

PlasticityNet

Learning to Simulate Metal, Sand, and Snow
for Optimization Time Integration

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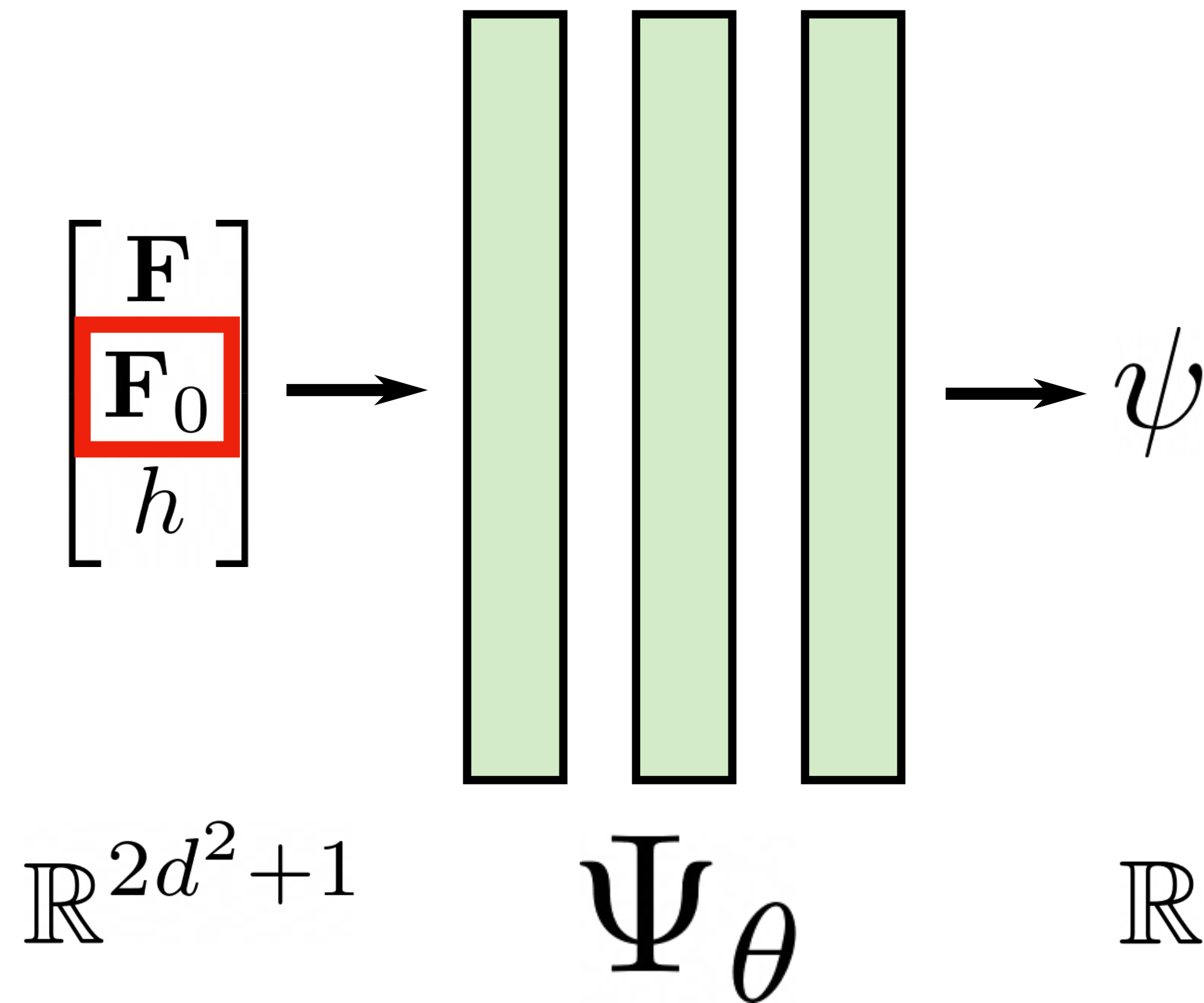


- Overview
- Technical Details
- Experiment Results

Motivation

- Optimization time integrator is stable but requires $f^{\text{int}} = -\frac{\partial \Psi}{\partial x}$.
- Implicit plasticity leads to $\frac{\partial f_i}{\partial x_j} \neq \frac{\partial f_j}{\partial x_i}$ in general.
- Goal: use optimization time integrators to simulate general plasticities with **large time steps**.

PlasticityNet

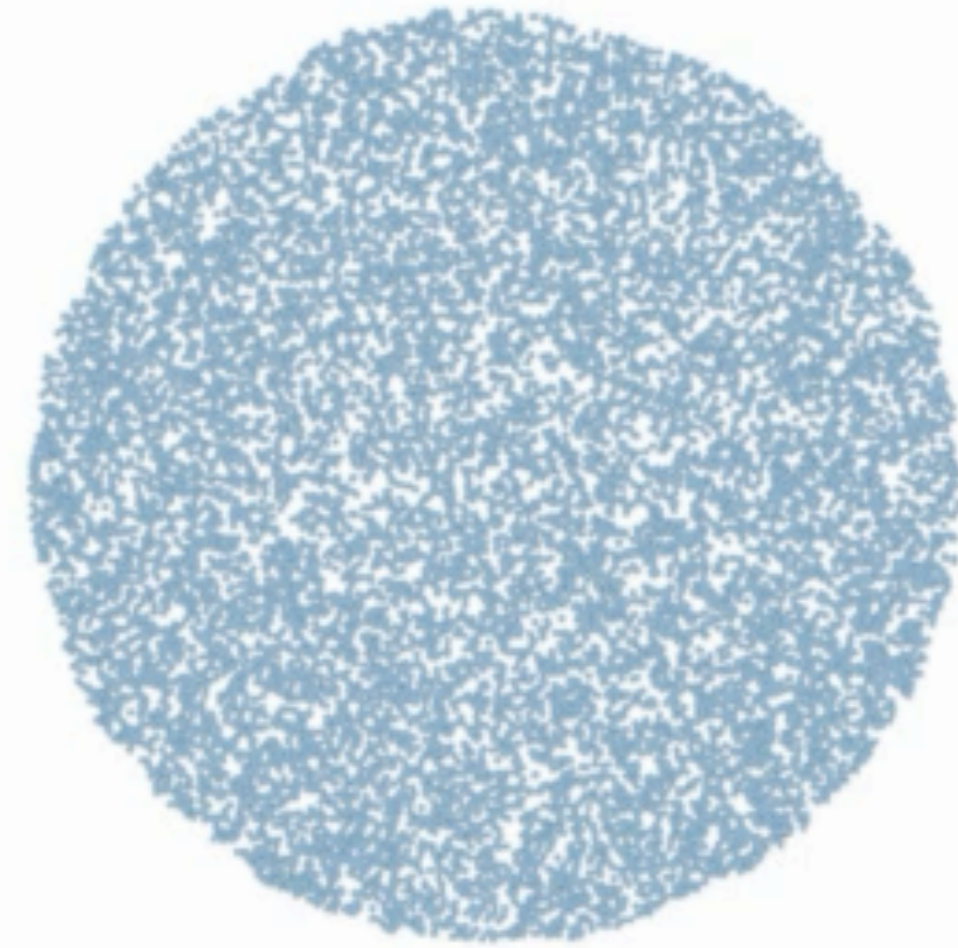


- Learning an **energy** for plastic forces.
- Compatible with **optimization time integrators**.

