

When can Regression-Adjusted Control Variates Help?

Rare Events, Sobolev Embedding and Minimax Optimality

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OF MATHEMATICAL SCIENCES

Agenda

Part I: Intro to Regression-Adjusted Control Variates (RACV)

- ▶ What is a RACV-based algorithm? How to interpret it as an estimator?
- ▶ Applications in various fields (numerical analysis - quadrature rule, trace estimation; statistics - causal inference; machine learning - gradient estimation)

Part II: Information Theoretic Lower Bound

- ▶ Recap of non-parametric statistics - what is minimax optimality?
- ▶ Information Theoretic Lower Bound for Quadrature Rules

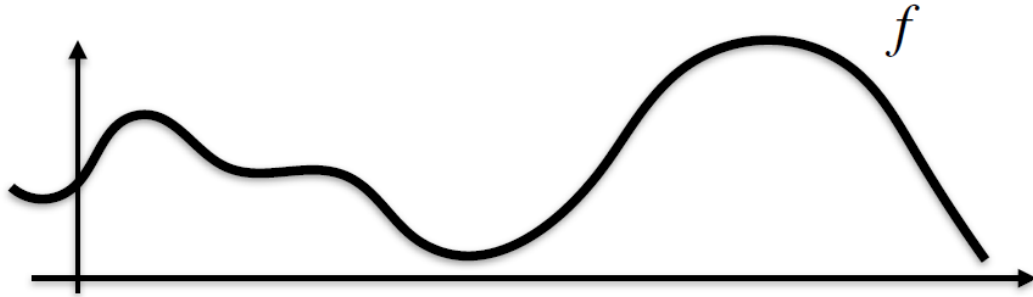
Part III: Minimax Optimal Upper Bound

- ▶ Claim: use different algorithms for functions of varying degrees of smoothness
- ▶ Proof Sketch: Use Sobolev Embedding Theorem appropriately



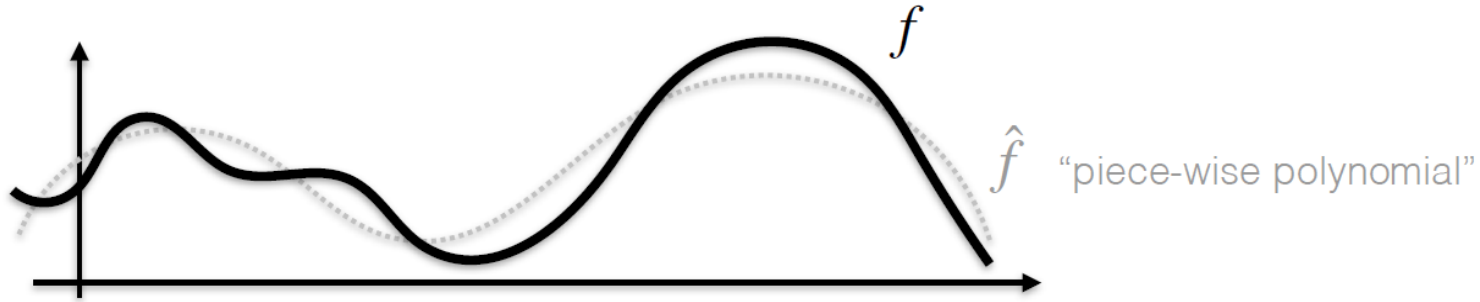
Quadrature Rule

Aim Estimate $\mathbb{E}_P f$



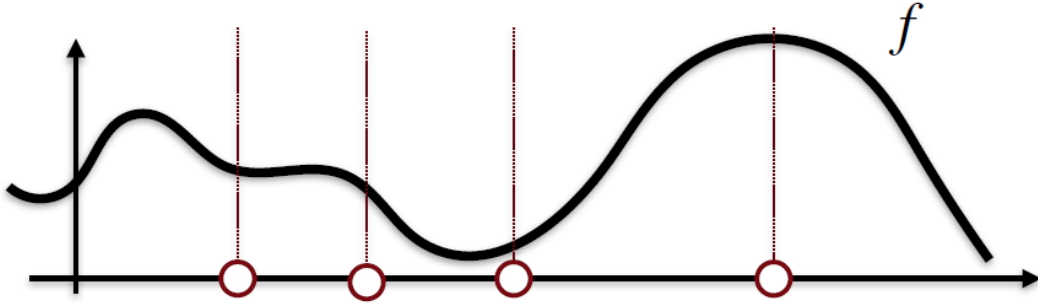
Quadrature Rule

Aim Estimate $\mathbb{E}_P f \approx \mathbb{E}_P \hat{f}$



Quadrature Rule via Monte Carlo

Aim Estimate $\mathbb{E}_P f \approx \mathbb{E}_{\hat{P}} f$



Key Idea: Doubly Robust Estimation

Aim Estimate $\mathbb{E}_P f \approx \mathbb{E}_P \hat{f}$
 $\approx \mathbb{E}_{\hat{P}} f$

$$\begin{aligned} xy &= x\hat{y} + x(y - \hat{y}) \\ &= \hat{x}y + y(x - \hat{x}) \end{aligned}$$

$$xy = \hat{x}y + \hat{y}x - \hat{x}\hat{y} + \underbrace{(y - \hat{y})(x - \hat{x})}_{\text{Smaller error}}$$

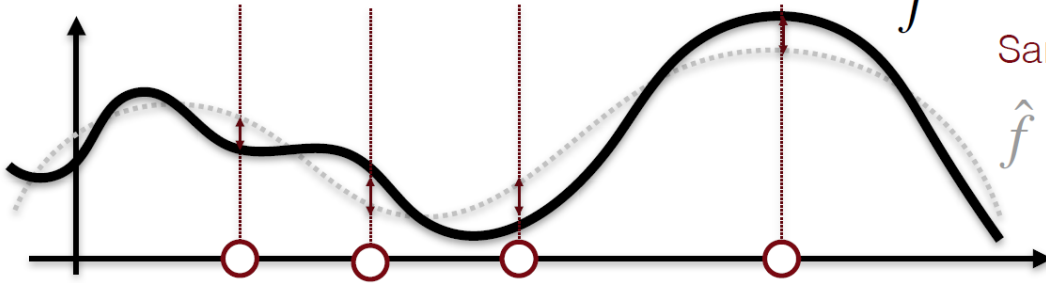


Quadrature Rule

Aim Estimate $\mathbb{E}_P f = \mathbb{E}_P \hat{f} + \mathbb{E}_P (f - \hat{f})$



Debiasing
"semi-"parametric



Sample extra data to know $f - \hat{f}$

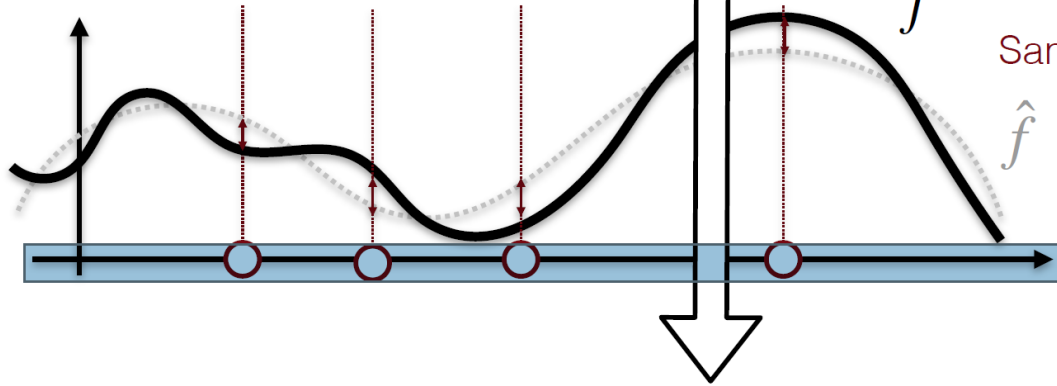


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(nonparametric-)“Regression-adjusted” control variate



Numerical Analysis: estimating the trace of a matrix

- ▶ Task: given matrix $A \in \mathbb{R}^{d \times d}$ and an oracle for computing matrix-vector multiplication (at most m queries), estimate $\text{tr}(A)$
- ▶ Naive Monte Carlo Algorithm (Hutch): appropriately sampled $X \in \mathbb{R}^{d \times m}$

$$\text{tr}(A) \approx \frac{1}{m} \sum_{i=1}^m x_i^T A x_i = \text{tr}(X^T A X)$$

- ▶ RACV-based Algorithm: appropriately sampled orthonormal matrices $Q, G \in \mathbb{R}^{d \times \frac{m}{3}}$

$$E_1 = \text{tr}(Q^T A Q), \quad E_2 = \text{tr}(G^T (I - Q Q^T) A (I - Q Q^T) G)$$

Estimator $E_1 + E_2 \approx \text{tr}(A)$ (Hutch++)

(Lin 2017; Mewyer-Musco-Musco-Woodruff 2020)



Machine Learning: estimation of gradient

- ▶ Task: estimate the gradient $\nabla_{\theta} \mathbb{E}_{q_{\theta}}[f(x)] = \mathbb{E}_{q_{\theta}}[f(x) \nabla_{\theta} \log q_{\theta}(x)]$ via $\{x_i\}_{i=1}^n$
- ▶ Naive Monte-Carlo estimator: $\frac{1}{n} \sum_{i=1}^n f(x_i) \nabla_{\theta} \log q_{\theta}(x_i)$
- ▶ Leave-one-out estimator:

$$\frac{1}{n} \sum_{i=1}^n \left(f(x_i) - \frac{1}{n-1} \sum_{j \neq i} f(x_j) \right) \nabla_{\theta} \log q_{\theta}(x_i)$$

