

# Escaping Saddle Points for Effective Generalization on Class-Imbalanced Data

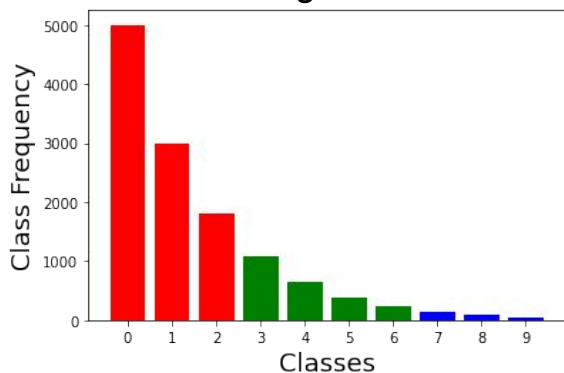
Harsh Rangwani\*, **Sumukh K Aithal\***, Mayank Mishra,  
R. Venkatesh Babu

Indian Institute of Science, Bengaluru



# Long-Tailed Learning

Training data

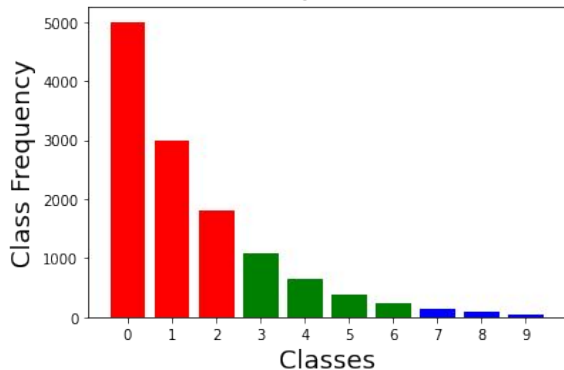


Long tailed distribution

Natural datasets are often imbalanced in terms of the frequency of samples in each class.

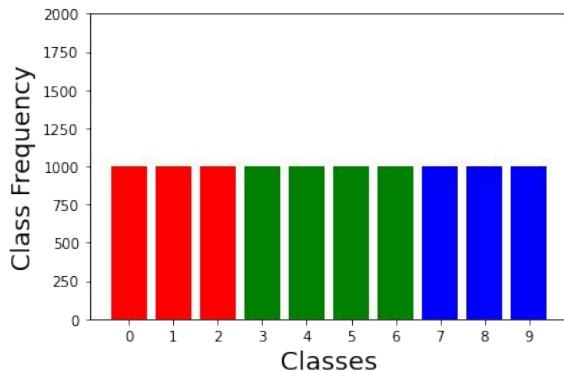
# Long-Tailed Learning

### Training data



Long tailed distribution

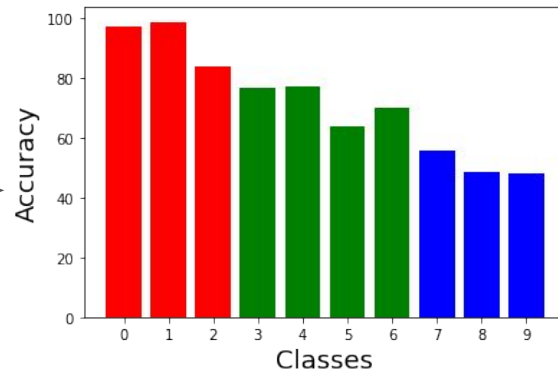
### Test data



Balanced distribution

### Model

### Class-Wise Accuracy on Balanced Test Set



The performance of neural networks degrades significantly on the minority class samples.

# Long-Tailed Learning

In this work, we primarily focus on analyzing the nature of solutions of loss manipulation methods.

1. **Cross-Entropy + Deferred-Reweighting (CE+DRW)<sup>[1]</sup>**

Re-weight the CE loss based on the inverse of number of samples in each class. (Minority class samples are given more weight)

<sup>[1]</sup>Cao, Kaidi, et al. "Learning Imbalanced Datasets with Label-Distribution-Aware Margin Loss." *NeurIPS* 2019.

