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Enhancing Knowledge Transfer for Task Incremental Learning with Data-free Subnetwork

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Background



◆ Catastrophic Forgetting & Knowledge Transfer

- ✓ Neuron-wise mask
- ✓ Data-free memory replay

◆ Networks are usually over-parameterized

- ✓ Lottery Ticket Hypothesis
- ✓ Sub-networks



Related Work



◆ Continual learning

- Regularization-based approaches
- Rehearsal-based approaches
- Architecture-based approaches

◆ Knowledge Transfer

- Bayes model and regression methods
- Mask-based methods
- Few-shot replay methods



Motivations



- **Discover compact subnetworks for (task) incremental learning**
- Lottery Ticket Hypothesis: a randomly-initialized neural network contains a subnetwork such that, when trained in isolation, can match the performance of the original network.

- **Neuron-wise mask**

determines which neurons and their corresponding weights should be used for a new coming task

- **Data-free memory replay**

- measure the mask similarity scores
- craft the impressions of the most similar task via data-free memory replay



■ DSN : Enhancing Knowledge Transfer for Task

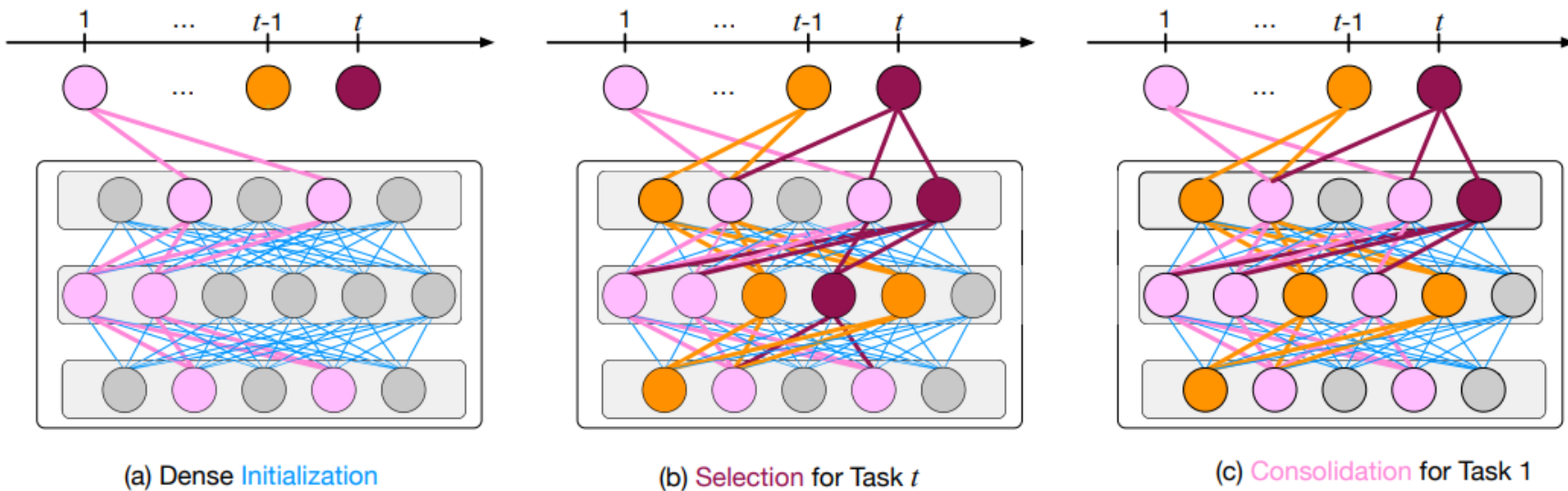
Incremental Learning with **Data-free Subnetwork**

Challenges

- **Catastrophic Forgetting**
- **Fail to obtain a subnetwork for each corresponding task**
- **Backward knowledge transfer is not considered**

Neuron-wise Mask:

- **Layer mask** $m_t^l \in m_t$: $m_t^l = \sigma(\gamma \cdot e_t^l)$,
- **Forward** : $h_t^l = h_t^l \odot m_t^l$,
- **Backward**: $\theta_{lij} = \theta_{lij} - \frac{\partial \mathcal{L}}{\partial \theta_{lij}} \odot \max(m_t^{l,i}, m_t^{l-1,j})$,



Data-free Replay:

Insights

- A class similarity matrix M_t describe the correlation between different classes.
- Model outputs representation sampled form Dirichlet distribution

```

for  $c = 1 : C_{\text{argmax}(S_t)}$  do
  Set the concentration parameter  $\alpha^c = M_{\text{argmax}(S_t)}^c$ ;
  for  $b = B_1, B_2, \dots, B_{C_{\text{argmax}(S_t)}}$  do
    for  $i = 1 : b$  do
      Sample  $\hat{o}_{\text{argmax}(S_t)}^c \sim \text{Dir}(C_{\text{argmax}(S_t)}, \beta_b \times \alpha^c)$ ;
      Initialize  $\hat{x}_{\text{argmax}(S_t)}^{c,i}$  to random noise and craft  $\hat{x}_{\text{argmax}(S_t)}^{c,i}$  via Eq.(9);
       $\mathcal{I}_{\text{argmax}(S_t)} \leftarrow \mathcal{I}_{\text{argmax}(S_t)} \cup \hat{x}_{\text{argmax}(S_t)}^{c,i}$ ;

```

$$\hat{x}_t^{c,i} = \operatorname{argmin} \mathcal{L}_{IC}(\mathcal{H}(\cdot, \theta(n \odot m_t), \tau), \hat{o}_t^c), \quad (9)$$

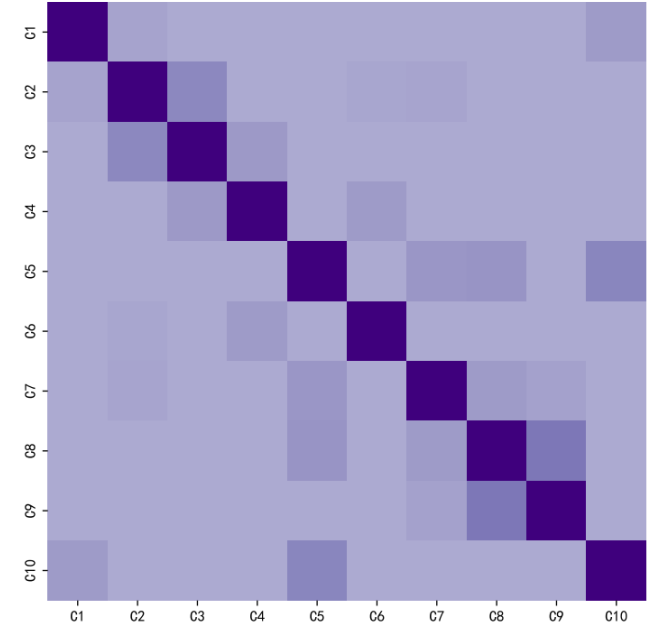


Figure 7: Confusion Matrix of the first task in TinyImageNet.

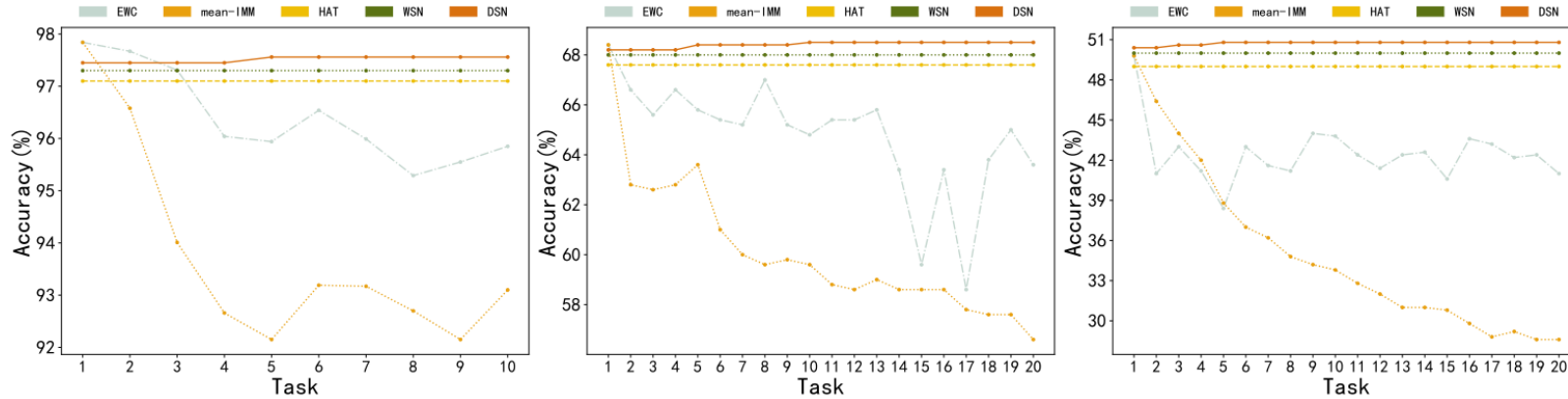
Overall Performance

Table 1: Performance comparison of the proposed method and baselines on four datasets.