- ▶ RACV-enhanced leave-one-out estimator: $E_1 + E_2$

$$E_1 = \frac{2}{n} \sum_{i=1}^{\frac{n}{2}} \left((f(x_i) - b(x_i)) - \frac{1}{\frac{n}{2} - 1} \sum_{1 \leq j \neq i \leq \frac{n}{2}} (f(x_j) - b(x_j)) \right) \nabla_{\theta} \log q_{\theta}(x_i)$$

$$E_2 = \frac{2}{n} \sum_{i=\frac{n}{2}+1}^n \left(b(x_i) - \frac{1}{\frac{n}{2} - 1} \sum_{\frac{n}{2} < j \neq i \leq n} b(x_j) \right) \nabla_{\theta} \log q_{\theta}(x_i)$$



Modern Applications of RACV

Other applications include:

- ▶ Conformal Prediction (Romano-Patterson-Candes 2019)
- ▶ Causal Inference (Jordan-Wang-Zhou 2022; Angelopoulos-Bates-Fannjiang-Jordan-Zrnic 2023)

Unifying Framework

- ▶ Step I: Get a "coarse" estimator via a subset of the data
- ▶ Step II: Obtain a "finer" estimator via calibration on the remaining dataset (estimating the bias)



Machine Learning Research

Aim: fit function $(x_i, y_i = f(x_i)), i = 1, 2, \dots, n$

Specify problem set, i.e. the space of f

Step 1 Information-Theoretical Lower Bound

Step 2 Statistical guarantee for the estimator

“Minimax Optimal” Algorithms

“worst case selection of f ”

Best Estimator

Information Theory

From Coding to Learning

FIRST EDITION

Yury Polyanskiy
Department of Electrical Engineering and Computer Science
Massachusetts Institute of Technology
Yihong Wu
Department of Statistics and Data Science
Yale University

Why we have a lower bound?

For all estimator $H : (\text{data})^{\otimes n} \rightarrow \text{function}$, we have

$$\sup_{f \in \mathcal{F}} \mathbb{E}_{\text{data}_i \sim f} \|H(\text{data}_1, \dots, \text{data}_n) - f\| \geq n^{\text{rate}}$$

$f \in \mathcal{F}$

$\|f\| < 1$



f_2

f_1

Using information theory

1. Generate similar data (in TV, KL...)

2. f_1 and f_2 have a **gap**

The gap is not distinguishable



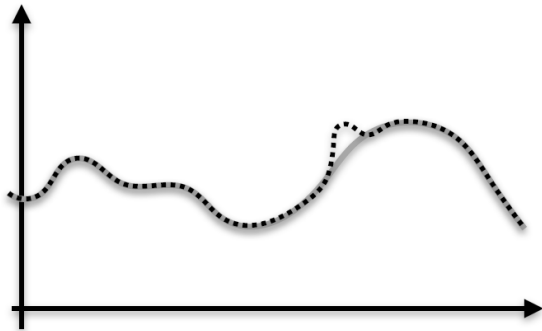
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Understanding this statistically...

Is this algorithm statistical optimal?



When this improves MC estimator?

Aim

Estimate $\mathbb{E}_P f$

Step 1

Using half of the data to estimate \hat{f}

Step 2

$$\mathbb{E}_P f = \mathbb{E}_P(\hat{f}) + \mathbb{E}_P(f - \hat{f})$$

Low order term



Understanding this statistically...



Is this algorithm statistical optimal?

Why consider q -th moment?

When this improves MC estimator?

Why consider $W^{s,p}$?