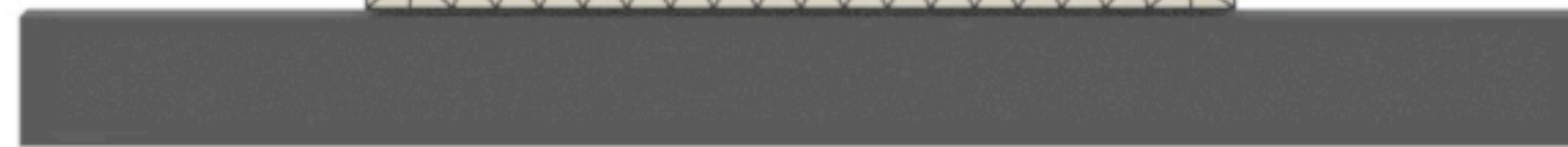
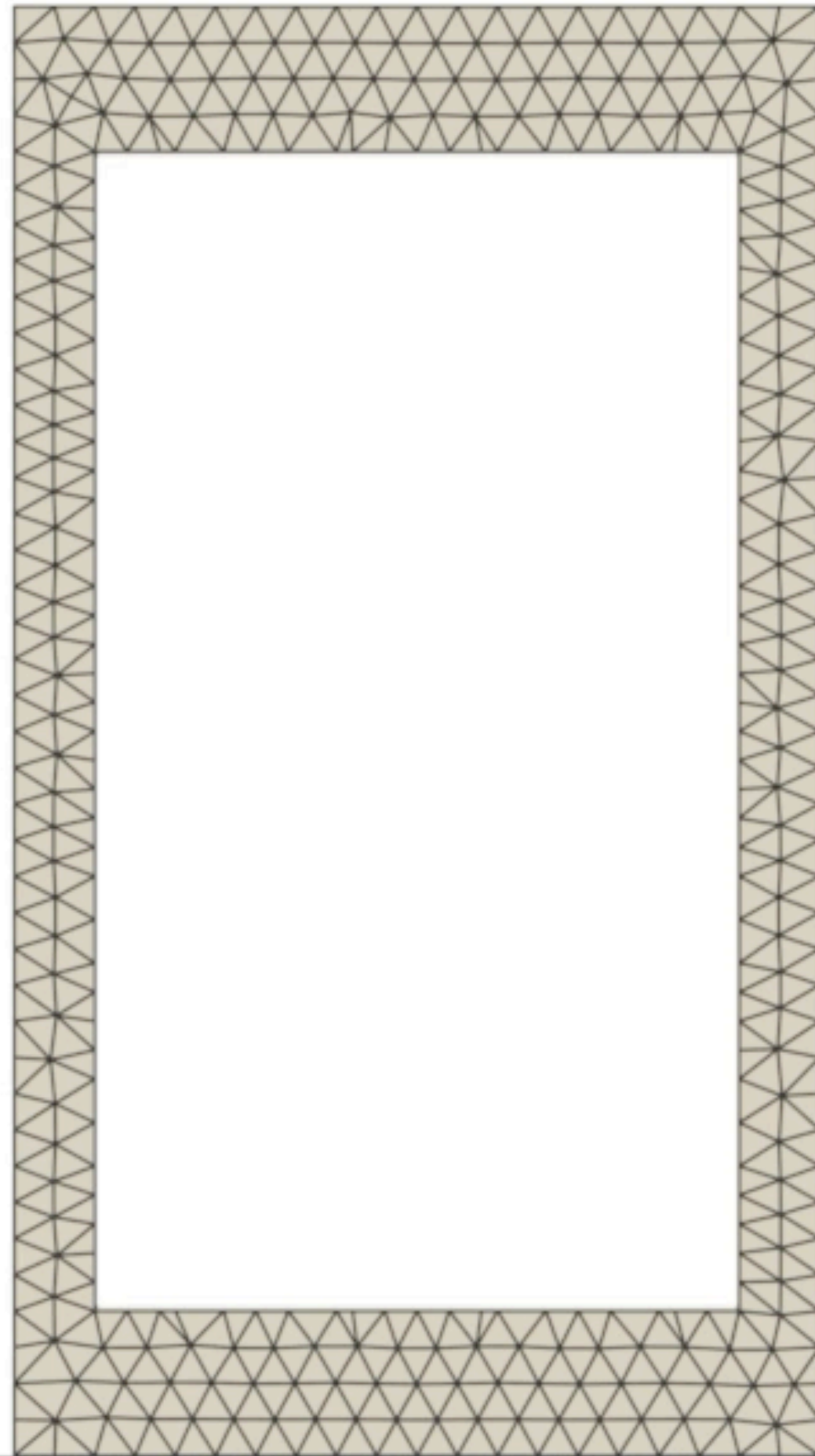
Sand



Snow



Metal





- Overview
- **Technical Details**
- Experiment Results

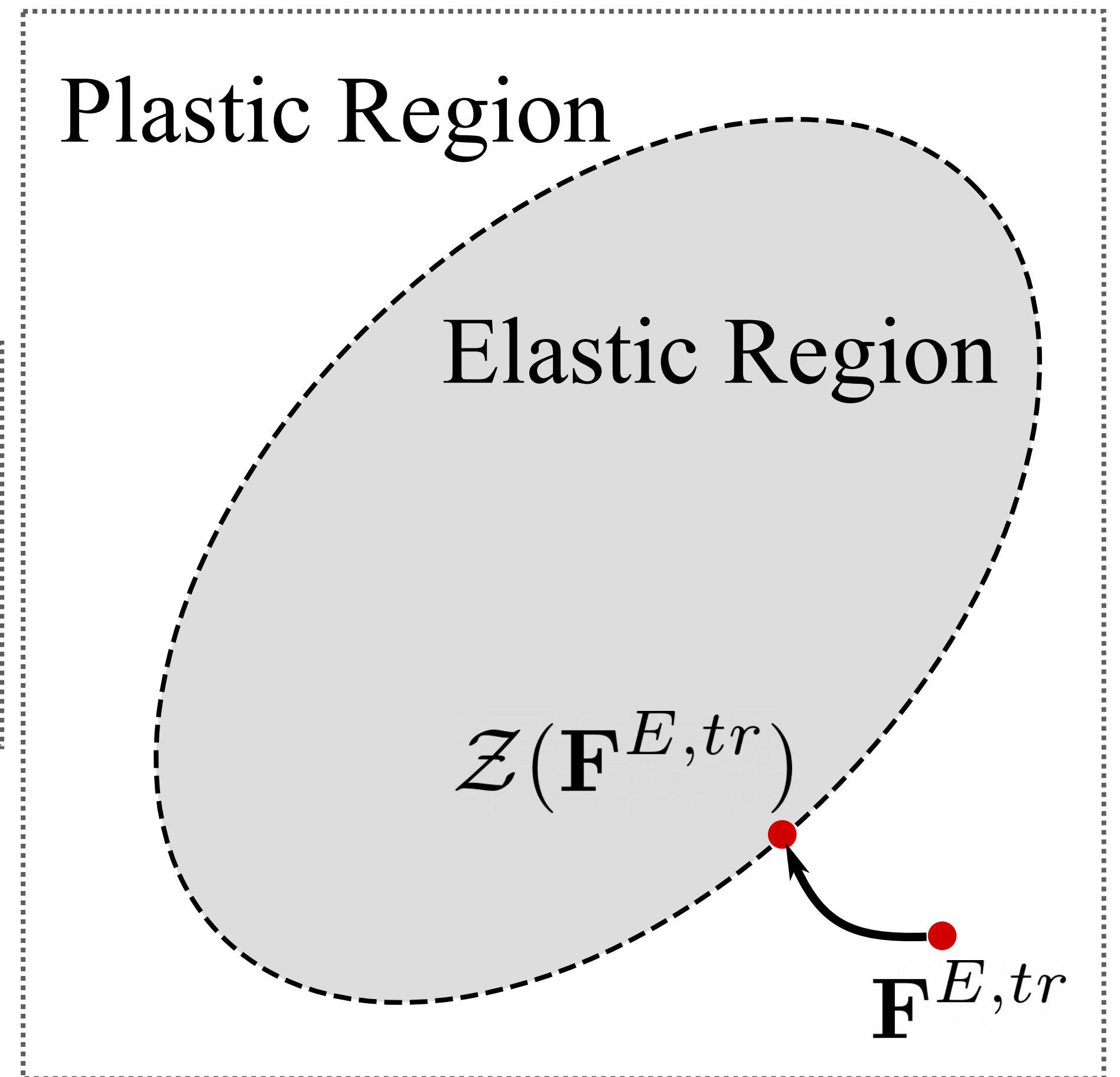
Implicit Time Integration

Return mapping for **plasticity**

Momentum conservation

$$\mathbf{M}(\mathbf{v}^{n+1} - (\mathbf{v}^n + \mathbf{g}\Delta t)) = \Delta t \mathbf{f}^{n+1}$$
$$\mathbf{f}_i^{n+1} = - \sum_q V_q^0 \tau(\mathcal{Z}(\mathbf{F}_q^{E,tr})) \mathbf{F}_q^{E,tr} \mathbf{F}^{P,n} \nabla w_{iq}$$

