uncertainty estimation quality

- EU quantification quality robust against different measures like generalized Hartley measure
- Enhanced uncertainty quantification compared to deep ensembles that applied the DRO strategy or ‘product of experts’ strategy and several Bayesian neural network baselines
- Superior performance in a case study of active learning
- Marginal increase in inference complexity compared to deep ensembles