Aim

Estimate $\mathbb{E}_P f$ $\mathbb{E}_P f^q, f \in W^{s,p}$

Step 1

Using half of the data to estimate \hat{f}

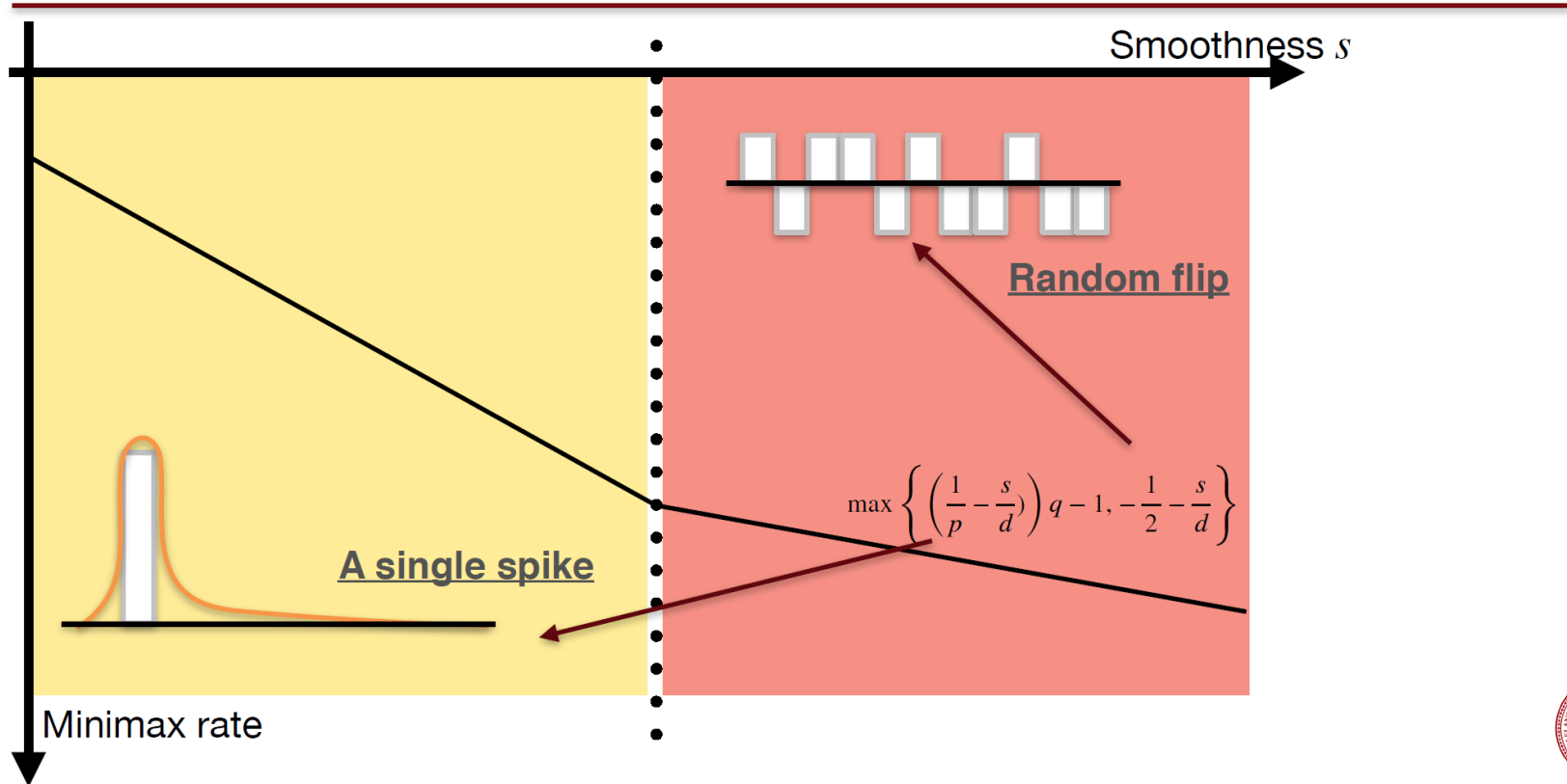
Step 2

$$\mathbb{E}_P f^q = \mathbb{E}_P (\hat{f})^q + \mathbb{E}_P (f - \hat{f})^q$$

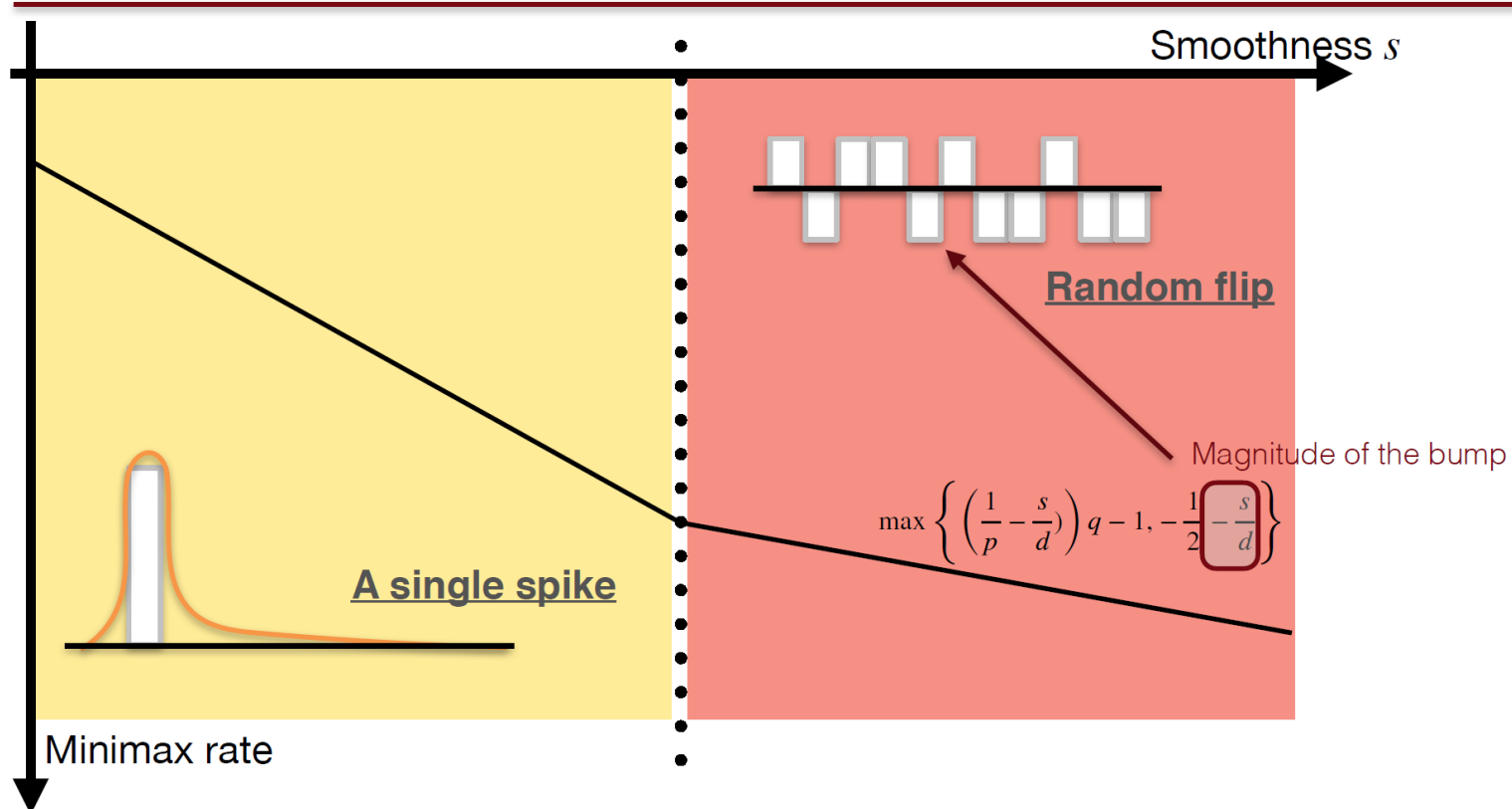
Low order term



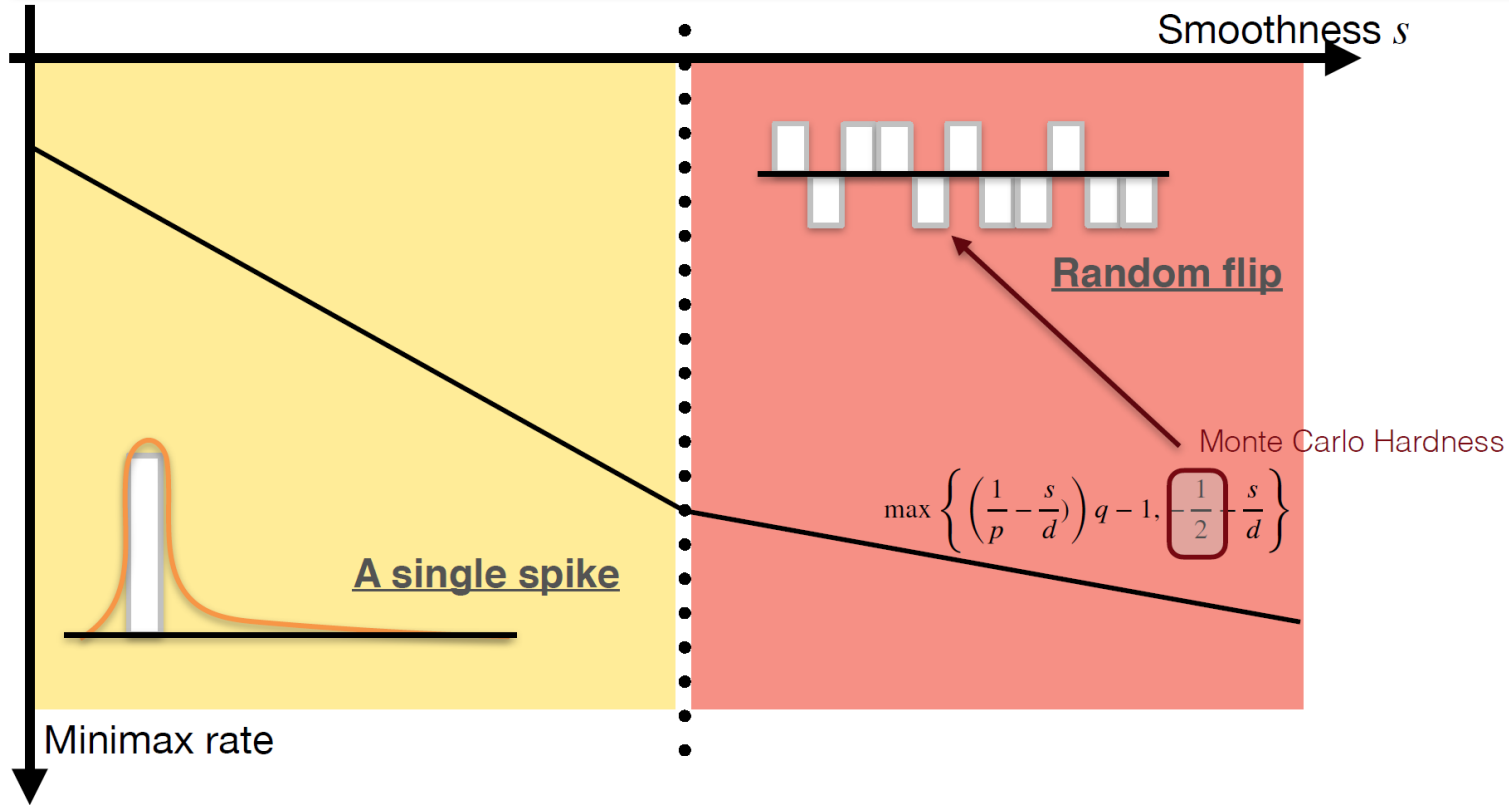
Setting the information theoretical limit



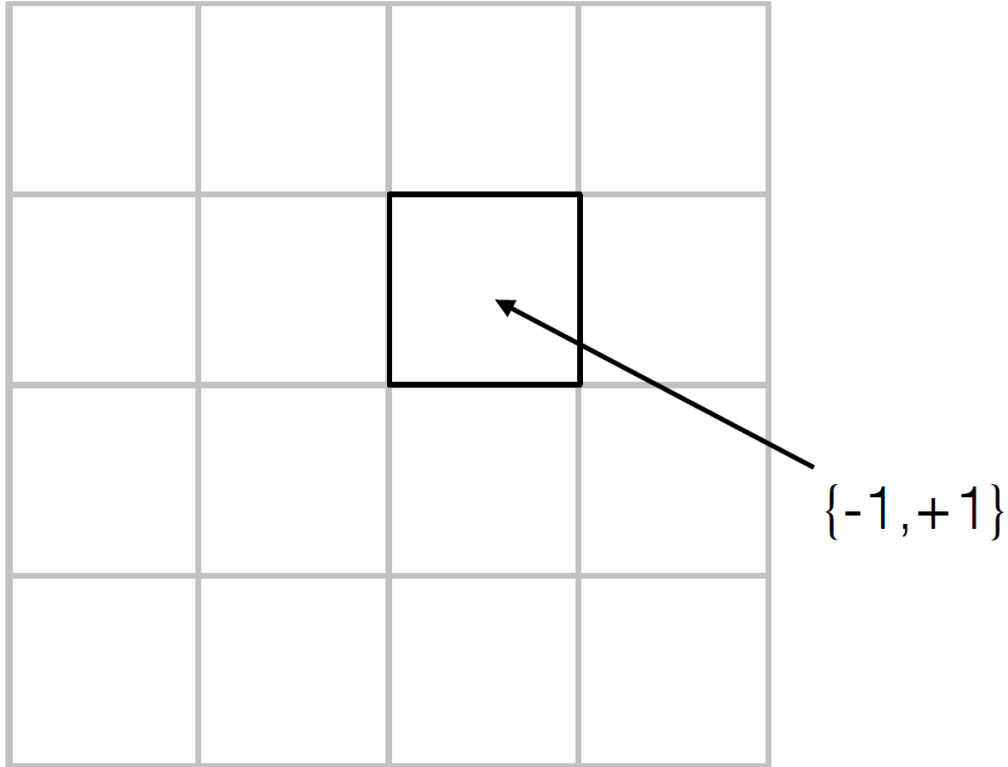
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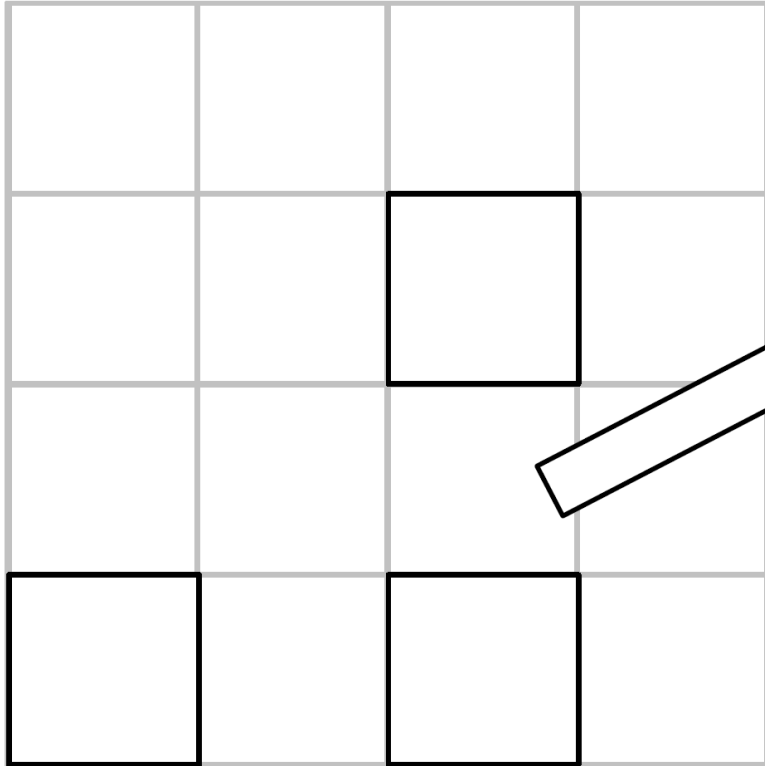
Setting the information theoretical limit