# Long-Tailed Learning

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1. **Cross-Entropy + Deferred-Rewighting (CE+DRW)<sup>[1]</sup>**  
Re-weight the CE loss based on the inverse of number of samples in each class. (Minority class samples are given more weight)
2. **LDAM (Margin Based Loss)<sup>[1]</sup>**  
Regularize the minority class samples more (Larger margin) compared to the majority class samples.
3. **Vector Scaling Loss (VS)<sup>[2]</sup>**  
Combination of Multiplicative (Class Dependent Temperature) and Additive Adjustments (Logit Adjustment)

<sup>[1]</sup>Cao, Kaidi, et al. "Learning Imbalanced Datasets with Label-Distribution-Aware Margin Loss." *NeurIPS* 2019.

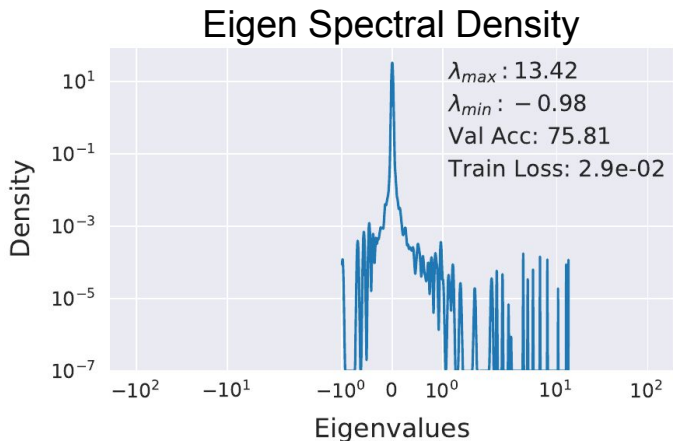
<sup>[2]</sup>Kini, Ganesh Ramachandra, et al. "Label-imbalanced and group-sensitive classification under overparameterization." *NeurIPS* 2021

## Loss Landscape

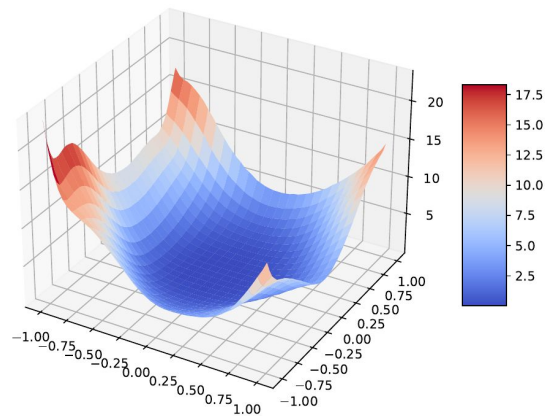
- The Hessian of the training loss can be used to analyze the nature of converged solution and the dynamics of optimization in deep neural networks.

# Loss Landscape

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- Eigenvalues of the Hessian (Eigen Spectral Density) characterize the local curvature of the loss at the solution.



3D Visualization of Loss Landscape



## Loss Landscape

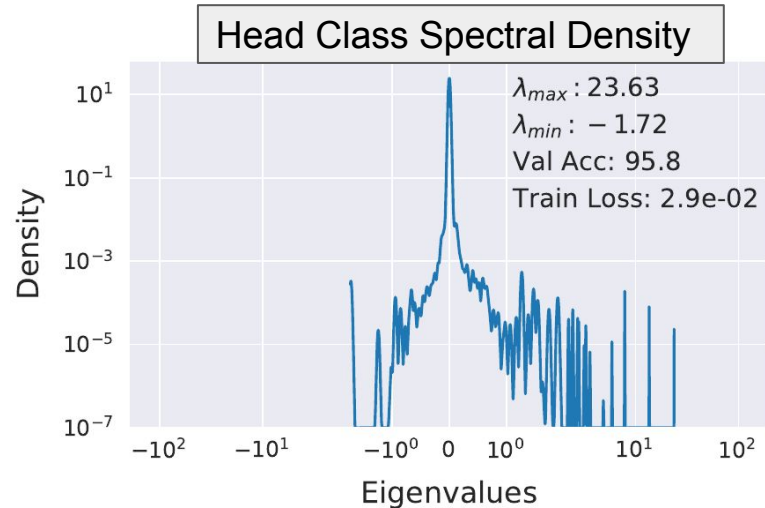
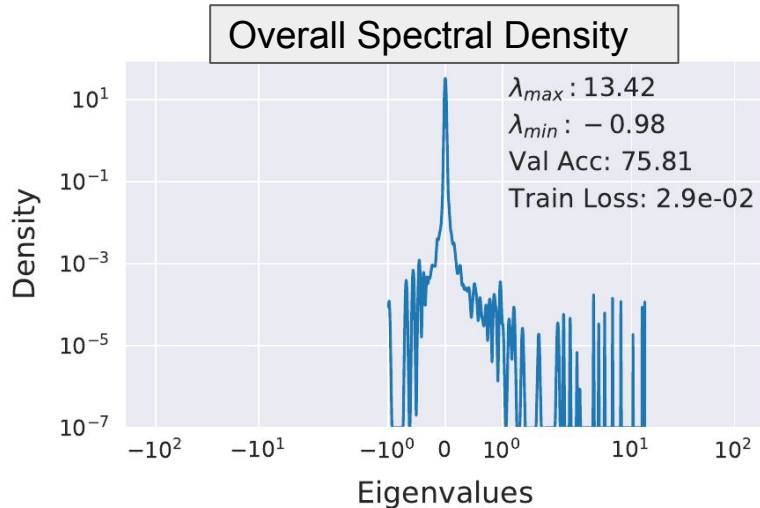
- The Hessian of the training loss can be used to analyze the nature of minima and the dynamics of optimization in deep neural networks.
- Eigenvalues of the Hessian (Eigen Spectral Density) characterize the local curvature of the loss at the solution.
- Geometry of the loss landscape is correlated with generalization. For example, flat minima generalizes better than sharp minima.<sup>[1]</sup>

