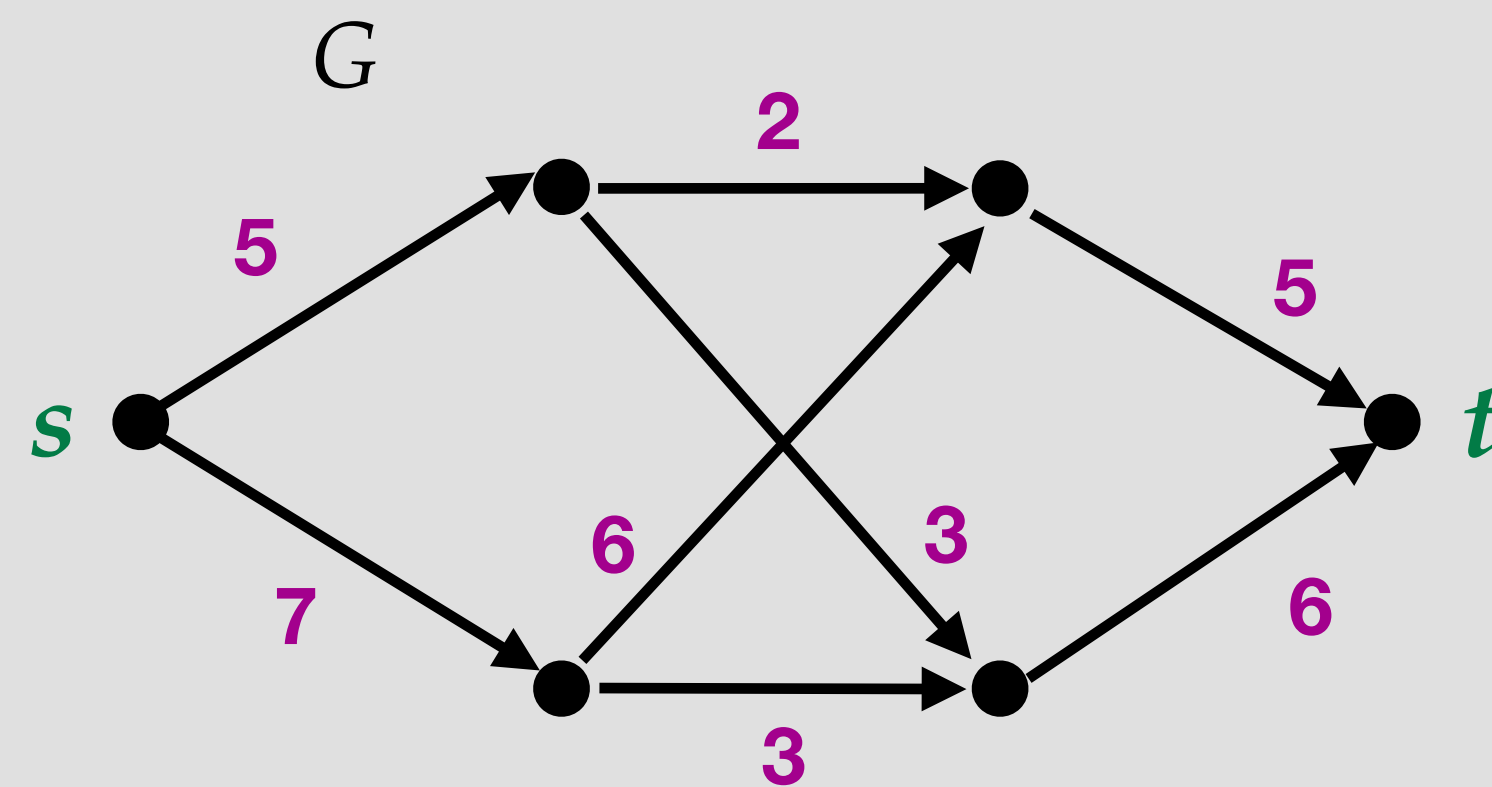


Warm-starting Push-Relabel

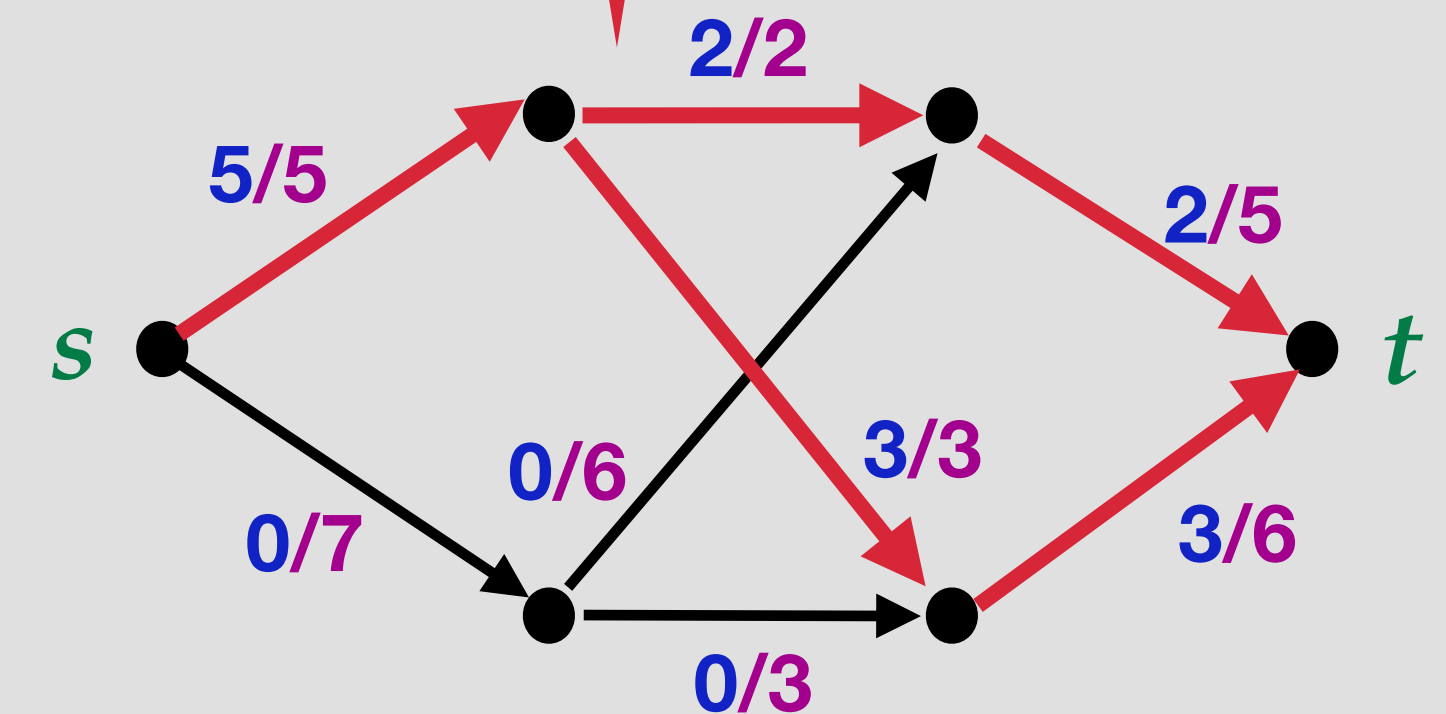
Sami Davies (UC Berkeley), Sergei Vassilvitskii (Google Research—New York),
Yuyan Wang (Google Research—New York)