Understanding the hardness in this regime

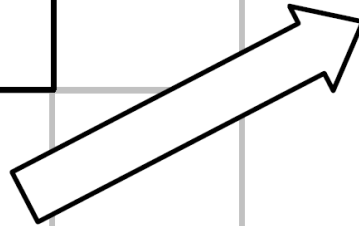


Understanding the hardness in this regime

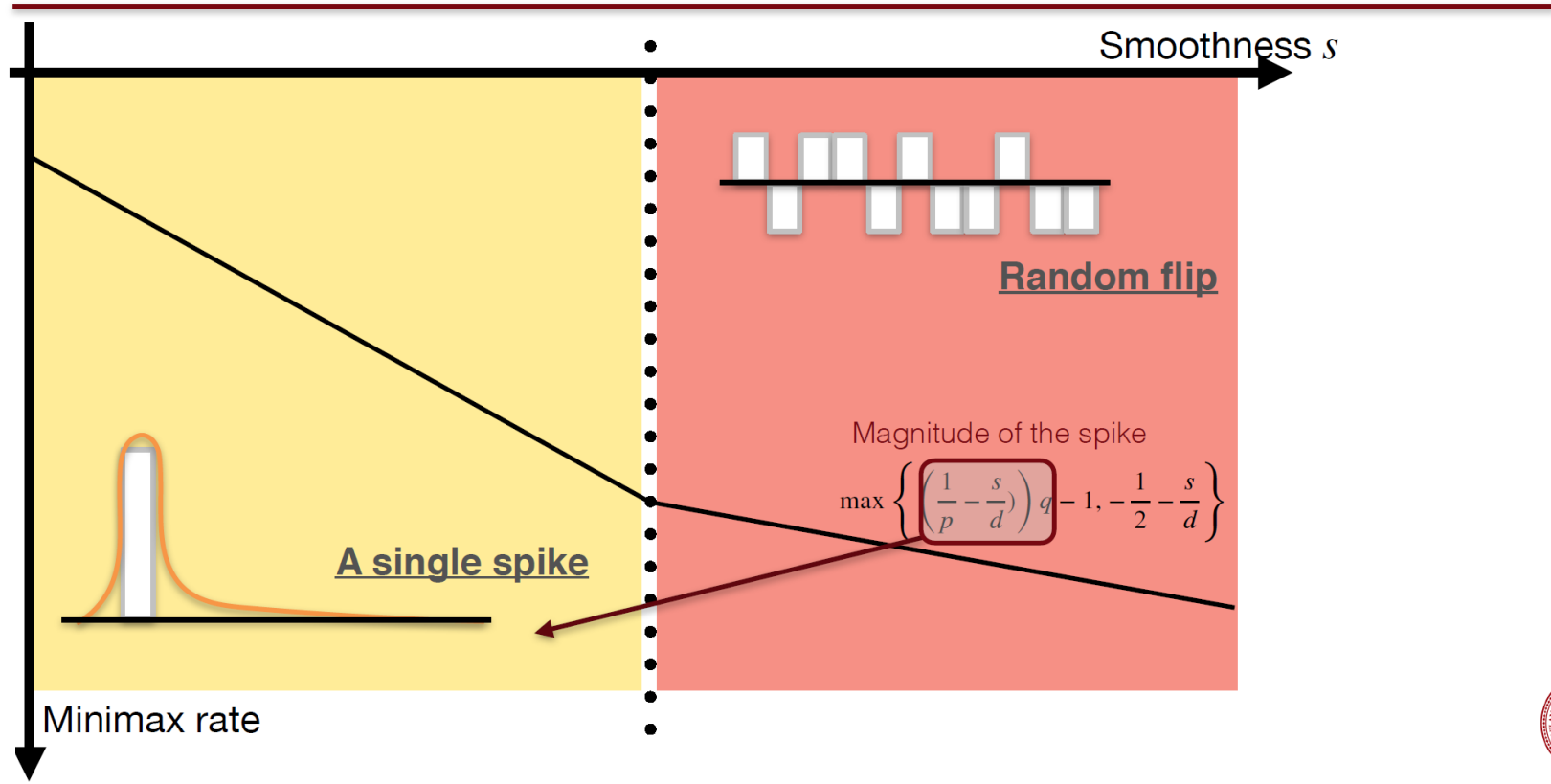


Sample without replacement

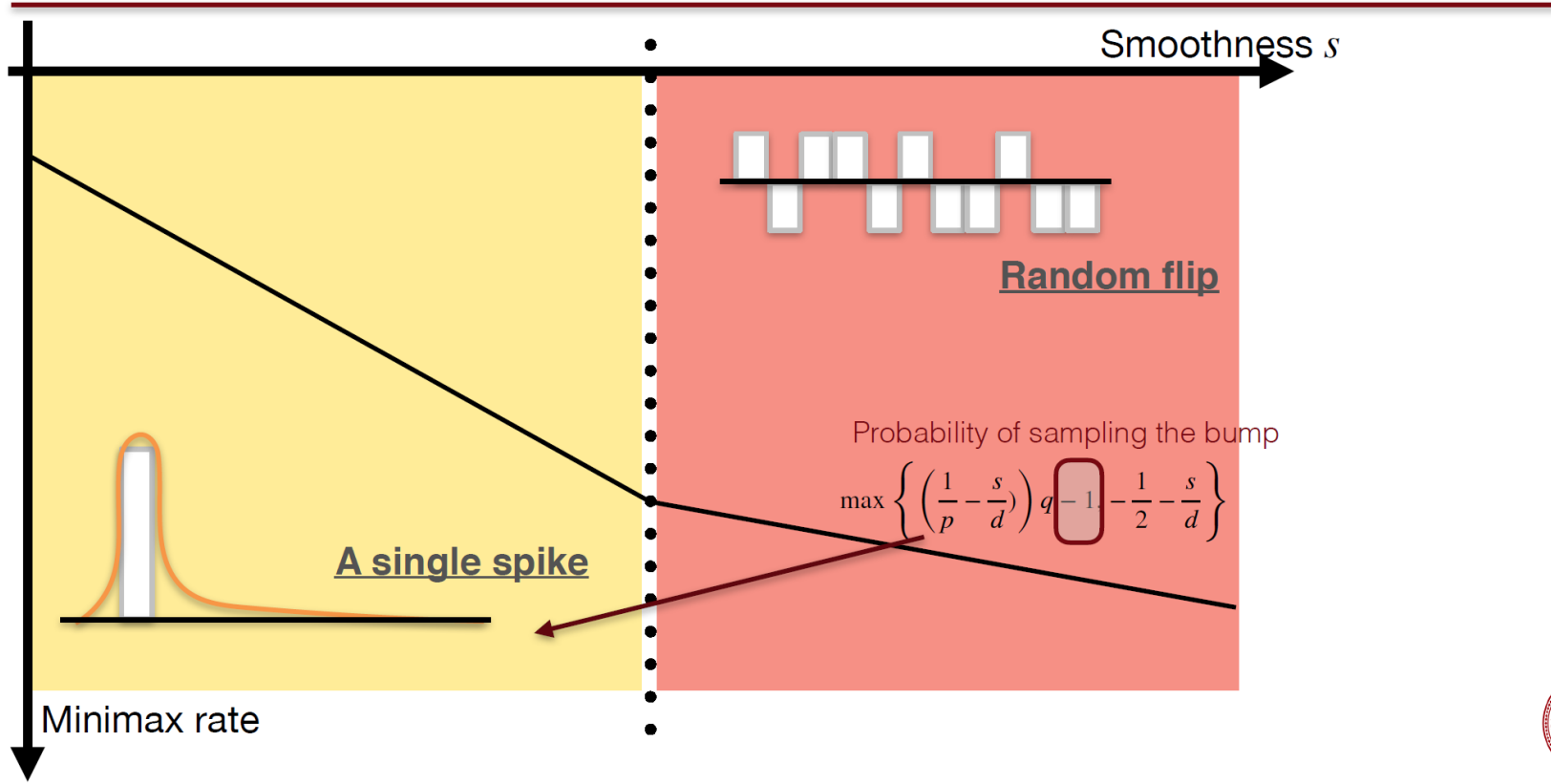
How many boxes have quadrature points?