<sup>[1]</sup>Keskar, Nitish Shirish, et al. "On large-batch training for deep learning: Generalization gap and sharp minima." ICLR 2017.



# Class-Wise Loss Landscape Analysis in Imbalanced Datasets

- **Prior Work:** Hessian of the average loss (Eigen Spectral Density) is used to characterize the nature of minima.
- On imbalanced datasets, this analysis is not very useful as it indicates convergence to **local minima** and **imitates the head class**.

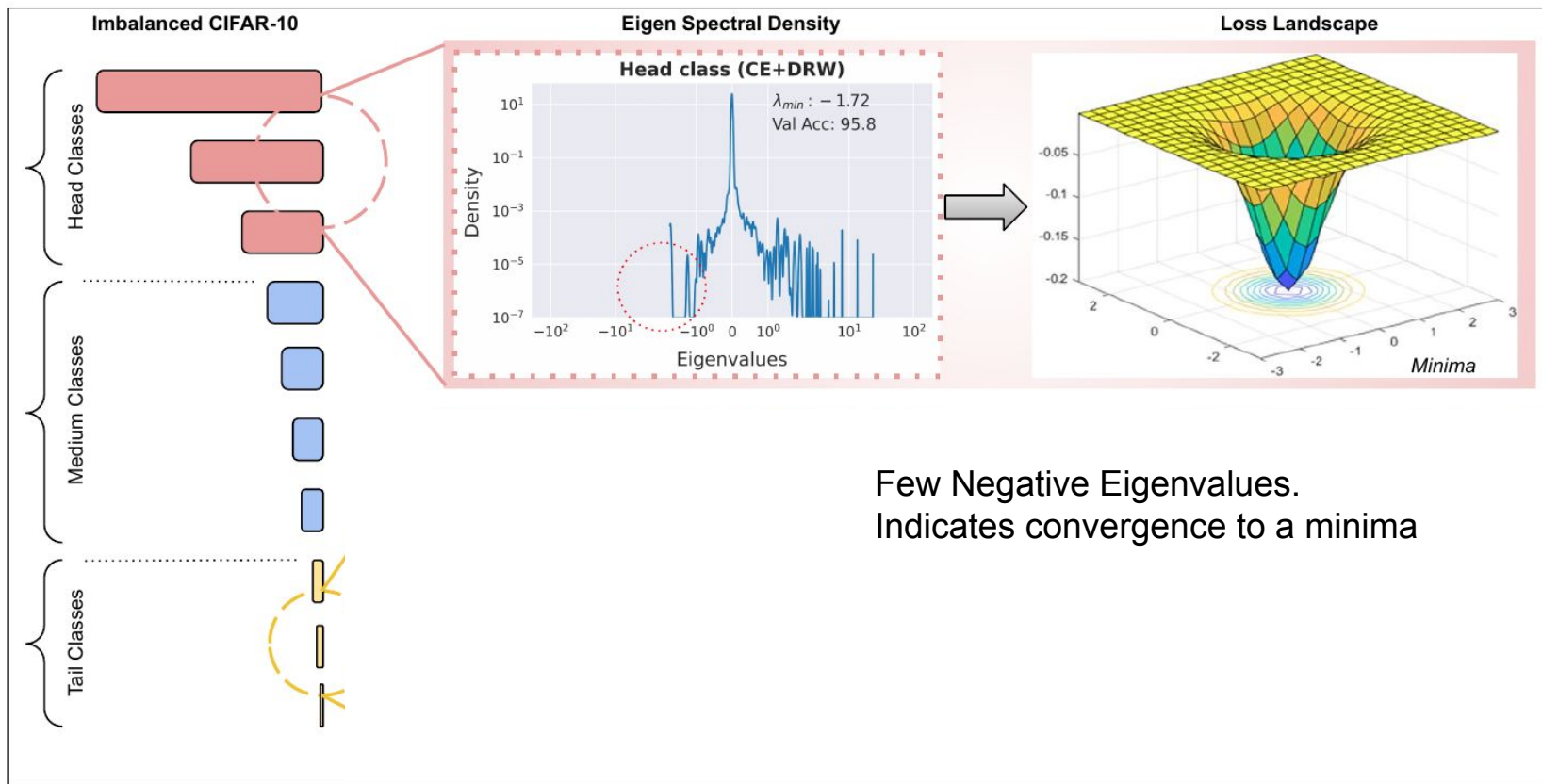


# Class-Wise Loss Landscape Analysis in Imbalanced Datasets

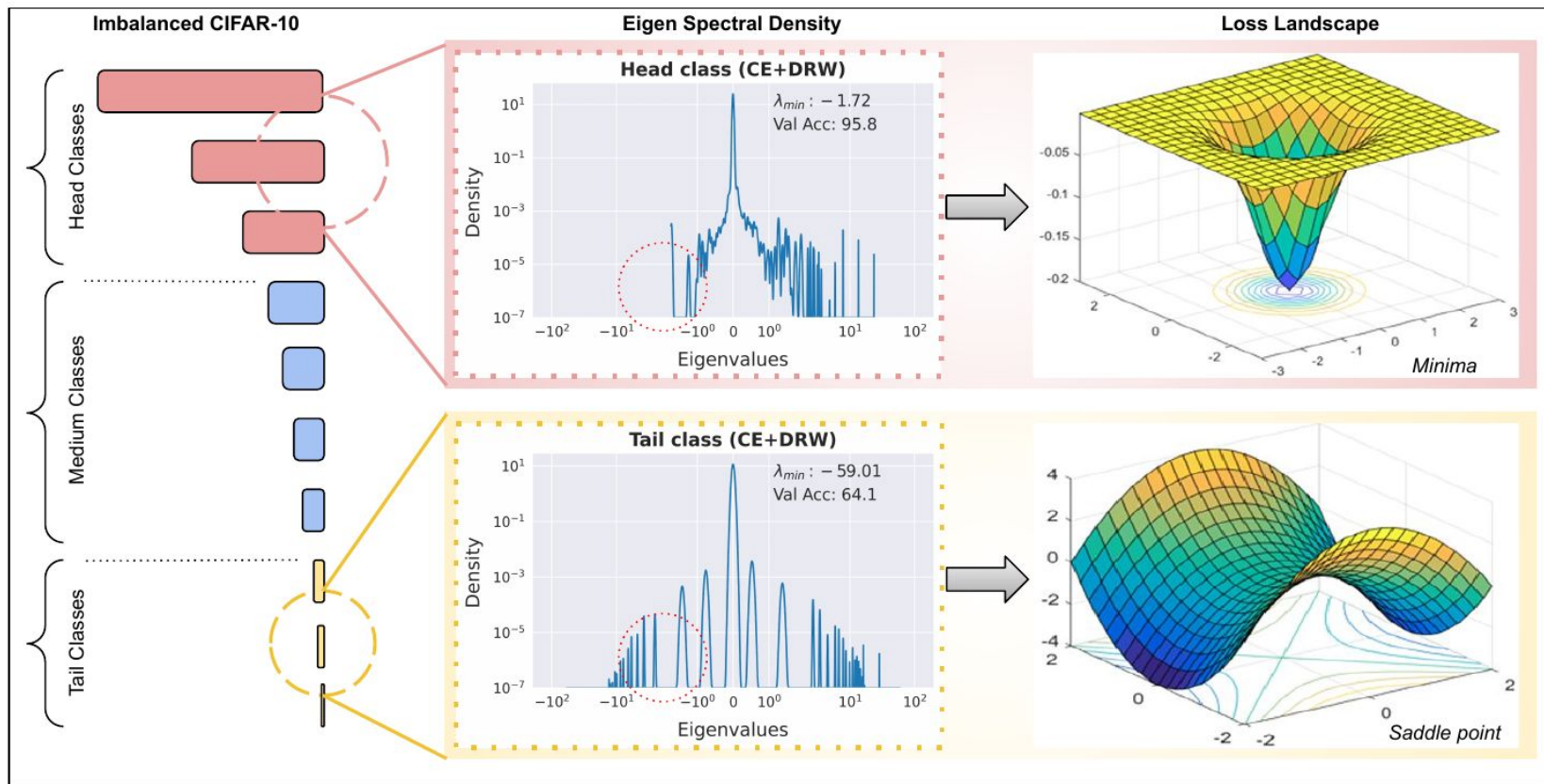
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***Our work:** Class-Wise Analysis of loss landscape on imbalanced datasets uncovers interesting insights.*