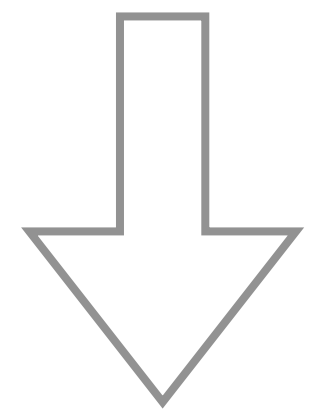
Plasticity
Elasticity



Optimization Time Integrator

Integrability Condition (Li et al. 2022)

$$\frac{\partial \Psi}{\partial \mathbf{F}} = \boldsymbol{\tau}(\mathcal{Z}(\mathbf{F}))\mathbf{F}^{-\top}$$



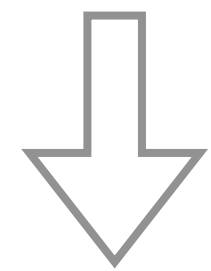
$$\mathbf{v}^{n+1} = \operatorname{argmin}_{\mathbf{v}} \frac{1}{2} \|\mathbf{v} - (\mathbf{v}^n + \mathbf{g}\Delta t)\|_{\mathbf{M}}^2 + \sum_q V_q^0 \Psi(\mathbf{F}_q)$$

Without Plasticity ($\mathcal{Z} = \text{id}$): 

With Plasticity: 

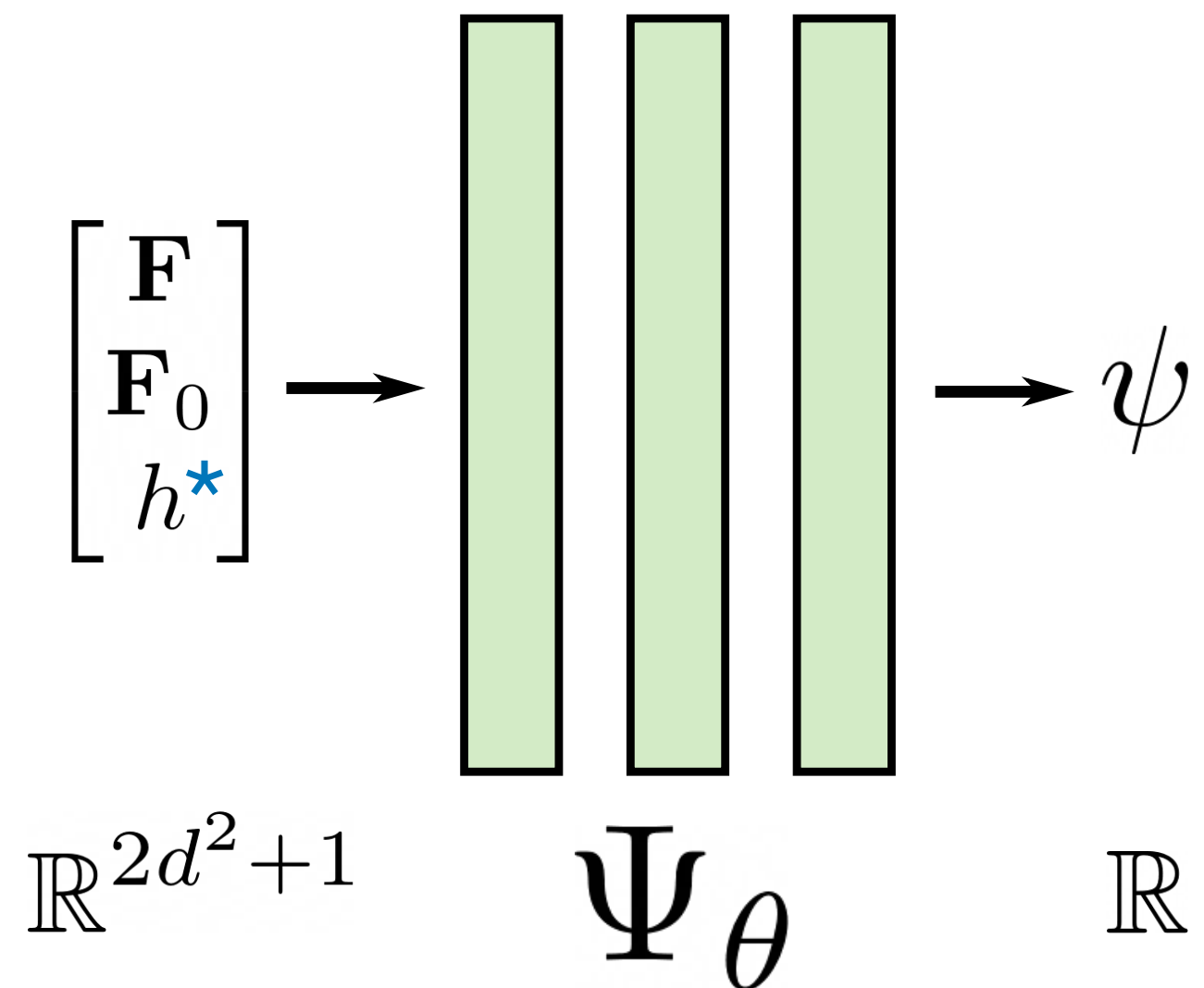
PlasticityNet

$$\frac{\partial \Psi}{\partial \mathbf{F}} = \boldsymbol{\tau}(\mathcal{Z}(\mathbf{F}))\mathbf{F}^{-\top}$$



Relaxation

$$\left\{ \begin{array}{l} \frac{\partial \Psi_{\theta}}{\partial \mathbf{F}}(\mathbf{F}, \mathbf{F}_0) |_{\mathbf{F}=\mathbf{F}_0} = \boldsymbol{\tau}(\mathcal{Z}(\mathbf{F}_0))\mathbf{F}_0^{-\top} \\ \frac{\partial \Psi_{\theta}}{\partial \mathbf{F}}(\mathbf{F}, \mathbf{F}_0) \approx \boldsymbol{\tau}(\mathcal{Z}(\mathbf{F}))\mathbf{F}^{-\top} \end{array} \right.$$



* Please see the description of the hardening state in the paper.

$$\Psi_{\theta}(\mathbf{F}, \mathbf{F}_0) = \mathcal{N}\mathcal{N}_{\theta}(\mathbf{F}, \mathbf{F}_0) - (\nabla_{\mathbf{F}}\mathcal{N}\mathcal{N}_{\theta}(\mathbf{F}_0, \mathbf{F}_0) - \boldsymbol{\tau}(\mathcal{Z}(\mathbf{F}_0))\mathbf{F}_0^{-\top}) \odot \mathbf{F}$$

→ **Training:** $\mathcal{L}(\theta) = \mathbb{E}_{\mathbf{F}_0}\mathbb{E}_{\mathbf{F}} \left\| \frac{\partial \Psi_{\theta}}{\partial \mathbf{F}}(\mathbf{F}, \mathbf{F}_0) - \boldsymbol{\tau}(\mathcal{Z}(\mathbf{F}))\mathbf{F}^{-\top} \right\|_F^2$

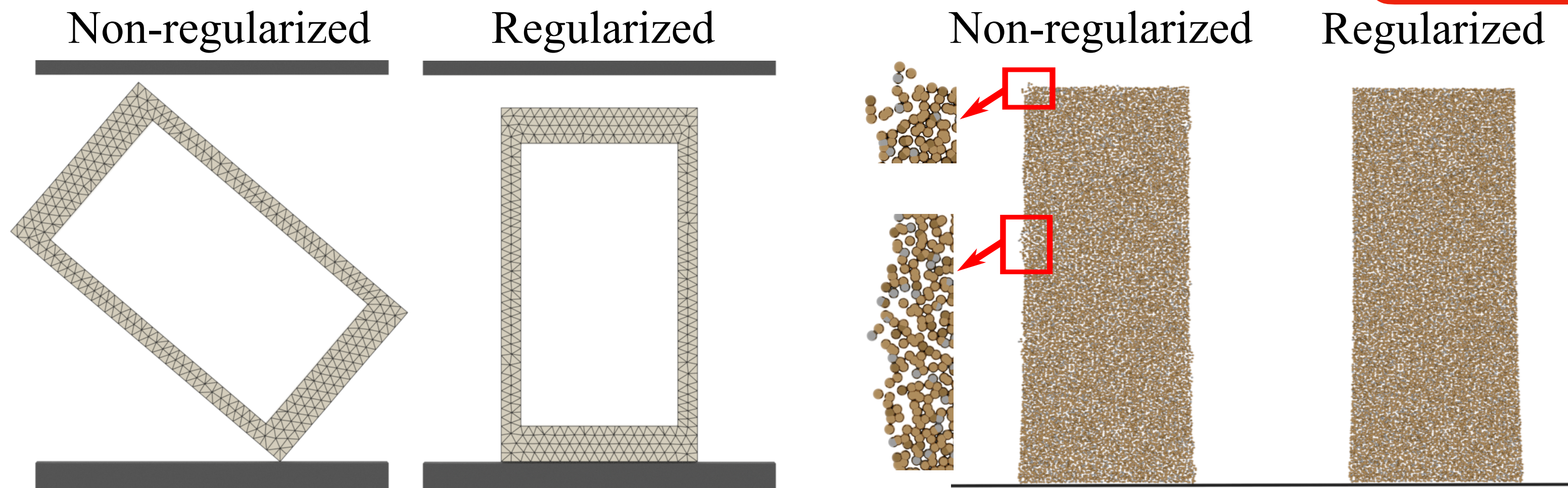
Optimization Time Integration with PlasticityNet