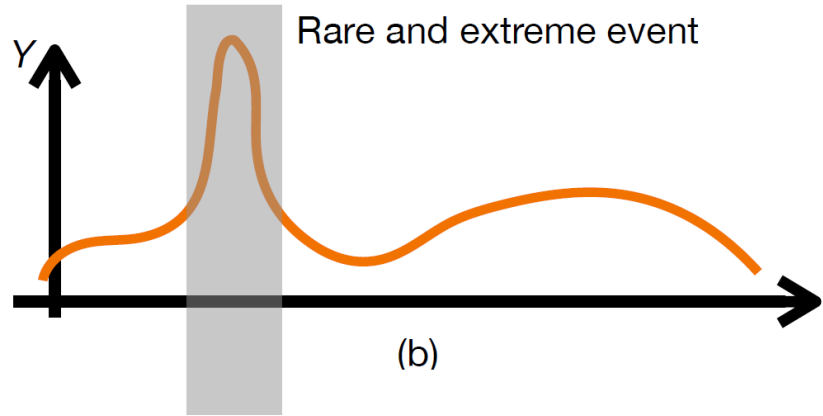
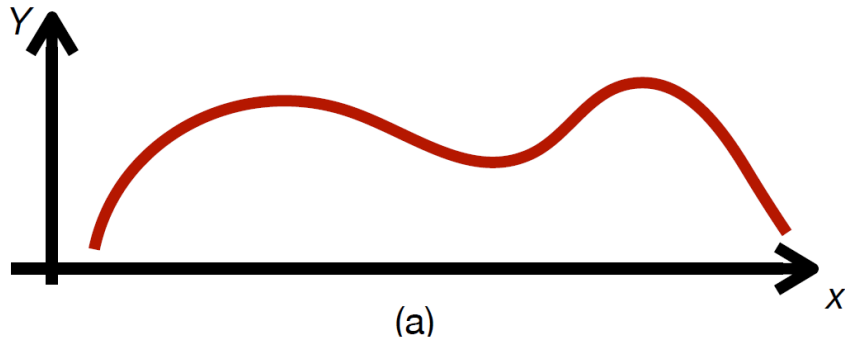
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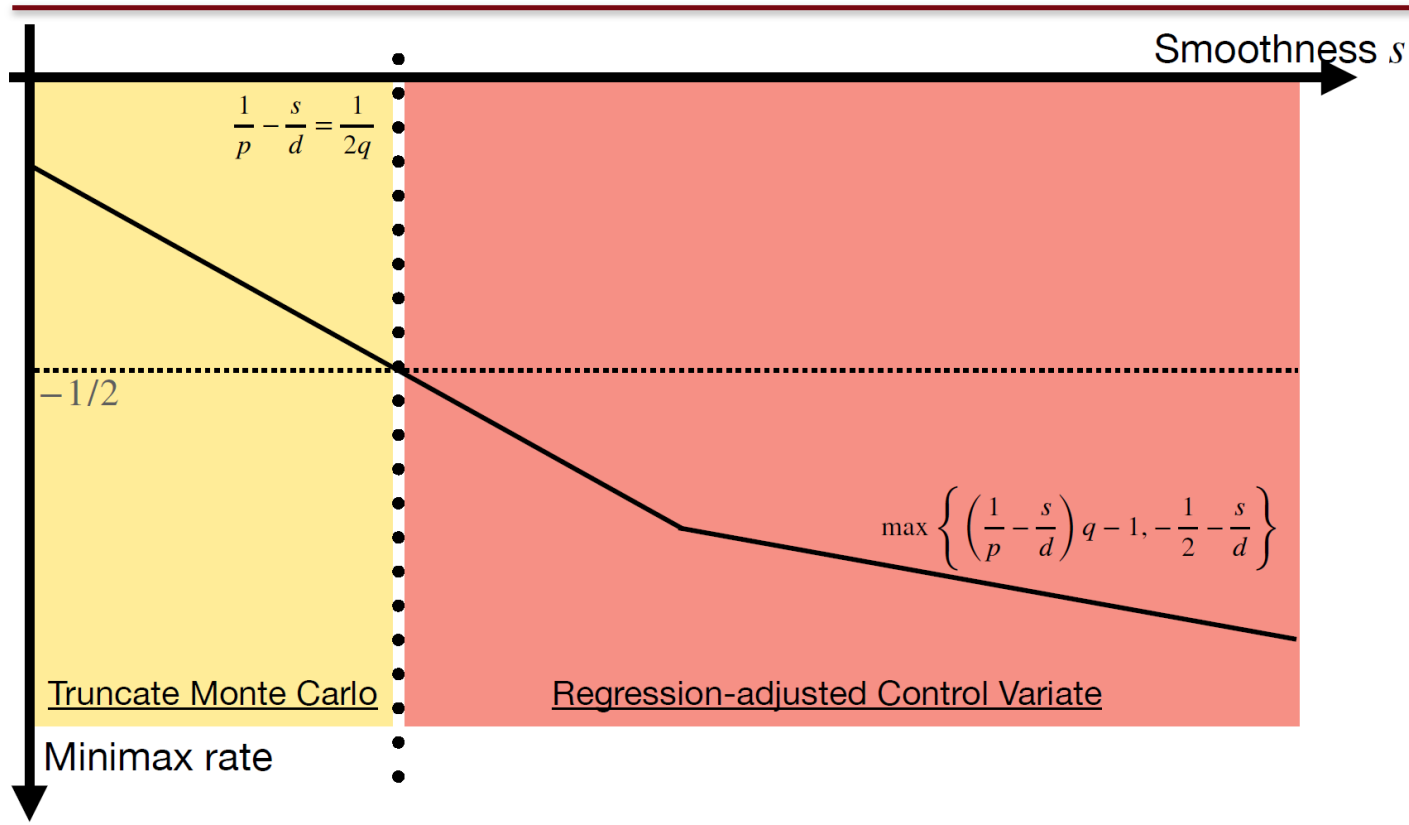
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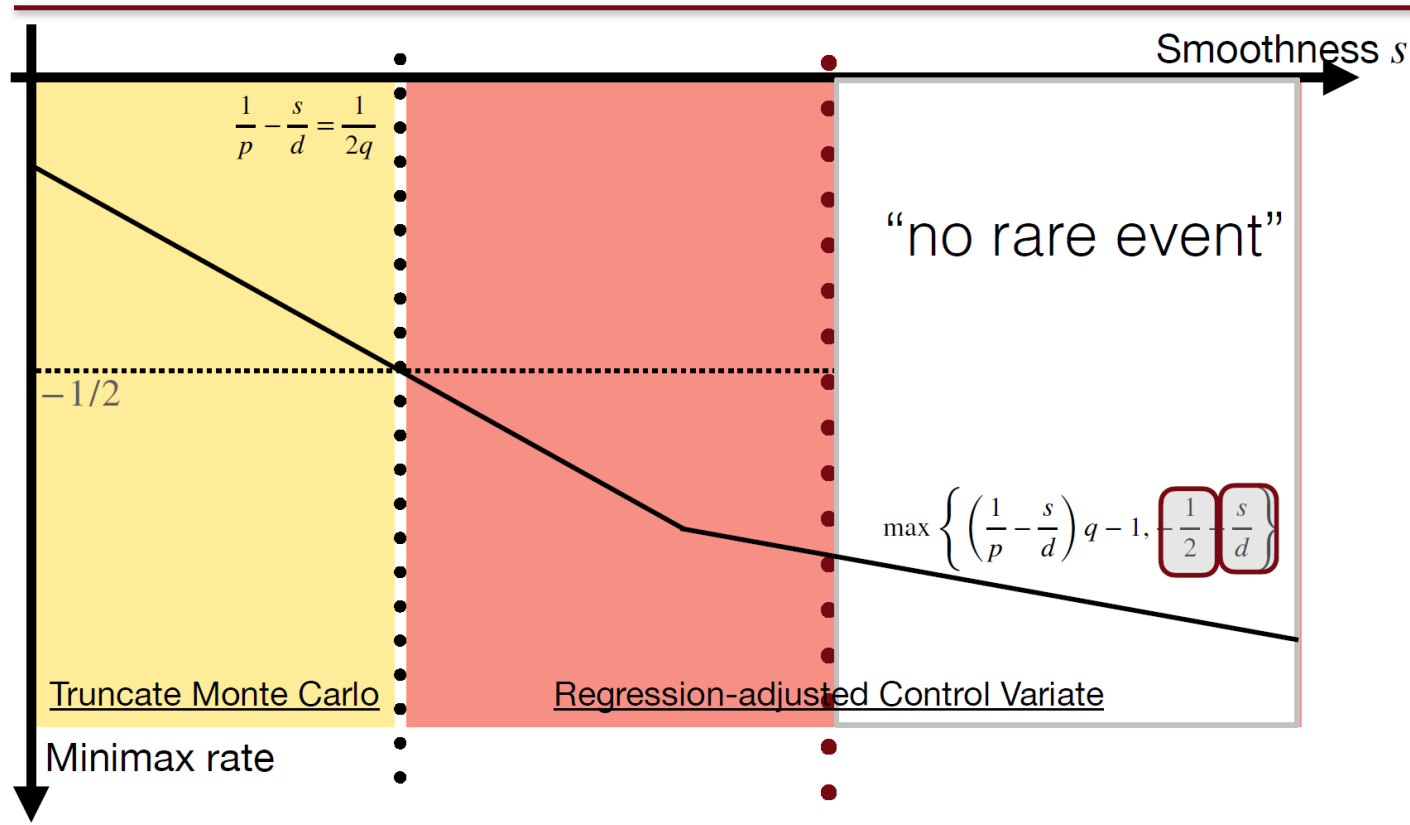
Rare Event and Smoothness...