Network flow

- ◆ Transportation
- ◆ Intrusion detection
- ◆ Network connectivity



Flows satisfy capacity and conservation constraints



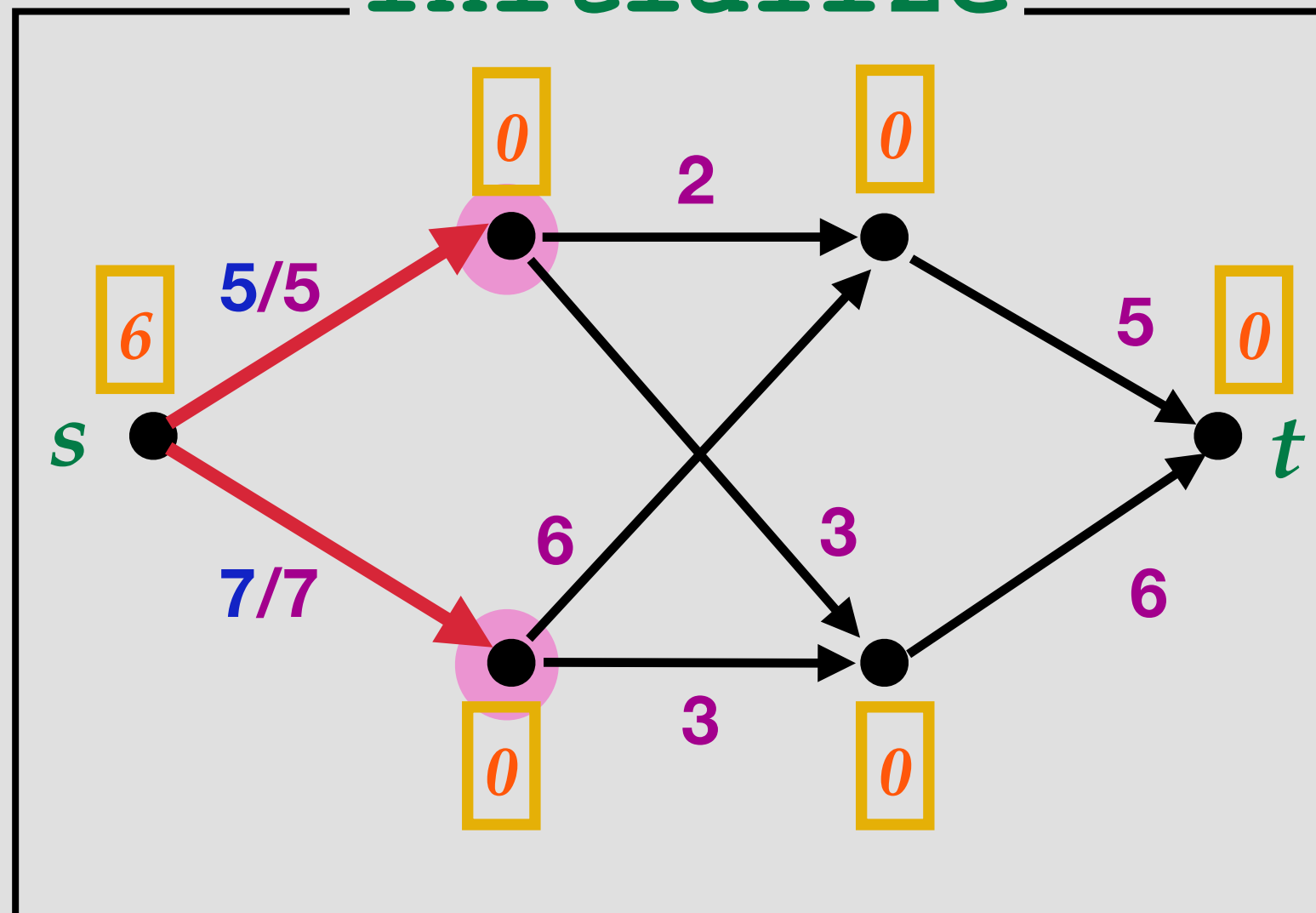
Push-Relabel

Height of a node u estimates length of shortest path between u and t in the residual graph