Fixed-point Iteration

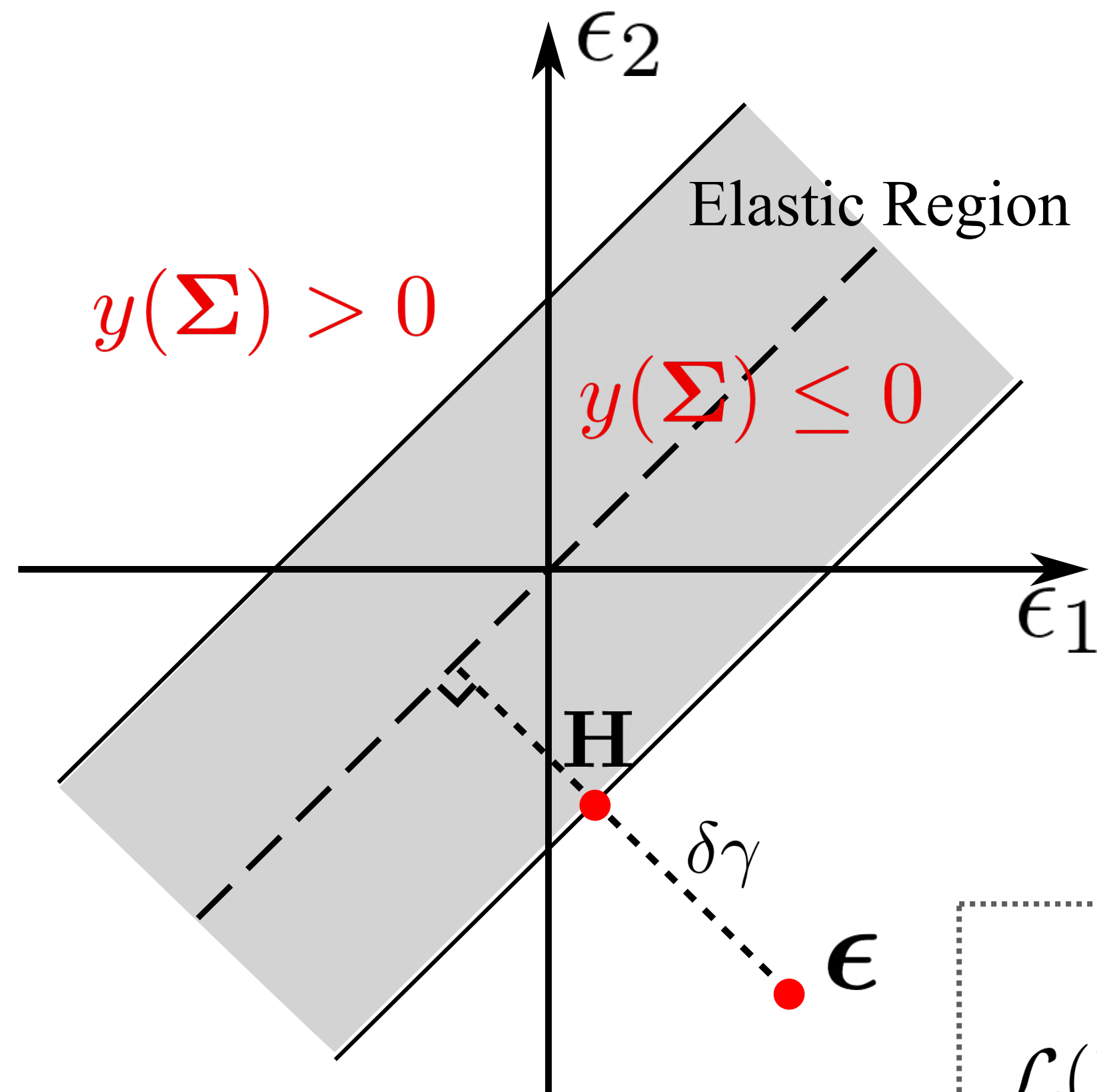
$$\mathbf{v}^{n+1,j+1} = \operatorname{argmin}_{\mathbf{v}} \frac{1}{2} \|\mathbf{v} - (\mathbf{v}^n + \mathbf{g}\Delta t)\|_{\mathbf{M}} + \sum_q V_q^0 \Psi_{\theta}(\mathbf{F}_q, \mathbf{F}_{0,q}^j), \quad \text{for } j = 0, 1, 2, \dots,$$
$$\mathbf{F}_0^j = \mathbf{F}(\mathbf{v}^{n+1,j})$$

Stability Regularizer

$$\Psi_{\theta}(\mathbf{F}, \mathbf{F}_0) = \mathcal{N}\mathcal{N}_{\theta}(\mathbf{F}, \mathbf{F}_0) - (\nabla_{\mathbf{F}}\mathcal{N}\mathcal{N}_{\theta}(\mathbf{F}_0, \mathbf{F}_0) - \tau(\mathcal{Z}(\mathbf{F}_0))\mathbf{F}_0^{-\top}) \odot \mathbf{F} + \frac{1}{2}\mu\|\mathbf{F} - \mathbf{F}_0\|_F^2$$



Learning Return Mapping



Neural Return Mapping:

$$\delta\gamma_\theta(\Sigma) = \min\{\mathcal{NN}_\theta(\Sigma), \|\hat{\epsilon}\|\}$$

$$\mathcal{Z}_\theta^\Sigma(\Sigma) = \begin{cases} \exp(\epsilon - \delta\gamma_\theta \frac{\hat{\epsilon}}{\|\hat{\epsilon}\|}), & y(\Sigma) > 0, \\ \Sigma, & y(\Sigma) \leq 0 \end{cases}$$

$$\mathcal{L}(\Sigma; \theta) = \begin{cases} y(\mathcal{Z}_\theta^\Sigma(\Sigma))^2 + \max\{\delta\gamma_\theta(\Sigma) - \|\hat{\epsilon}\|, 0\}, & y(\Sigma) > 0 \\ 0, & y(\Sigma) \leq 0 \end{cases}$$