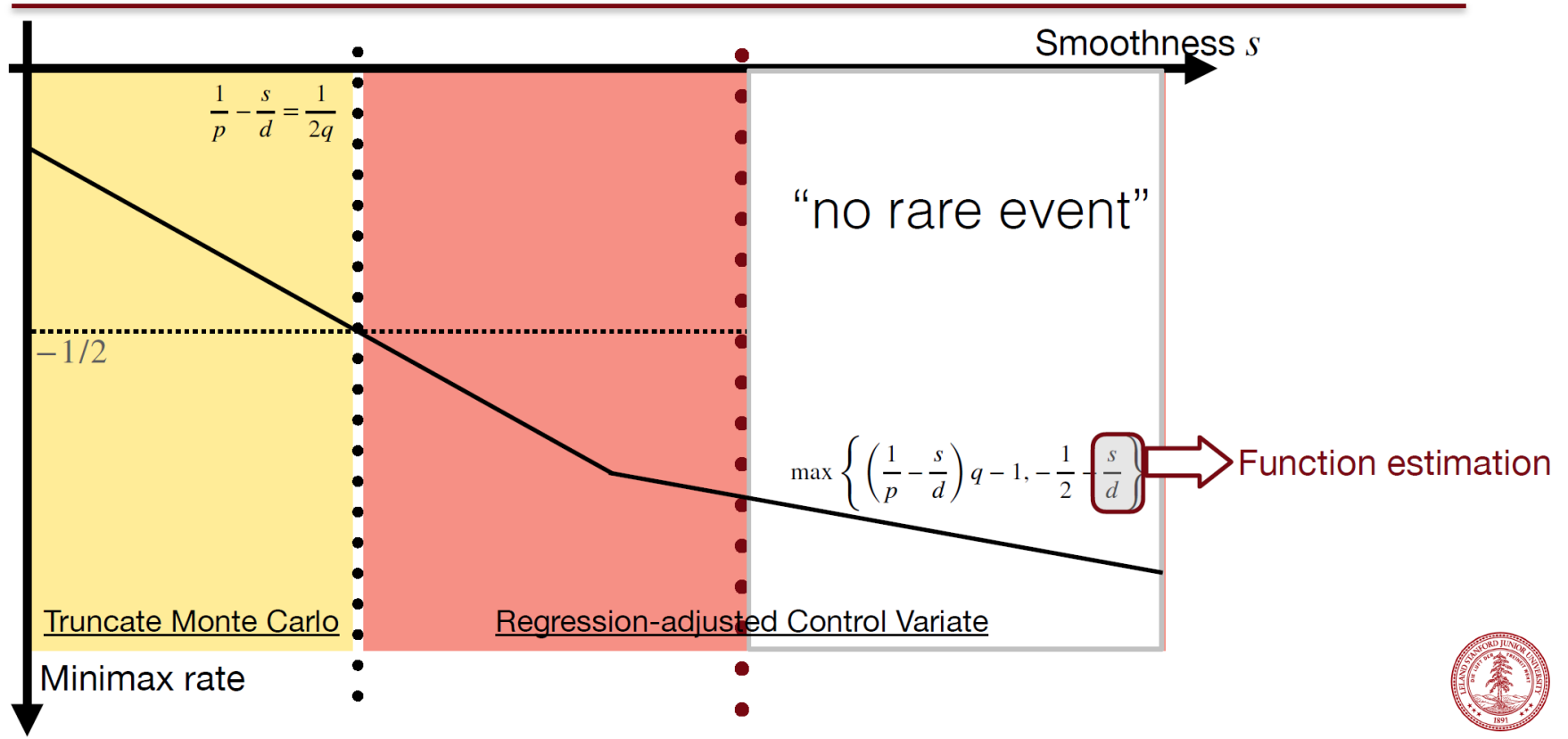
When the control variate helps



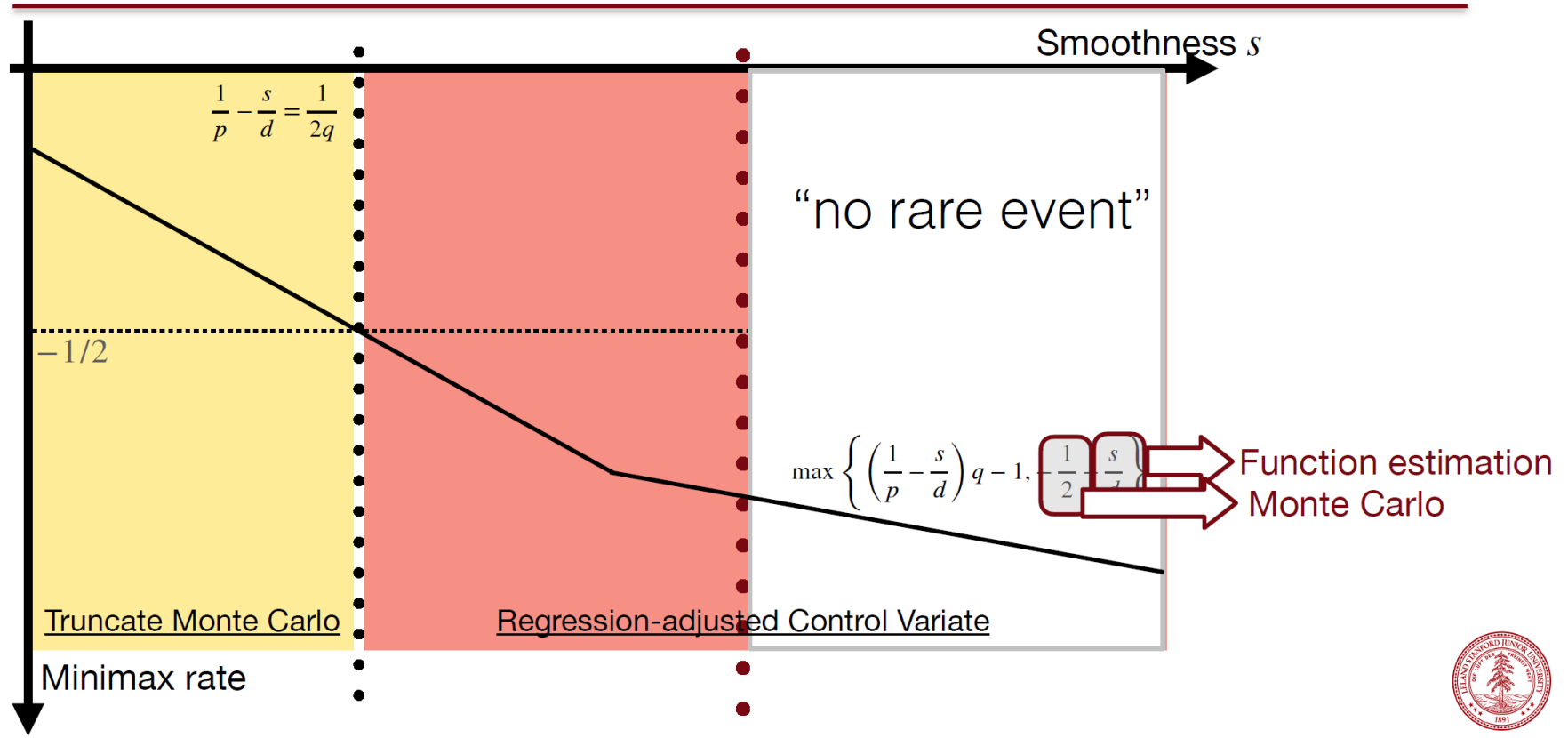
When the control variate helps



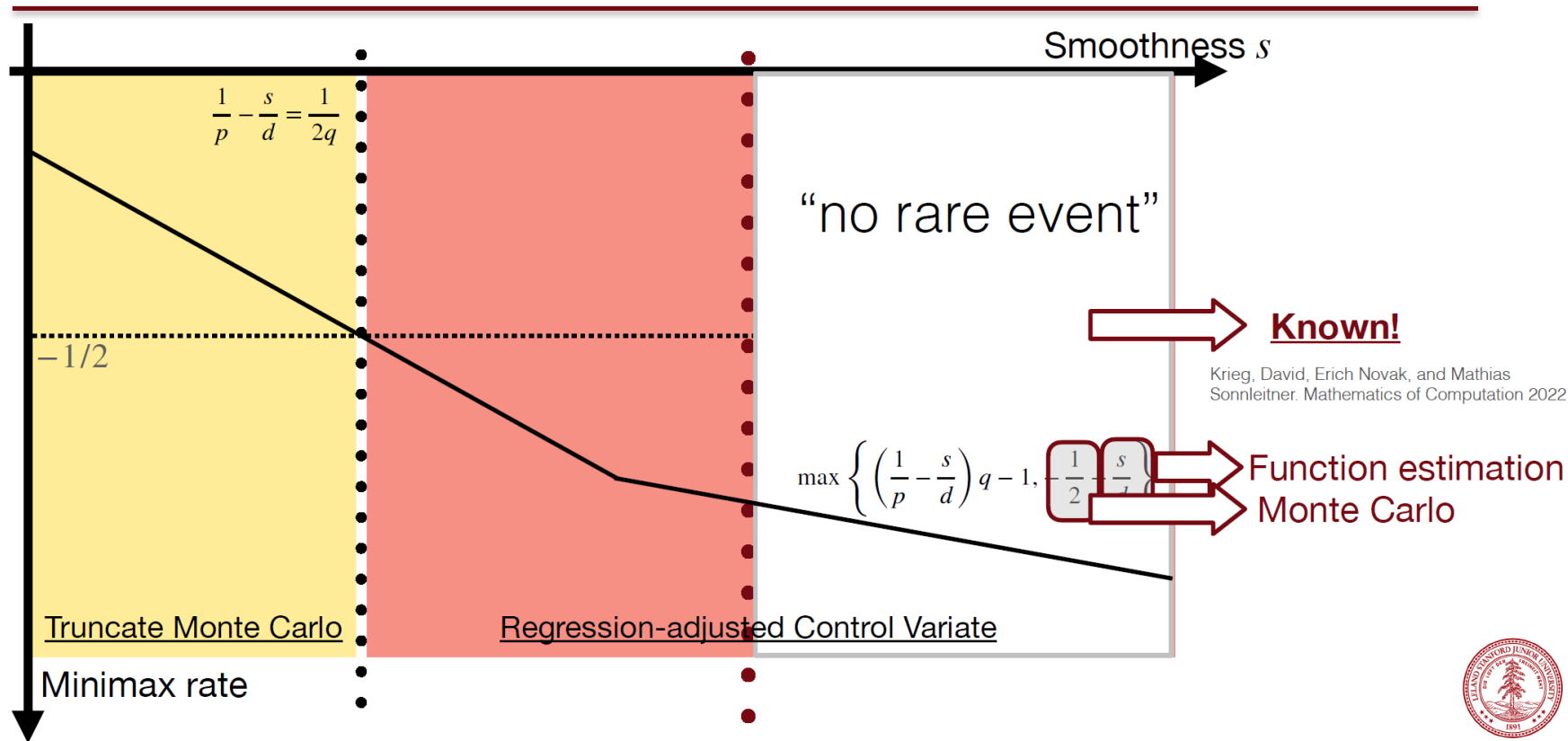
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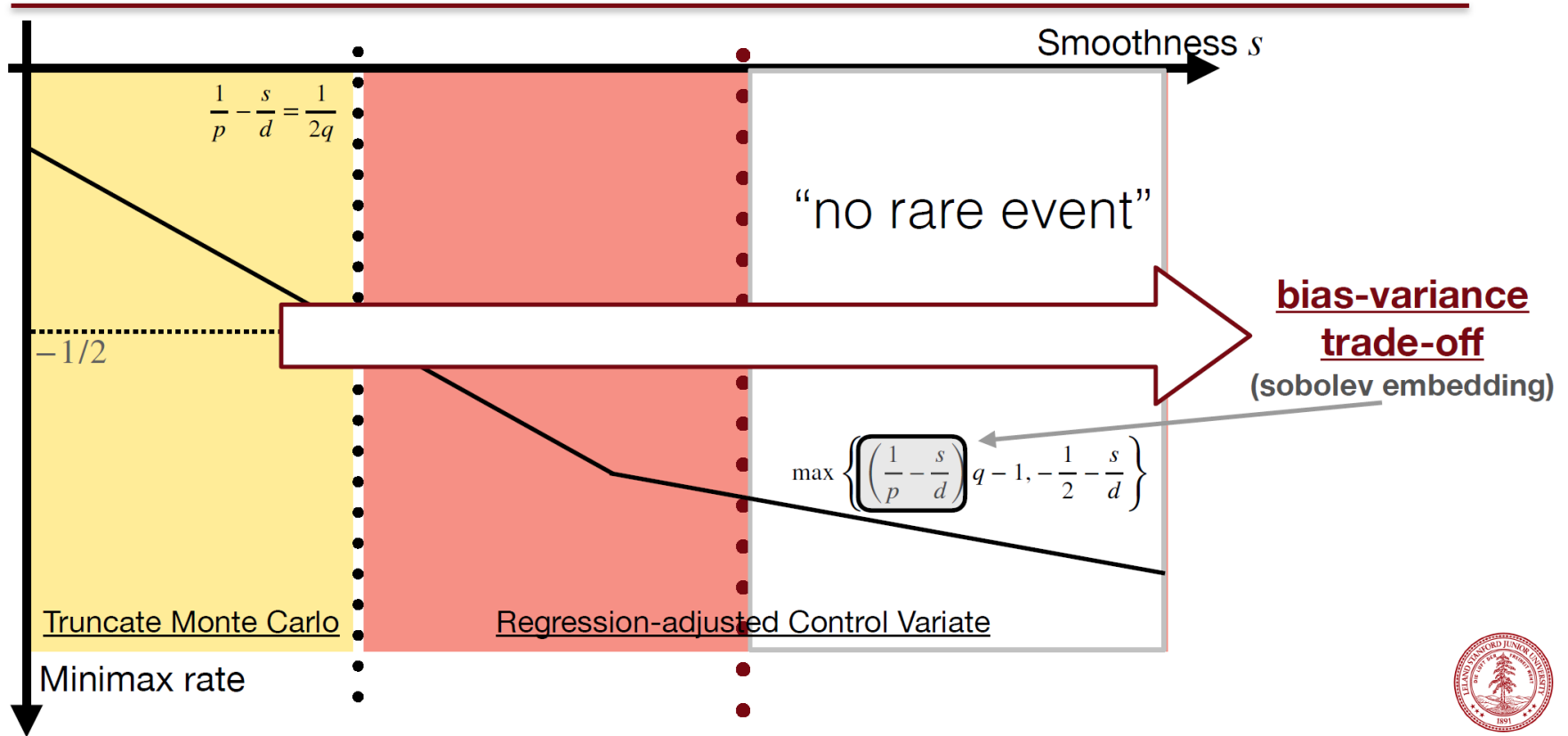
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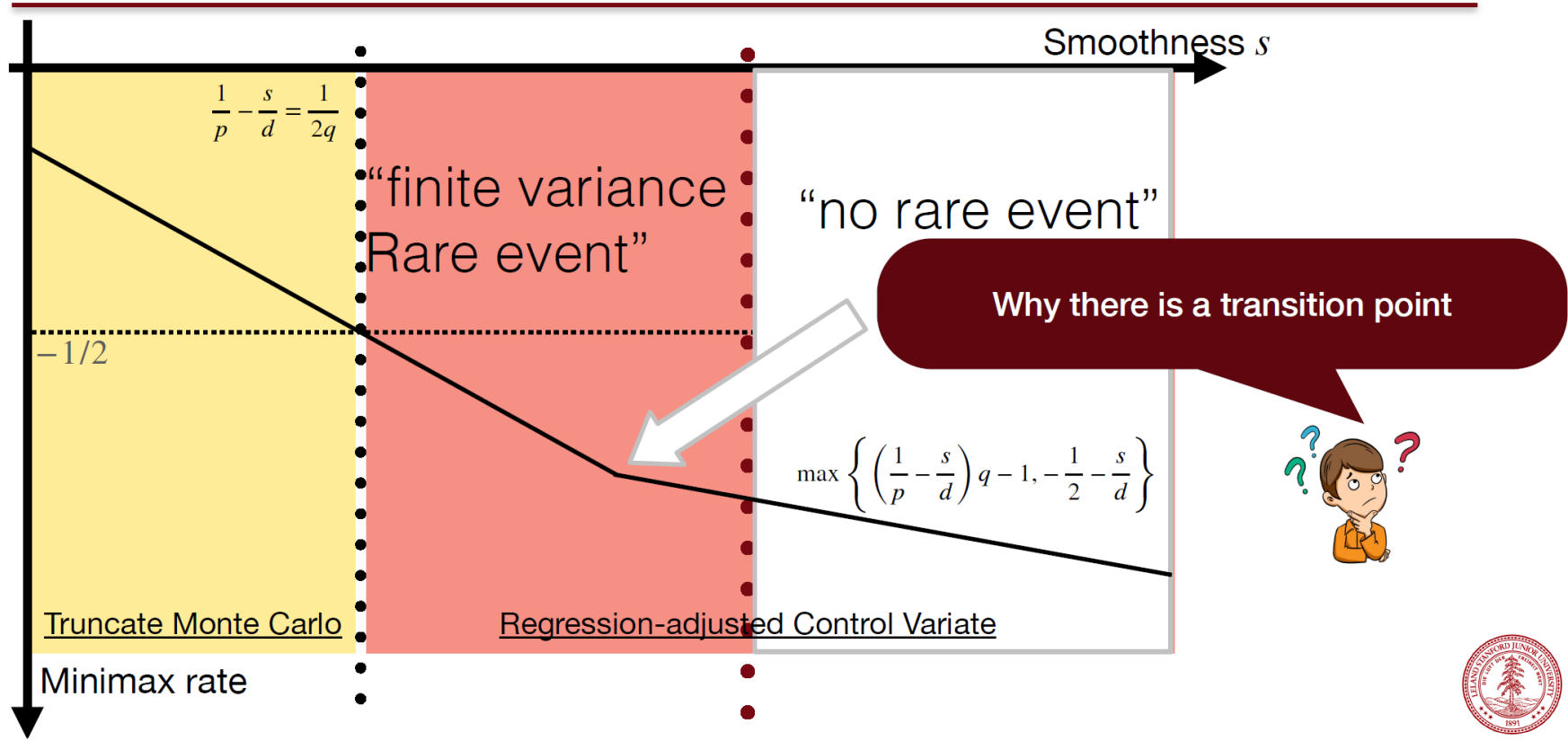
When the control variate helps



When the control variate helps



When the control variate helps



Sobolev Embedding Theorem (simplified version)

Fix $s, t \in \mathbb{N}_0$ and $p, q \in \mathbb{R}$ satisfying $s > t$, $p < d$ and $1 \leq p < q \leq \infty$, then we have:

(I) Inclusion between Sobolev spaces: $\frac{1}{p} - \frac{s}{d} = \frac{1}{q} - \frac{t}{d} \Rightarrow W^{s,p}(\mathbb{R}^d) \subseteq W^{t,q}(\mathbb{R}^d)$

(II) Special case when $t = 0$: $\frac{1}{p} - \frac{s}{d} \leq \frac{1}{q} \Rightarrow W^{s,p}(\mathbb{R}^d) \subseteq L^q(\mathbb{R}^d)$



Semi-parametric efficiency...

Example

Monte Carlo Estimate $\mathbb{E}_P f^q$, $f \in W^{s,p}$

Step 1

Using half of the data to estimate \hat{f}

Step 2

$$\mathbb{E}_P f^q = \mathbb{E}_P(\hat{f})^q + \mathbb{E}_P (f^q - \hat{f}^q)$$

Low order term

$$f^{q-1}(f - \hat{f}) + (f - \hat{f})^q$$

“influence function” (gradient) Error propagation



Semi-parametric efficiency...