Model	PMNIST			RMNIST			CIFAR-100			TinyImageNet		
	ACC(%)	BWT(%)	Trans(%)	ACC(%)	BWT(%)	Trans(%)	ACC(%)	BWT(%)	Trans(%)	ACC(%)	BWT(%)	Trans(%)
SGD	81.37	-24.52	-17.06	72.83	-25.32	-25.08	59.82	-24.09	-24.02	30.24	-19.12	-19.96
EWC	94.20	-0.32	-4.23	94.86	-0.73	-3.05	67.15	-8.61	-16.69	40.85	-5.24	-9.35
mean-IMM	80.10	-1.13	-18.33	88.81	-0.96	-9.10	56.08	0.23	-27.76	30.10	-3.21	-20.10
mode-IMM	93.13	-4.17	-5.30	89.48	-7.40	-8.43	61.22	-21.49	-22.62	32.26	-19.02	-17.94
PGN	91.89	0.00	-6.54	90.01	0.00	-7.90	53.84	-14.66	-30.00	24.47	-12.12	-25.73
DEN	91.96	-0.41	-6.47	91.53	-0.52	-6.38	59.32	-1.24	-12.79	33.86	-1.30	-3.88
RCL	92.28	0.00	-6.15	93.97	0.00	-3.94	61.77	0.00	-22.07	38.23	0.00	-11.79
HAT	97.10	0.00	-1.33	97.49	0.00	-0.42	71.23	0.00	-12.61	44.51	0.00	-5.69
SupSup	97.02	0.00	-1.41	97.15	0.00	-0.73	71.44	0.00	-12.40	43.22	0.00	-6.98
WSN	97.16	0.00	-1.27	97.32	0.00	-0.59	72.84	0.00	-11.00	45.96	0.00	-4.24
DSN	98.24	0.01	-0.19	97.73	0.02	-0.18	75.17	0.02	-8.67	46.56	0.04	-3.64

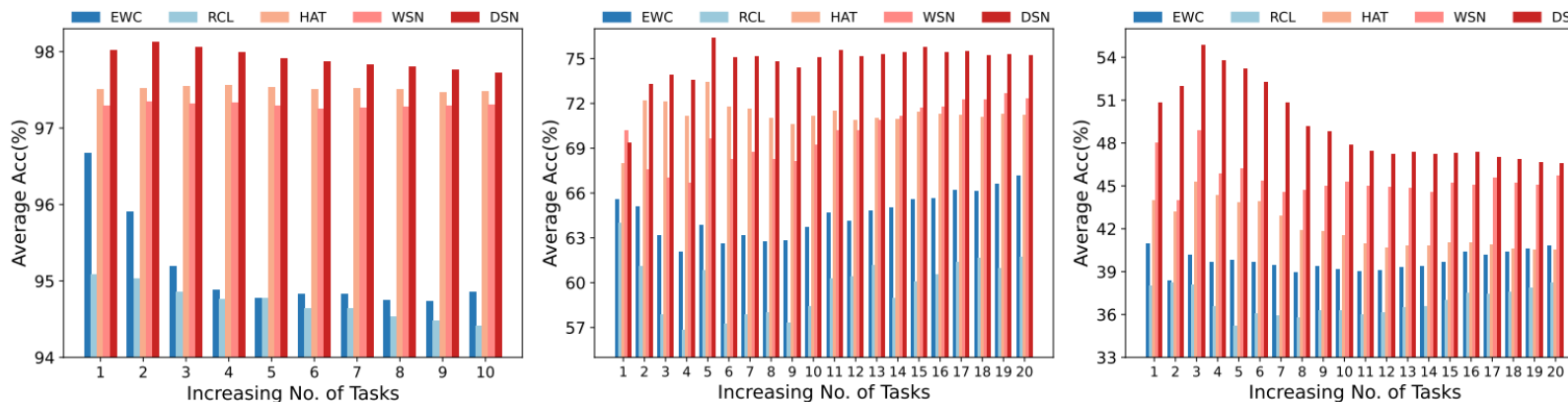
- DSN consistently outperforms all baselines regarding *ACC*, *BWT*, and *Trans(%)*
- DSN is the first to exceed 0 regarding *BWT*