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2D Sand

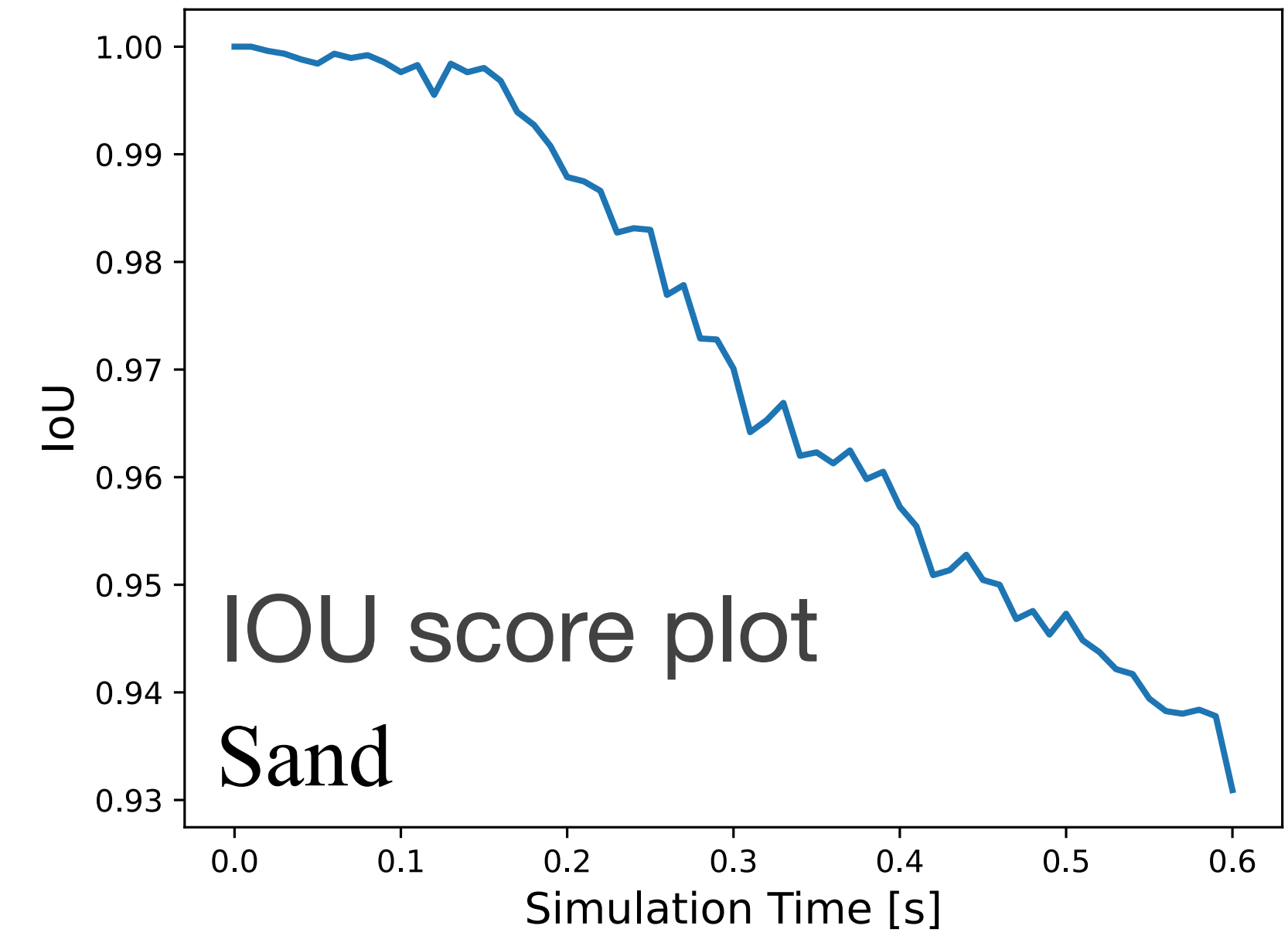
Ground Truth
dt = 1e-5



Ours
dt = 1e-5



StVK Elasticity + Drucker-Prager Plasticity



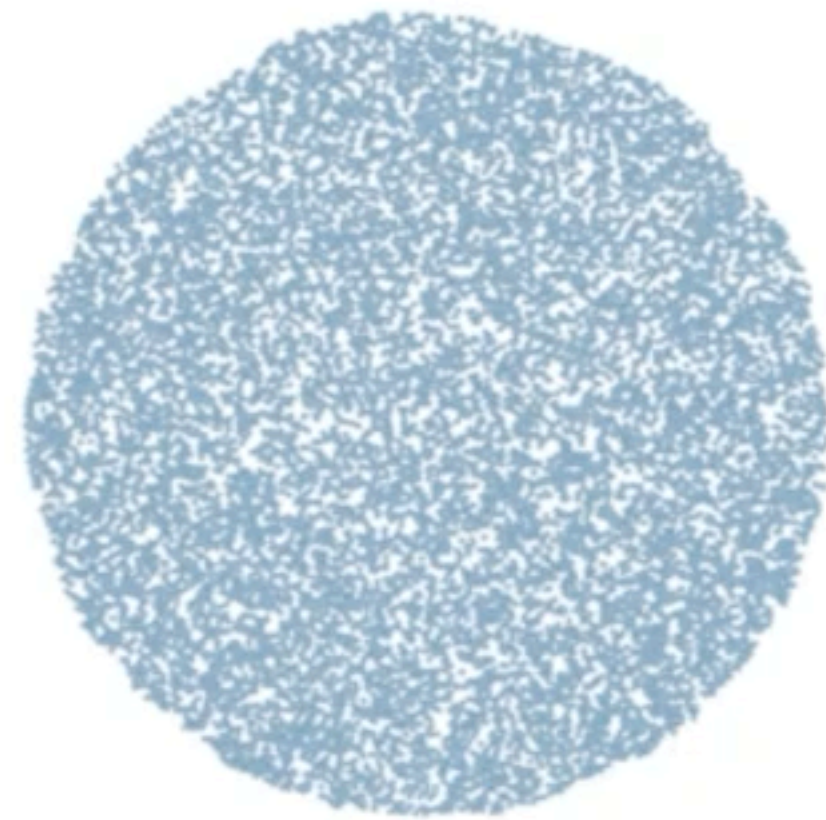
2D Sand

Ours
 $dt = 1e-3$

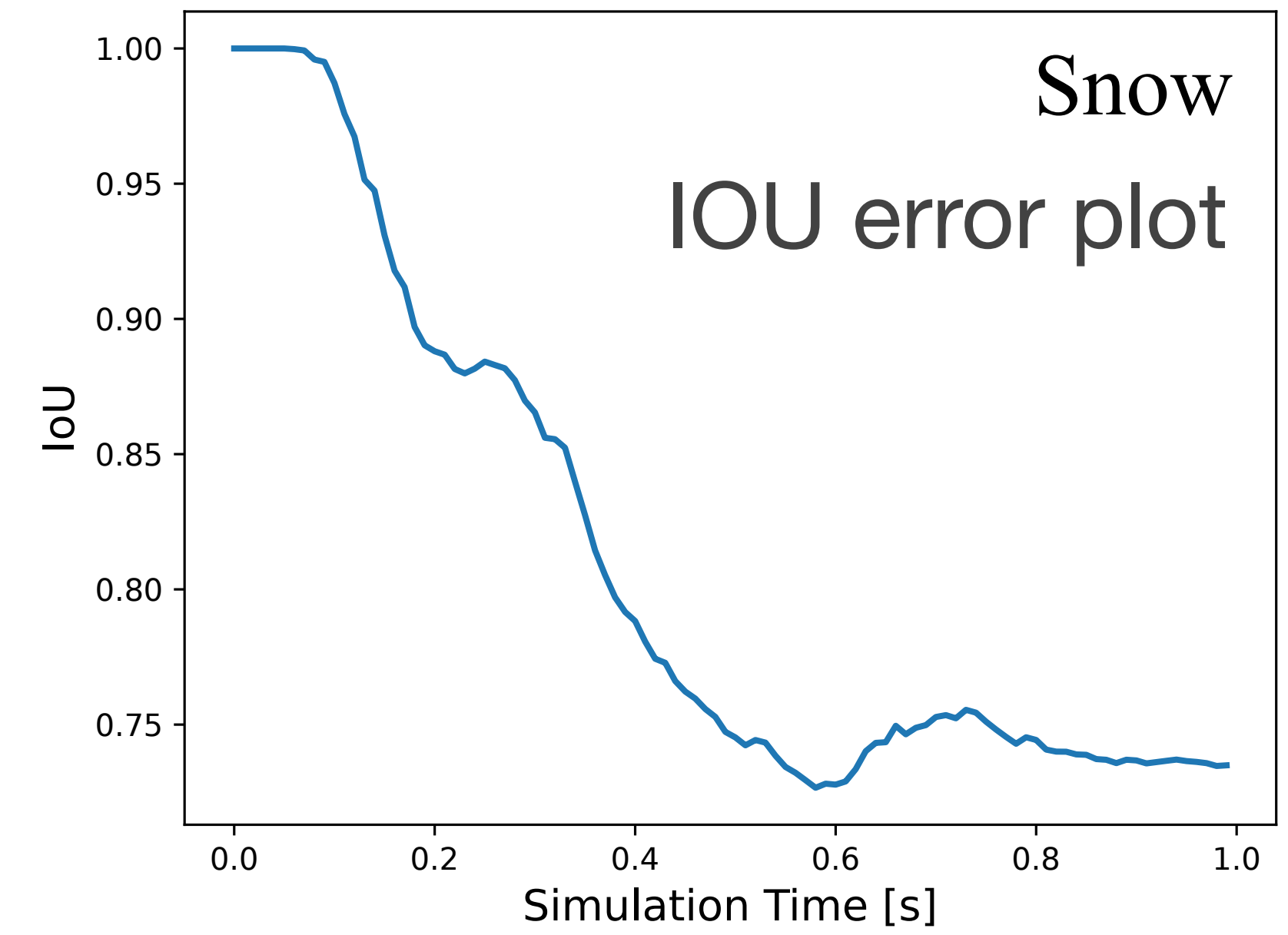
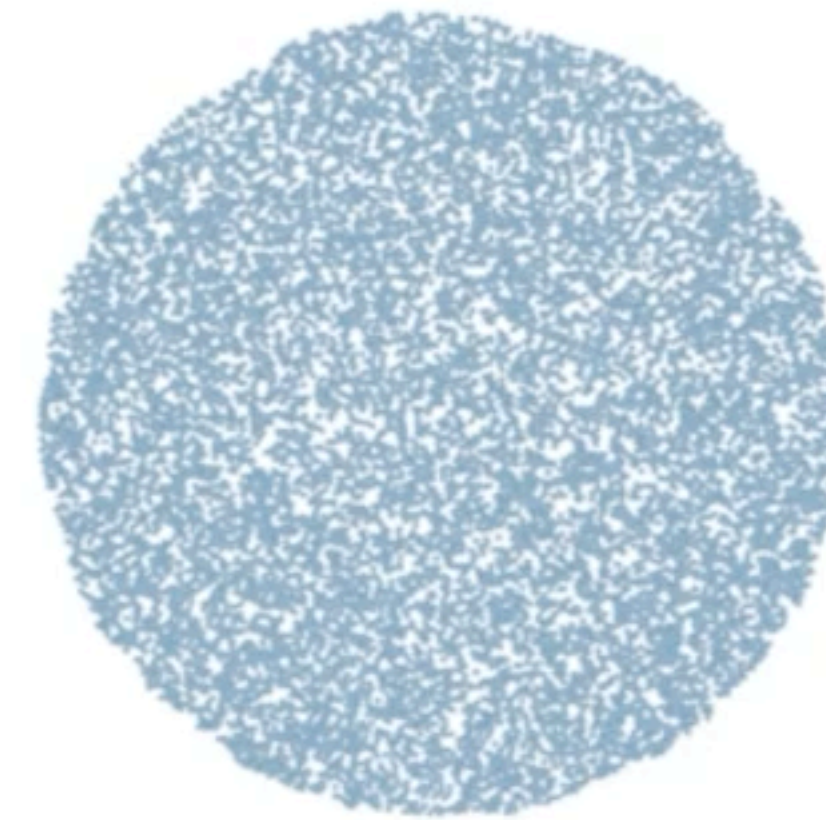