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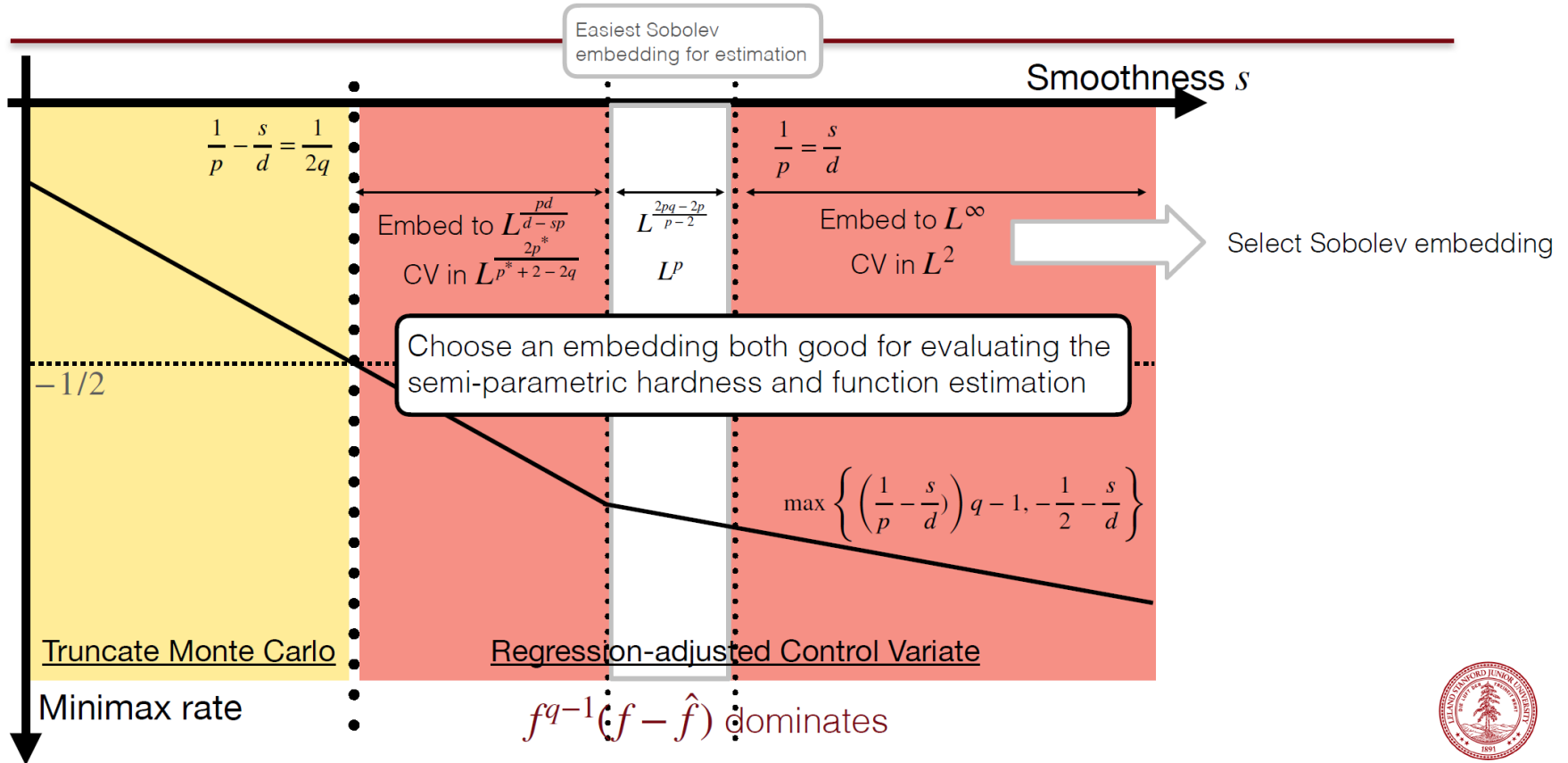
“influence function” (gradient)

Embed f^{q-1} and $f - \hat{f}$ into “dual” space

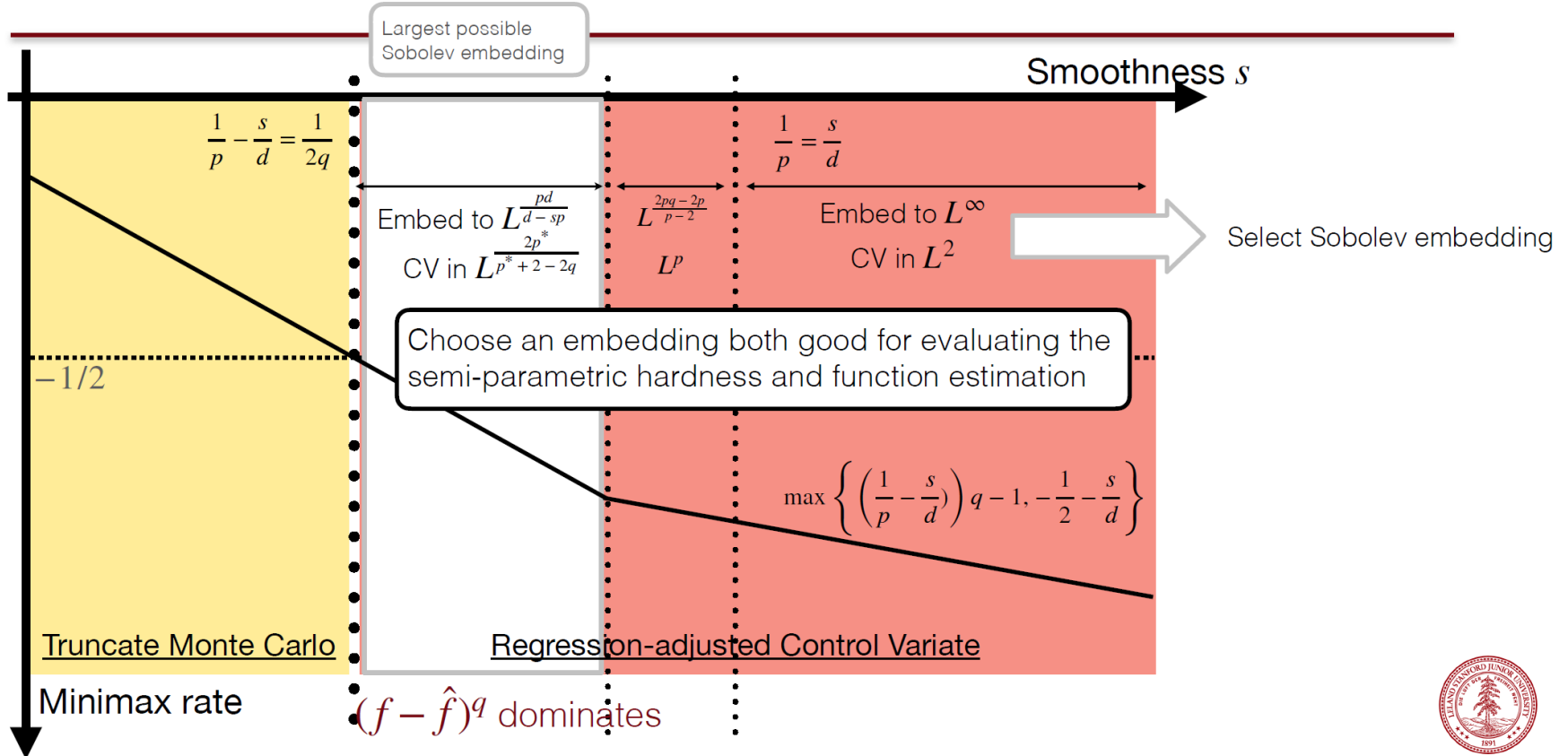
How to select the sobolev embedding



Tricky part of the Proof: select embedding

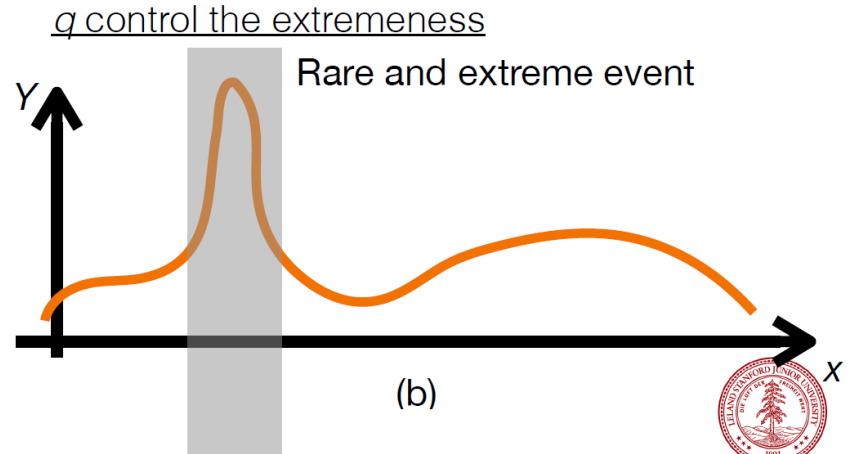
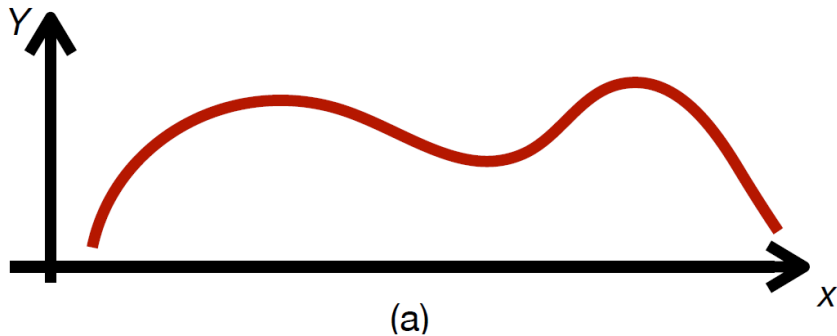


Tricky part of the Proof: select embedding



Take home message

- a) Statistical optimal regression is the optimal control variate
- b) It helps only if there isn't a hard to simulate (infinite variance)
Rare and extreme event



References

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- ▶ Angelopoulos, Anastasios N., et al. "Prediction-powered inference." *arXiv preprint arXiv:2301.09633* (2023).



Thank You all for Listening! Questions?