# Convergence to Saddle Points in Tail Class Loss Landscape



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# Escaping Saddle Points Improves Generalization

- Due to the occurrence of saddle points, we observe that the network suffers from poor generalization on minority classes.
- Prior work on escaping saddle points includes methods like Perturbed Gradient Descent (PGD)<sup>[1]</sup> which are not commonly used to train deep neural networks.

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- Prior work on escaping saddle points includes methods like Perturbed Gradient Descent (PGD)<sup>[1]</sup> which are not commonly used to train deep neural networks.
- Sharpness-Aware Minimization (SAM)<sup>[2]</sup> is a recently proposed optimizer with an objective to explicitly find a flat minima with a low loss.
- We show that **Sharpness-Aware Minimization (SAM)** can also escape saddle points and lead to improved generalization particularly on the tail classes.

<sup>[1]</sup>Jin, Chi, et al. "How to escape saddle points efficiently." *International Conference on Machine Learning*. PMLR, 2017.

<sup>[2]</sup>Foret, Pierre, et al. *Sharpness-aware minimization for efficiently improving generalization*. In *ICLR*, 2021

# Analysis of SAM for Escaping Saddle Points

**SAM:**

$$\min_w \max_{\|\epsilon\| \leq \rho} f(w + \epsilon)$$

$f$ : Objective Function

$\rho$ : Neighborhood size

*First step:* Find a sharp maximal point  $\epsilon$  in the neighborhood of the weights  $w$ .

*Second step:* Minimize the loss at this sharp maximal point.

$$\hat{\epsilon}(w) \approx \arg \max_{\|\epsilon\| \leq \rho} f(w) + \epsilon^T \nabla f(w) = \rho \nabla f(w) / \|\nabla f(w)\|_2$$