2D Snow

Ground Truth
dt = 1e-5



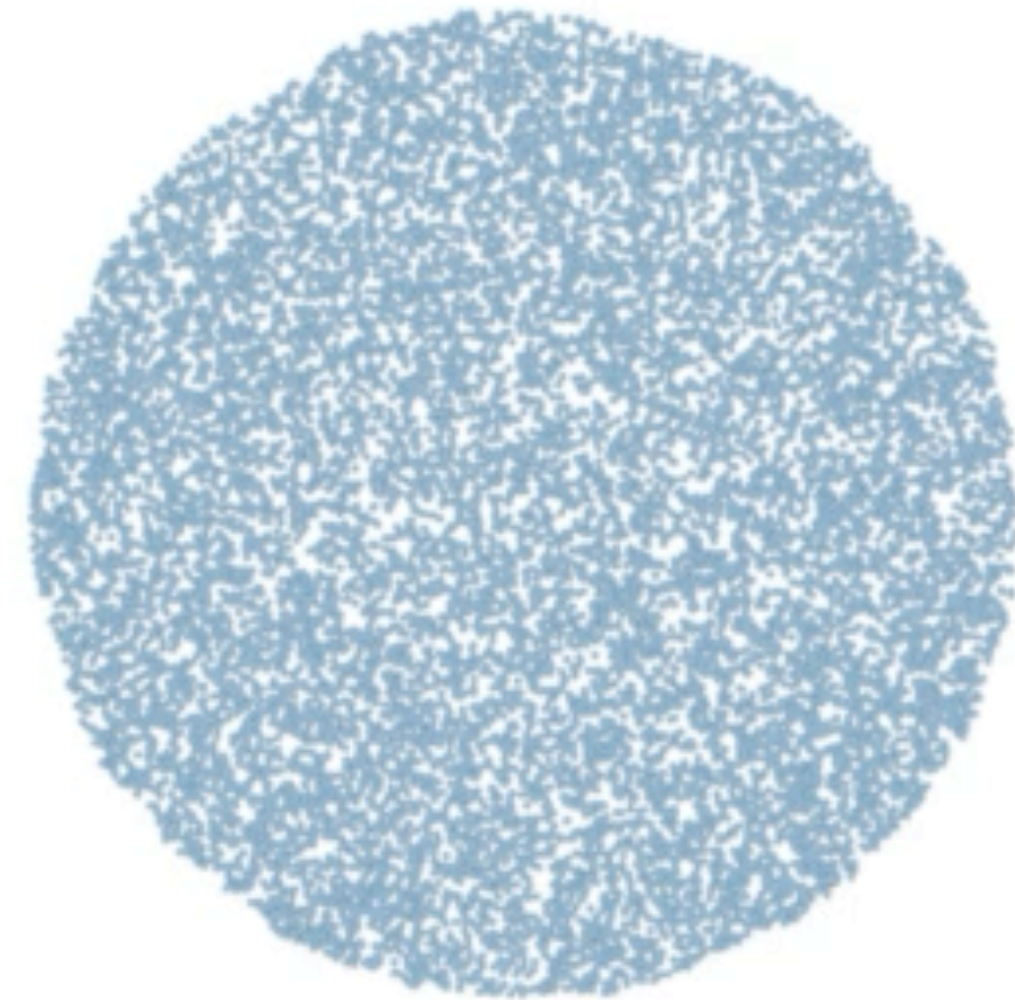
Ours
dt = 1e-5



Neo-Hookean Elasticity + Cam-Clay Plasticity

2D Snow

Ours
 $dt = 1e-3$



2D Metal

Ground Truth

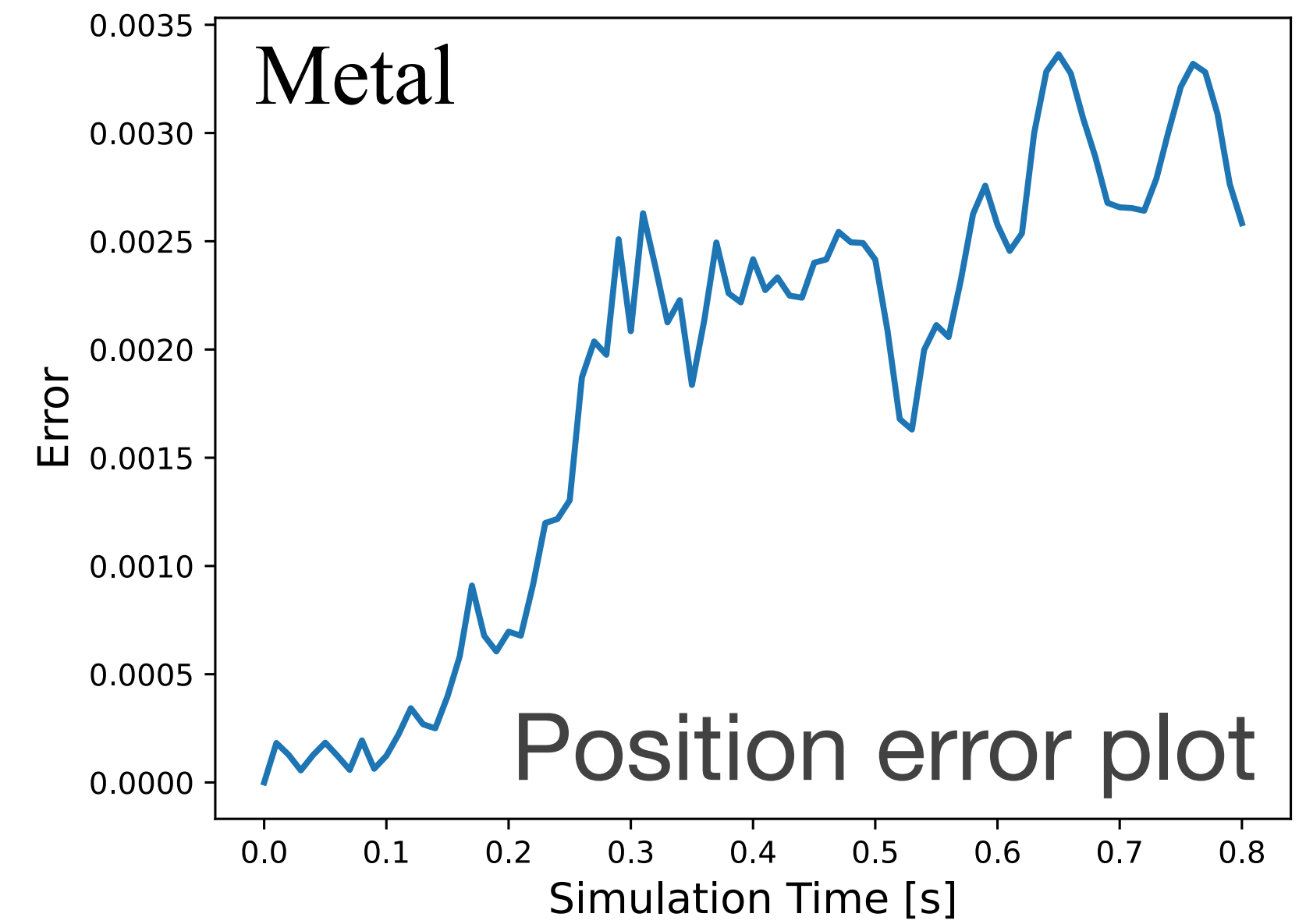
$E = 1e7$

$dt = 1e-5$