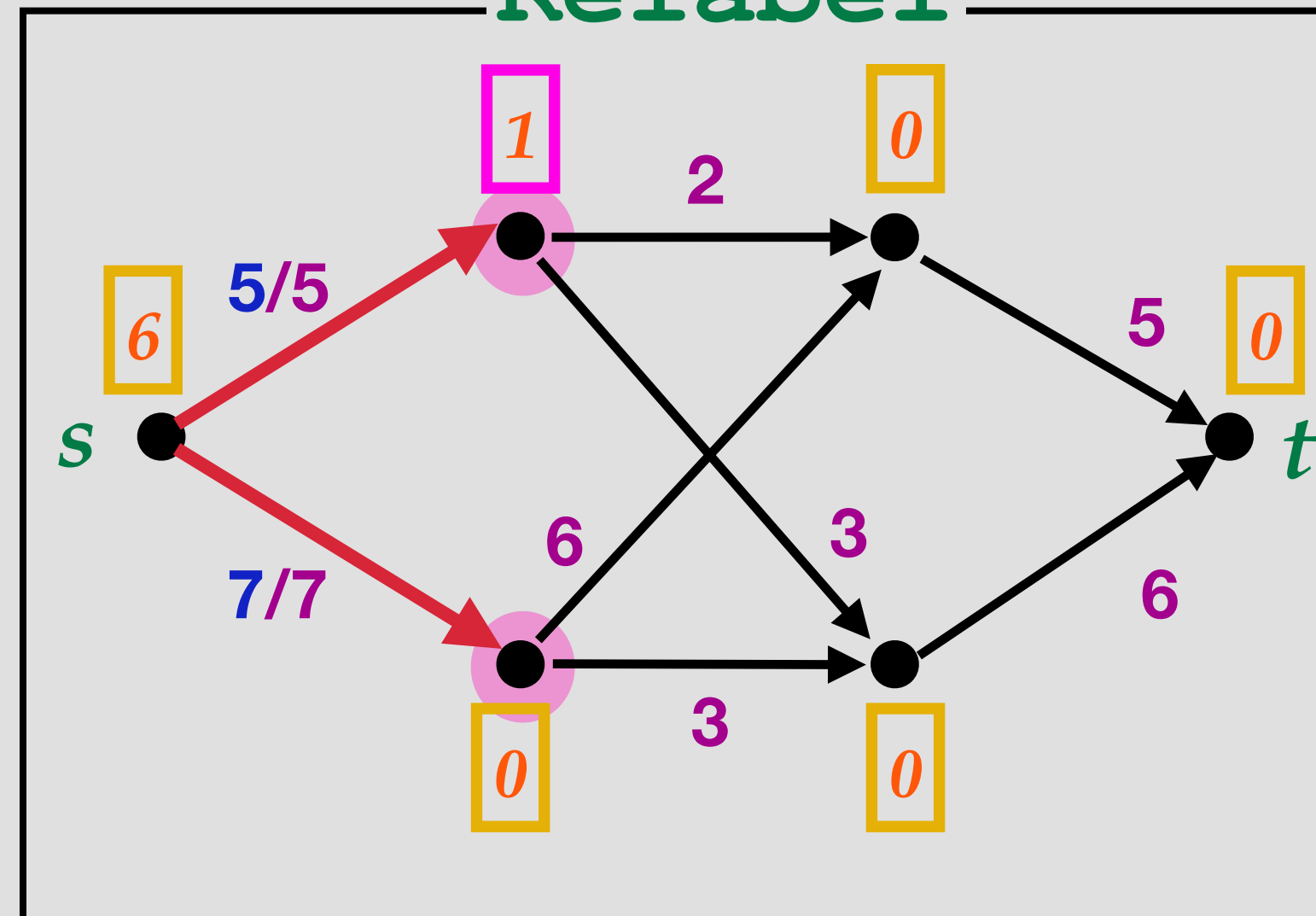
Push-Relabel (high level)

- ▶ Keeps track of a **pre-flow** on edges and **heights** for the nodes
- ▶ Algorithm is iterative—while there is a u node with **excess** flow
 1. Push flow from u with height h to a node with height $h-1$ (send flow “downhill”/ closer to t) or
 2. Increase height of u