The accuracy performance of the first task in incremental learning



- When new tasks arrive, DSN is the only one to perform better on the first task

The accuracy performance during entire incremental learning



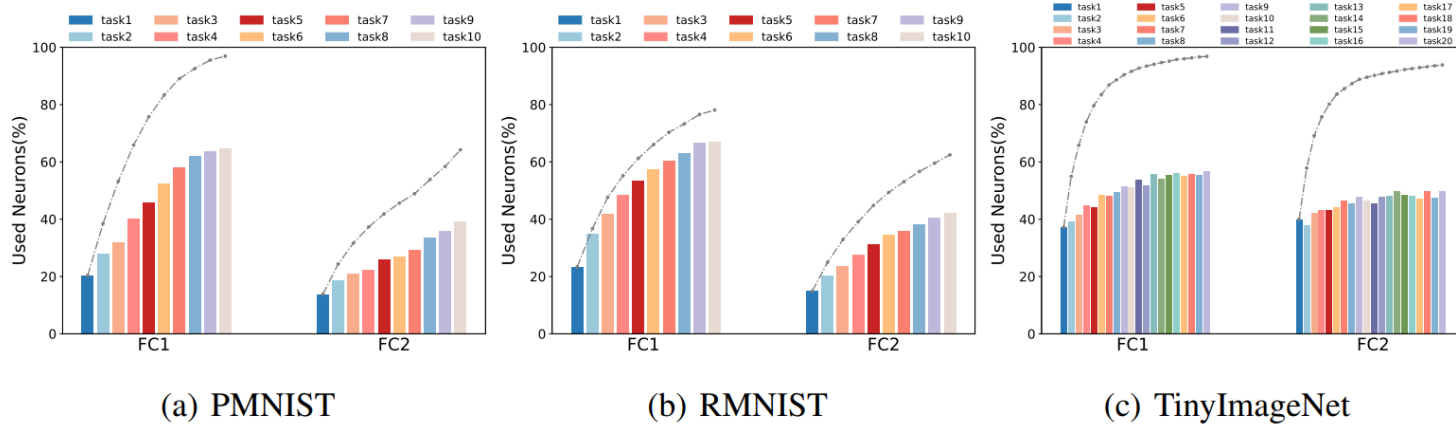
(a) RMNIST

(b) CIFAR100

(c) TinyImageNet

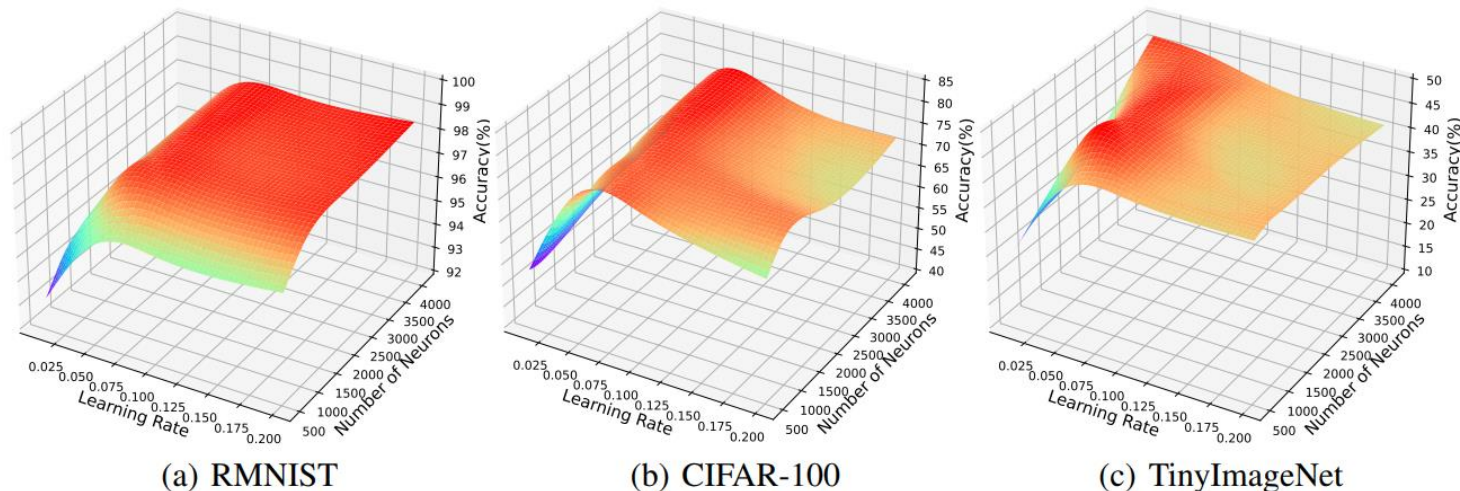
- DSN outperforms other baselines during the entire incremental learning process

■ The layer-wise neuron usage in incremental learning



- **DSN prefers to reuse more neurons from earlier tasks when a new task arrives**

■ Hypernetwork capacity in incremental learning varying different learning rates





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Thank you!

Q&A

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