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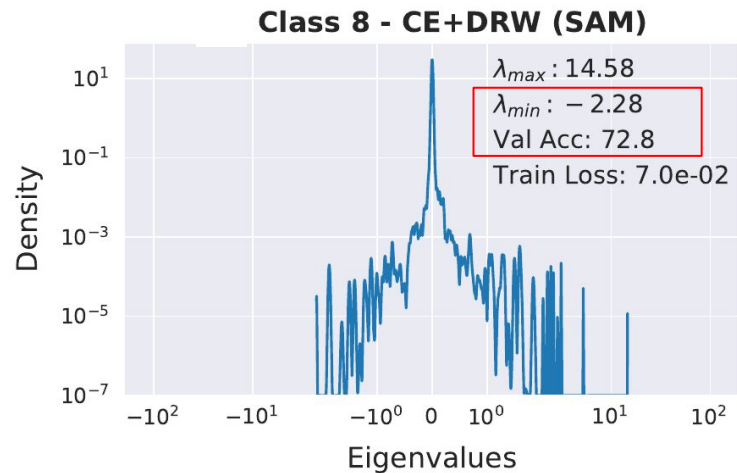
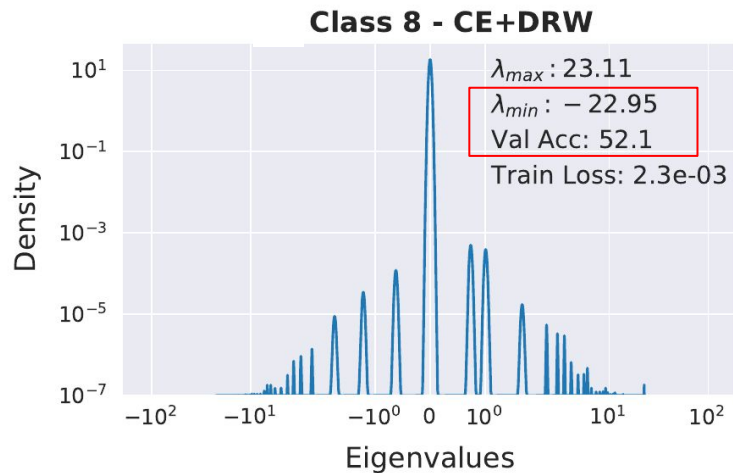
## Informal Theoretical Explanation:

We theoretically show that the SAM amplifies the gradient component along the negative curvature. This helps SAM to effectively escape saddle points.



# Escaping Saddle Points Improves Generalization

With SAM (high  $\rho$ ), the large negative eigenvalues present in the loss landscape of the tail class get suppressed. (i.e no more saddle point)

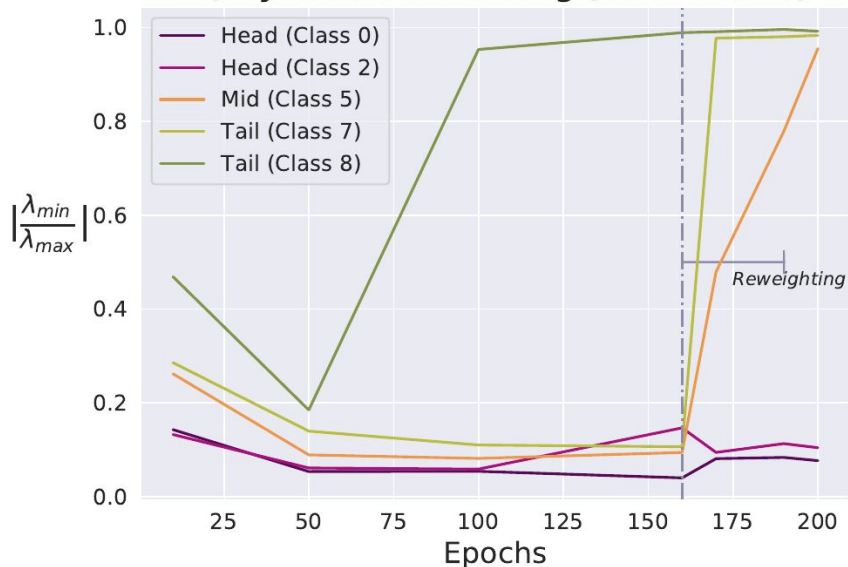


Eigen Spectral Density of **Tail Classes** with SGD (left) and SAM (right)

# Dynamics of Training on Long-Tailed datasets

With SGD, network converges to non-convex regions with negative curvature for tail classes.