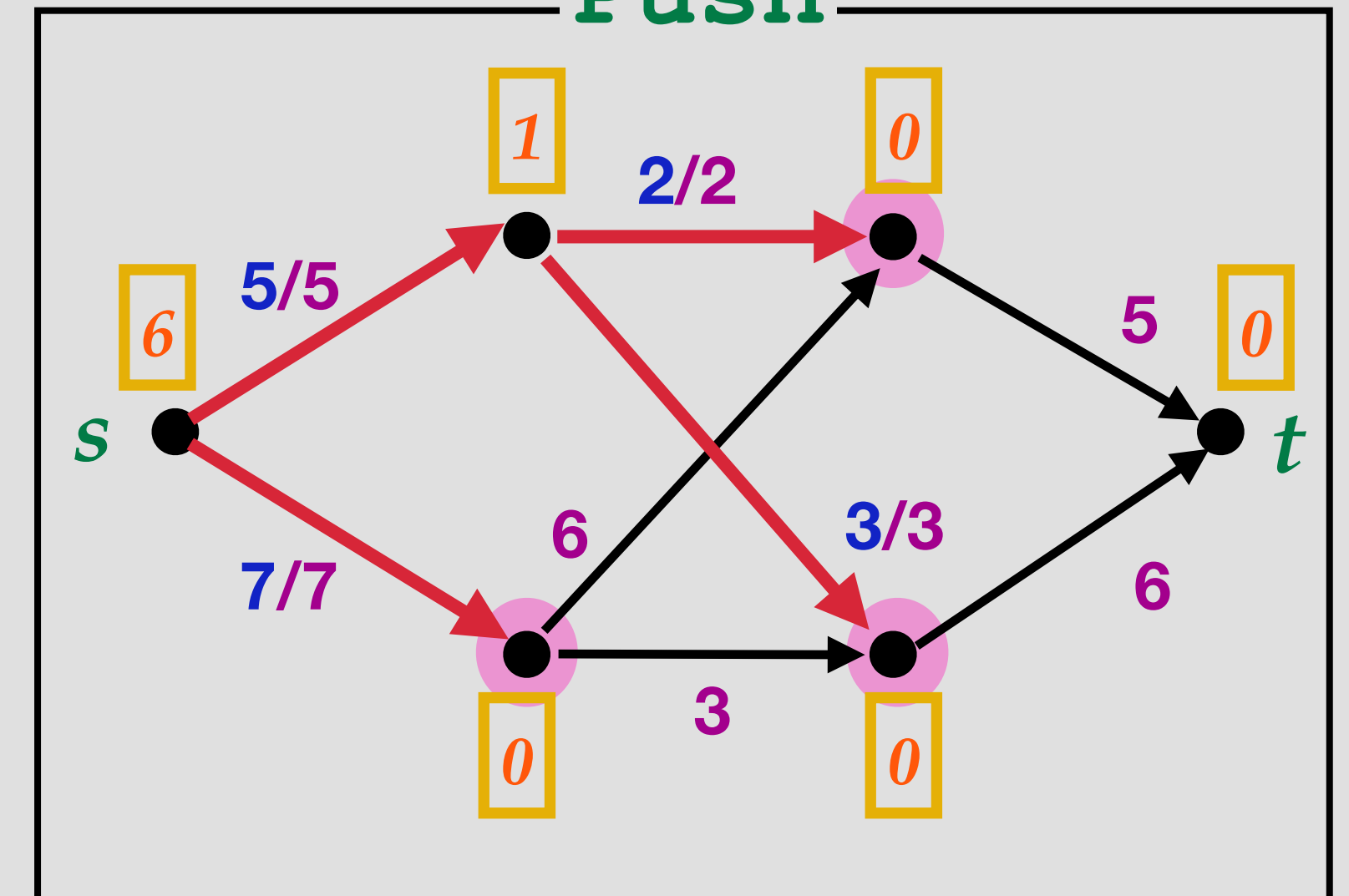
Initialize



Relabel



Push



Push-Relabel

Push-Relabel (high level)