Ours

$E = 1e7$

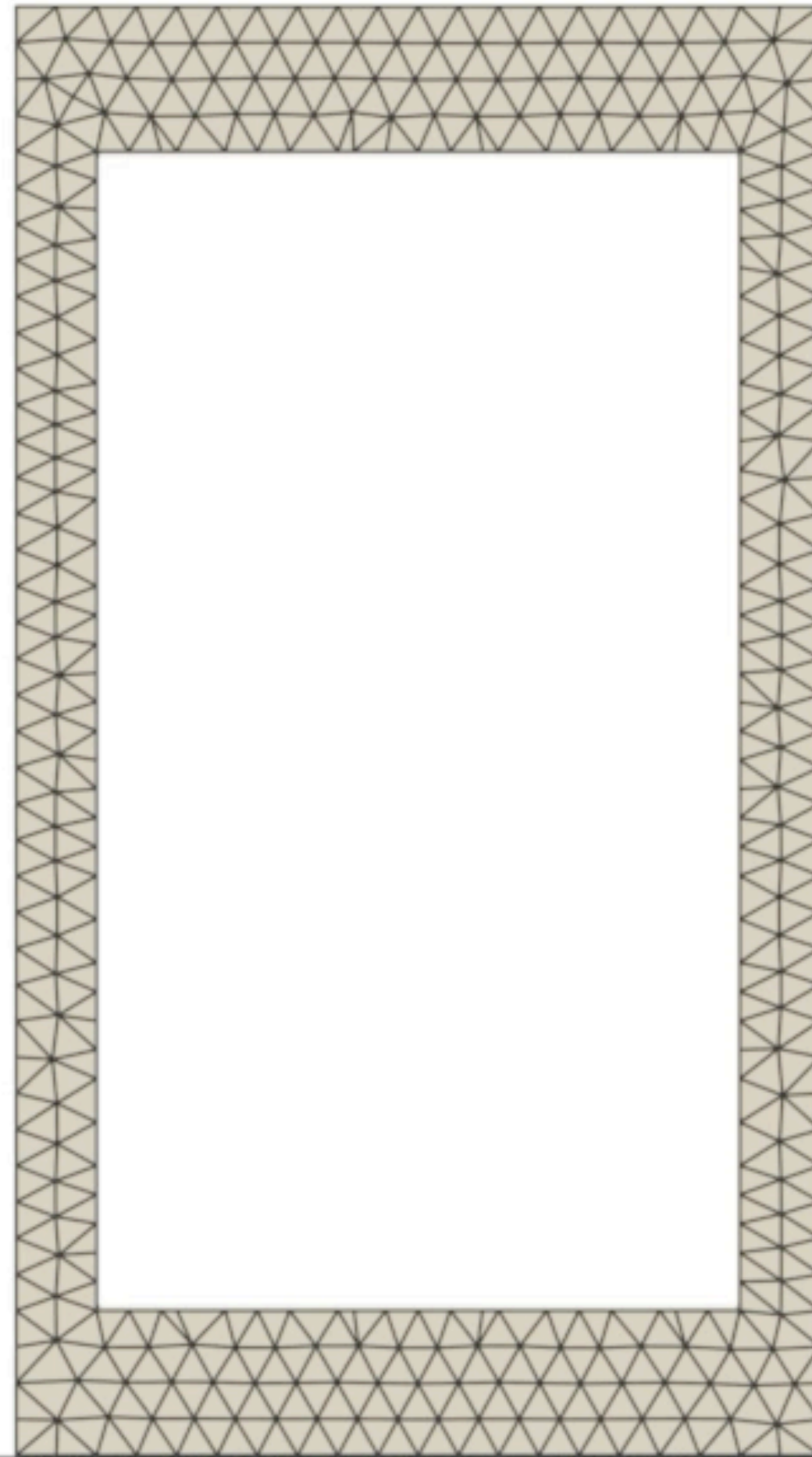
$dt = 1e-5$



StVK Elasticity

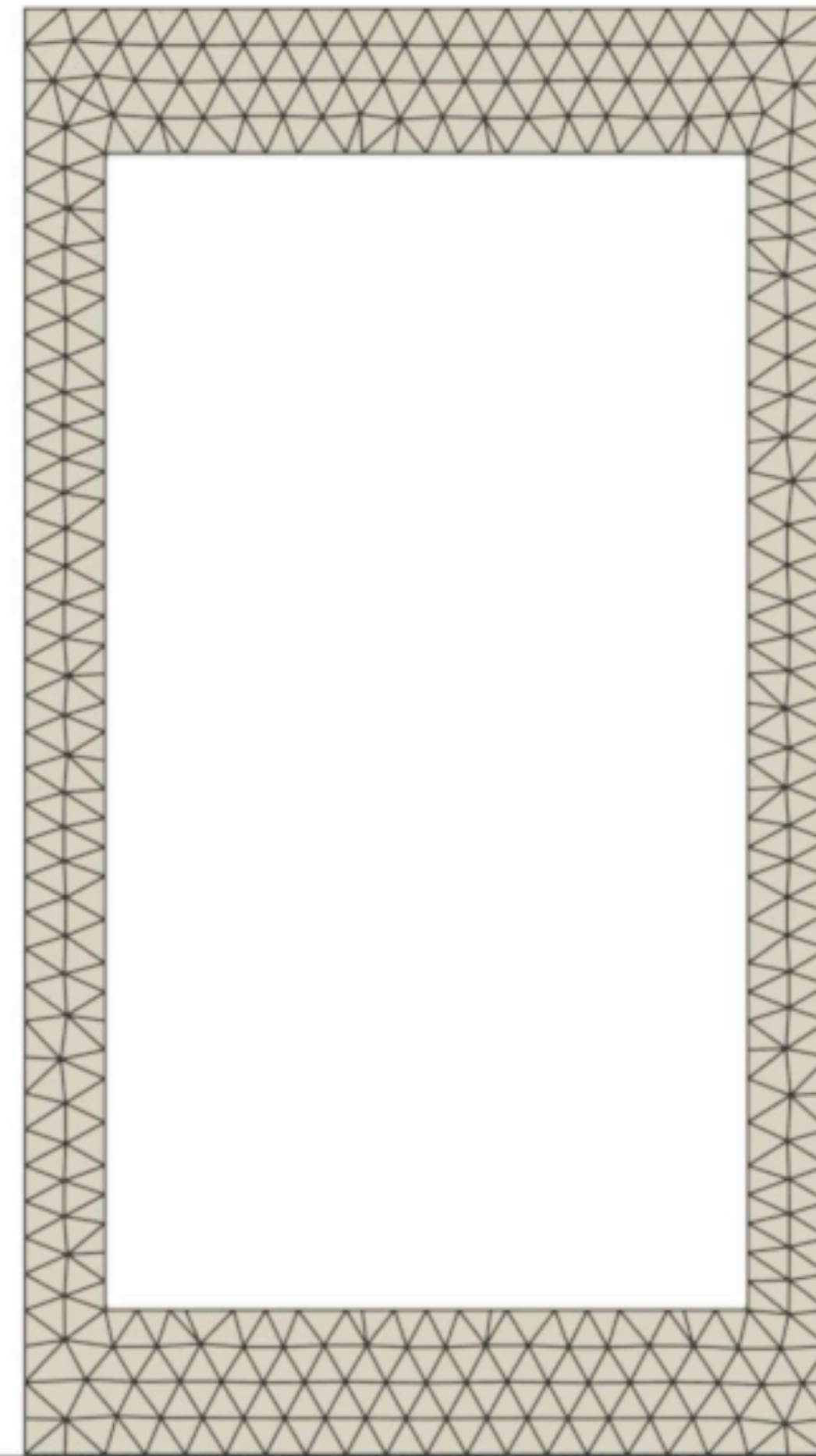
Von-Mises Plasticity

2D Metal



Ours
 $E = 1e10$
 $dt = 1e-2$

Learning Metal Plasticity Return Mapping



$$E = 1e10$$