**A) Dynamics of training (CIFAR-10 LT)**

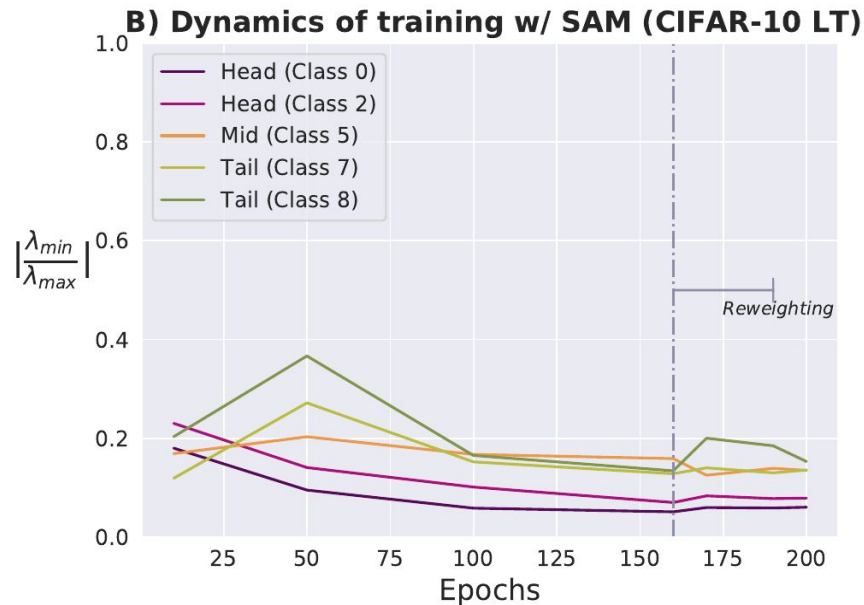
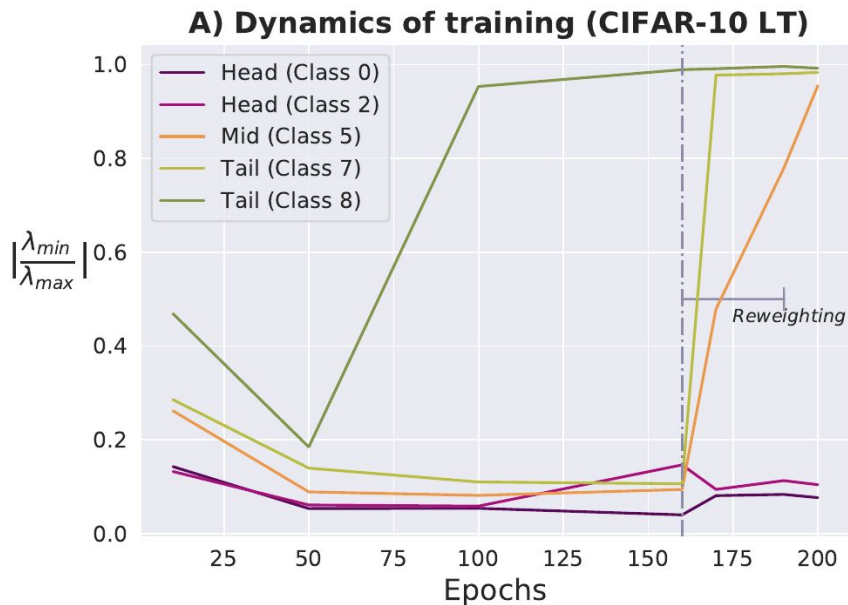


We find that with reweighting and margin enhancement is the main culprit, which forces model into non-convex regions leading to saddle points.

$\left| \frac{\lambda_{min}}{\lambda_{max}} \right|$  : Measure of non-convexity of the loss landscape. (High value indicates non-convex regions)



# Dynamics of Training on Long-Tailed datasets

SAM does not allow the tail classes to reach a region of high non-convexity.



$\left| \frac{\lambda_{min}}{\lambda_{max}} \right|$  : Measure of non-convexity of the loss landscape. (High value indicates non-convex regions)

## Results on CIFAR-10 LT and CIFAR-100 LT

	CIFAR-10 LT				CIFAR-100 LT			
	Acc	Head	Mid	Tail	Acc	Head	Mid	Tail
CE	71.7 $\pm$ 0.1	90.8 $\pm$ 3.6	71.9 $\pm$ 0.4	52.3 $\pm$ 3.7	38.5 $\pm$ 0.5	64.5 $\pm$ 0.7	36.8 $\pm$ 1.0	8.2 $\pm$ 1.0
CE + SAM	73.1 $\pm$ 0.3	93.3 $\pm$ 0.2	74.1 $\pm$ 0.6	51.7 $\pm$ 1.0	39.6 $\pm$ 0.6	66.5 $\pm$ 0.7	38.1 $\pm$ 1.1	8.0 $\pm$ 0.6
CE + DRW [8]	75.5 $\pm$ 0.2	91.6 $\pm$ 0.4	74.1 $\pm$ 0.4	61.4 $\pm$ 0.9	41.0 $\pm$ 0.6	61.3 $\pm$ 1.3	41.7 $\pm$ 0.5	14.7 $\pm$ 0.9
CE + DRW + SAM	80.6 $\pm$ 0.4	91.4 $\pm$ 0.3	78.0 $\pm$ 0.4	73.1 $\pm$ 0.9	44.6 $\pm$ 0.4	61.2 $\pm$ 0.8	47.5 $\pm$ 0.6	20.7 $\pm$ 0.6
	5.1% 				3.6% 			