- ▶ Keeps track of a **pre-flow** on edges and **heights** for the nodes
- ▶ Algorithm is iterative—while there is a u node with **excess** flow
 1. Push flow from u with height h to a node with height $h-1$ (send flow “downhill”/ closer to t) or
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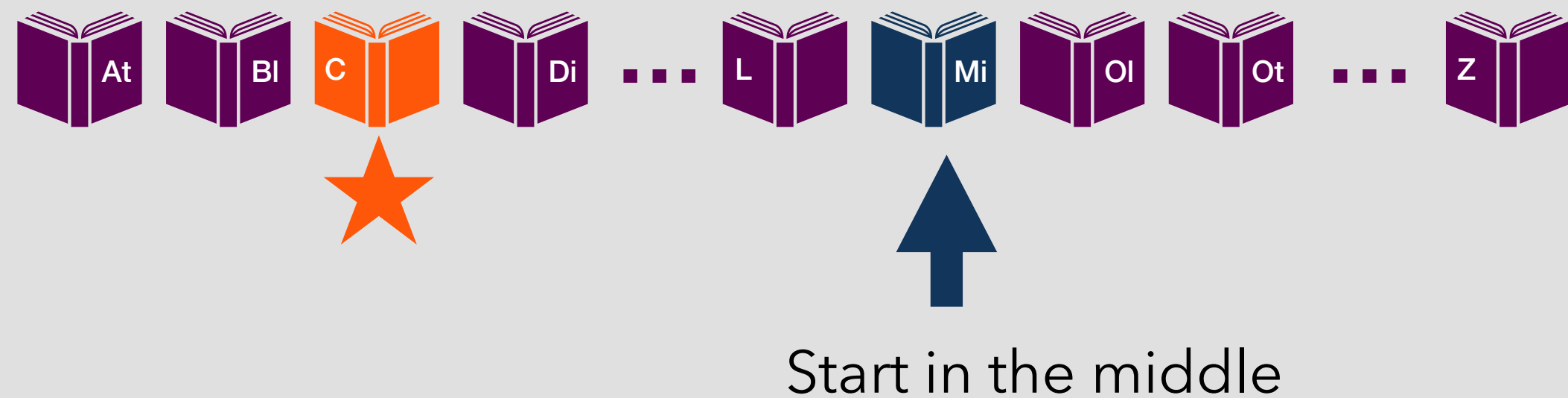
$O(|V|^2 |E|)$ running time [Goldberg, Tarjan '86] (or faster $O(|V|^2 \sqrt{|E|})$ with heuristics)
Considered the benchmark for max flow algorithms in practice

Why is Push-Relabel so much better in practice than its theoretical guarantees?

Learning-augmented algorithms

Goal: find book by author Lewis Carroll, n books total

Vanilla binary search



▶ Run-time $O(\log n)$

Learning-augmented binary search



▶ Run-time $O(\log err)$

Algorithm has access to a learned **prediction**
Prediction can guide the algorithm's decisions

Learning-augmented algorithms

Goal: find book by author Lewis Carroll, n books total

Vanilla binary search

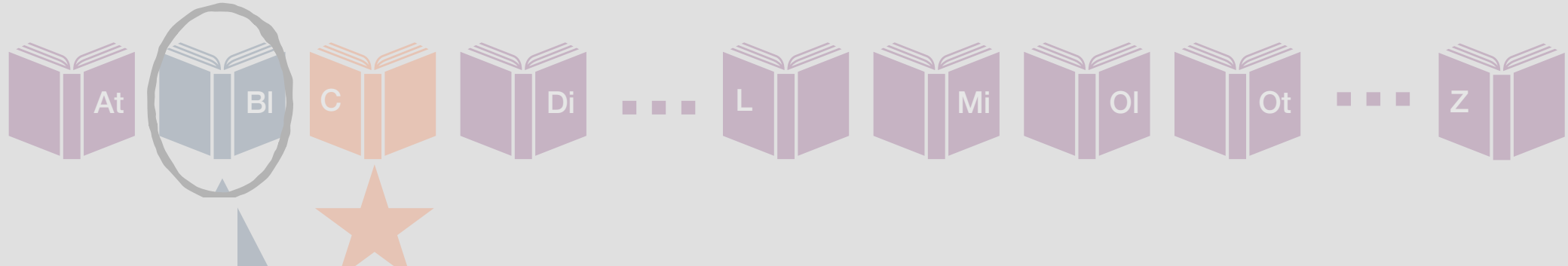


>200 papers in past 5 years!

<https://algorithms-with-predictions.github.io/>

- ▶ Learned indexes [Kraska et al PODS18]
- ▶ Caching [Lykouris and Vassilvitskii JACM21]
- ▶ Social welfare maximization [Banerjee et al SODA22]

Learning-augmented binary search



Learning-augmented Push-Relabel

First proof that the *gap-relabeling heuristic* (popular in practice) can improve the performance of PR!

Main results:

- ▶ Can improve running-time of Push-Relabel with good predicted flows

With predicted flow \hat{f} , find optimal f^* in time $O(|V|^2 \cdot \min\{\|\hat{f} - f^*\|_1, |E|\})$.

- ▶ If optimal f^* has value $\leq \eta$, can find an optimal flow in time $O(\eta \cdot |V|^2)$.

- ▶ Apply our algorithm to image segmentation instances. Empirically obtain speed up using predicted flows, theory is predictive of practice!