$$dt = 1e-2$$

Neo-Hookean Elasticity

Learned Von-Mises Plasticity

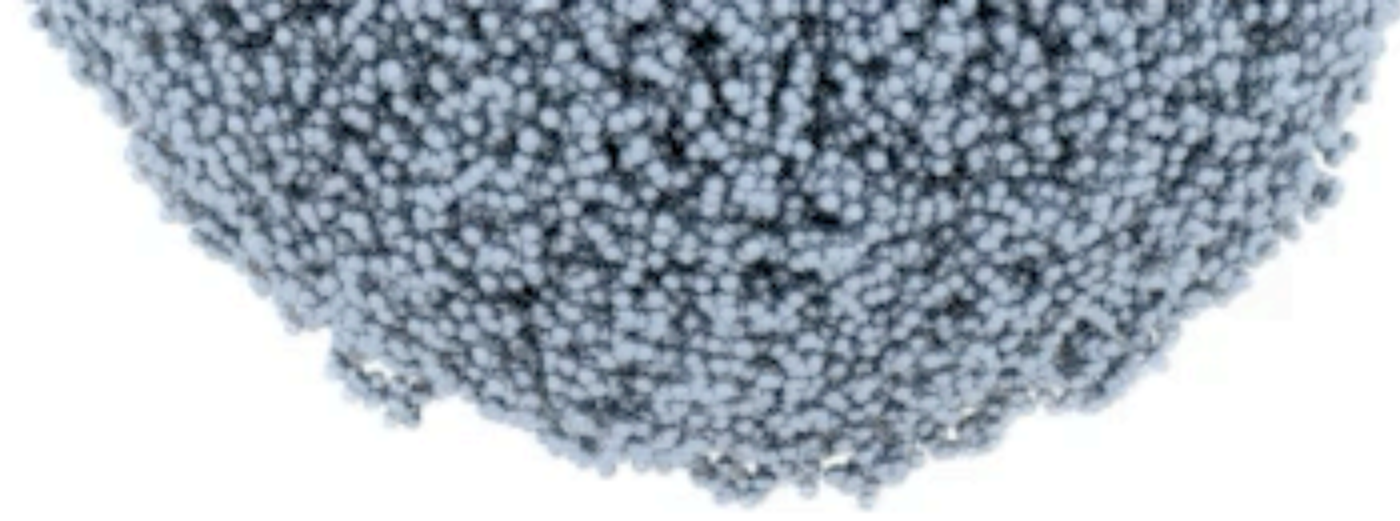


3D Examples

3D Sand

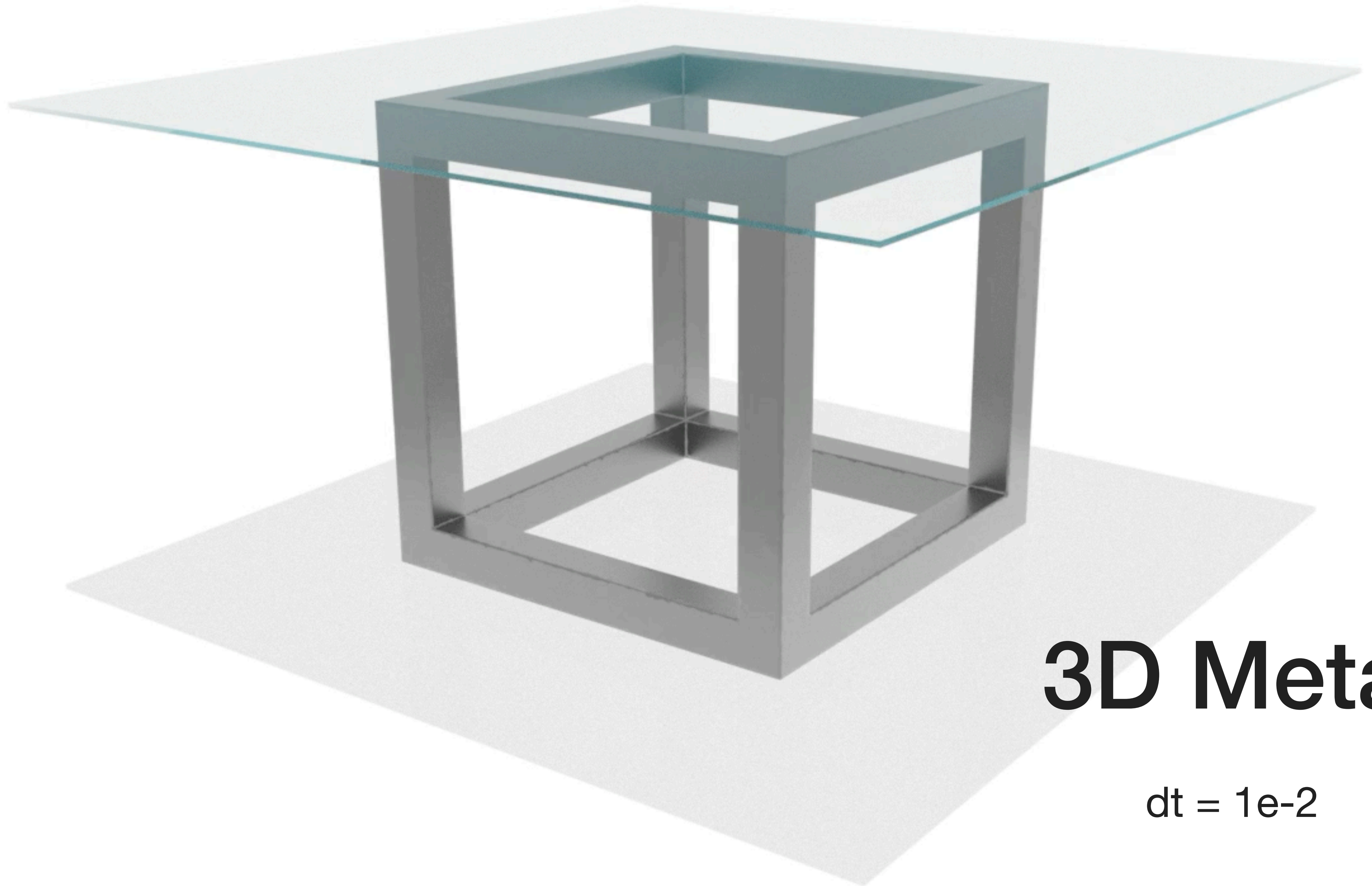
$dt = 1e-3$





3D Snow

$dt = 1e-3$



3D Metal

$dt = 1e-2$

Thanks for Watching!