*DRW + SAM improves upon the overall performance of CE+DRW by 5.1% on CIFAR-10 LT and 3.6% on CIFAR-100 LT datasets, with the tail class accuracy increasing by 11.7% and 7.7% respectively.*

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LDAM + DRW [8]	77.5 $\pm$ 0.5	91.1 $\pm$ 0.8	75.7 $\pm$ 0.7	66.4 $\pm$ 0.2	42.7 $\pm$ 0.3	61.8 $\pm$ 0.6	42.2 $\pm$ 1.5	19.4 $\pm$ 0.9
LDAM + DRW + SAM	81.9 $\pm$ 0.4	91.0 $\pm$ 0.2	79.2 $\pm$ 0.5	76.4 $\pm$ 1.1	45.4 $\pm$ 0.1	64.4 $\pm$ 0.3	46.2 $\pm$ 0.2	20.8 $\pm$ 0.3
VS [30]	78.6 $\pm$ 0.3	90.6 $\pm$ 0.4	75.8 $\pm$ 0.5	70.3 $\pm$ 0.5	41.7 $\pm$ 0.5	54.4 $\pm$ 0.2	41.1 $\pm$ 0.6	26.8 $\pm$ 1.0
VS + SAM	82.4 $\pm$ 0.4	90.7 $\pm$ 0.0	79.6 $\pm$ 0.5	78.0 $\pm$ 0.2	46.6 $\pm$ 0.4	56.4 $\pm$ 0.4	48.8 $\pm$ 0.6	31.7 $\pm$ 0.1

*Integrating SAM with state-of-the-art techniques for long-tailed learning (LDAM, VS) leads to significant gains in overall accuracy primarily due to the major gain in the accuracy on the tail classes.*

## Results on Large Scale Datasets

- Problem of saddle points also exists in large datasets.
- SAM is easily generalizable to large-scale imbalanced datasets without any changes.

Method	iNaturalist 2018					ImageNet-LT			
	Two stage	Acc	Head	Mid	Tail	Acc	Head	Mid	Tail
CE	×	60.3	72.8	62.7	54.8	42.7	62.5	36.6	12.5
cRT [27] †	✓	68.2	<u>73.2</u>	68.8	66.1	50.3	<u>62.5</u>	47.4	29.5
LWS [27] †	✓	69.5	71.0	69.8	68.8	51.2	61.8	48.6	33.5
MiSLAS [57]	✓	<b>71.6</b>	<u>73.2</u>	<b>72.4</b>	<u>70.4</u>	52.7	61.7	51.3	<b>35.8</b>
DisAlign [55]	✓	69.5	<u>61.6</u>	<u>70.8</u>	<u>69.9</u>	52.9	61.3	<b>52.2</b>	31.4
DRO-LT [44]	×	69.7	<b>73.9</b>	70.6	68.9	<b>53.5</b>	<b>64.0</b>	49.8	33.1
CE + DRW	×	63.0	59.8	64.4	62.3	44.9	57.9	42.2	21.6
CE + DRW + SAM	×	65.3	60.5	66.2	65.5	47.1	56.6	45.8	28.1
LDAM + DRW	×	67.5	63.0	68.3	67.8	49.9	61.1	48.2	28.3
LDAM + DRW + SAM	×	<u>70.1</u>	64.1	70.5	<b>71.2</b>	<u>53.1</u>	62.0	<u>52.1</u>	<u>34.8</u>

## Summary and Conclusion

1. Training on imbalanced datasets can lead to convergence to points with sufficiently **large negative curvature** in the loss landscape for **minority classes**.

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1. Training on imbalanced datasets can lead to convergence to points with sufficiently **large negative curvature** in the loss landscape for **minority classes**.
2. We propose to use **SAM** with a high regularization factor  $\rho$  as an effective method to escape regions of negative curvature and **enhance the generalization performance**.
3. Results on various datasets with different long-tail learning methods indicate that the proposed method is **generic** and **improves base method** significantly.

**Thank You**