

Local Metric Learning for Off-Policy Evaluation in Contextual Bandits with Continuous Actions

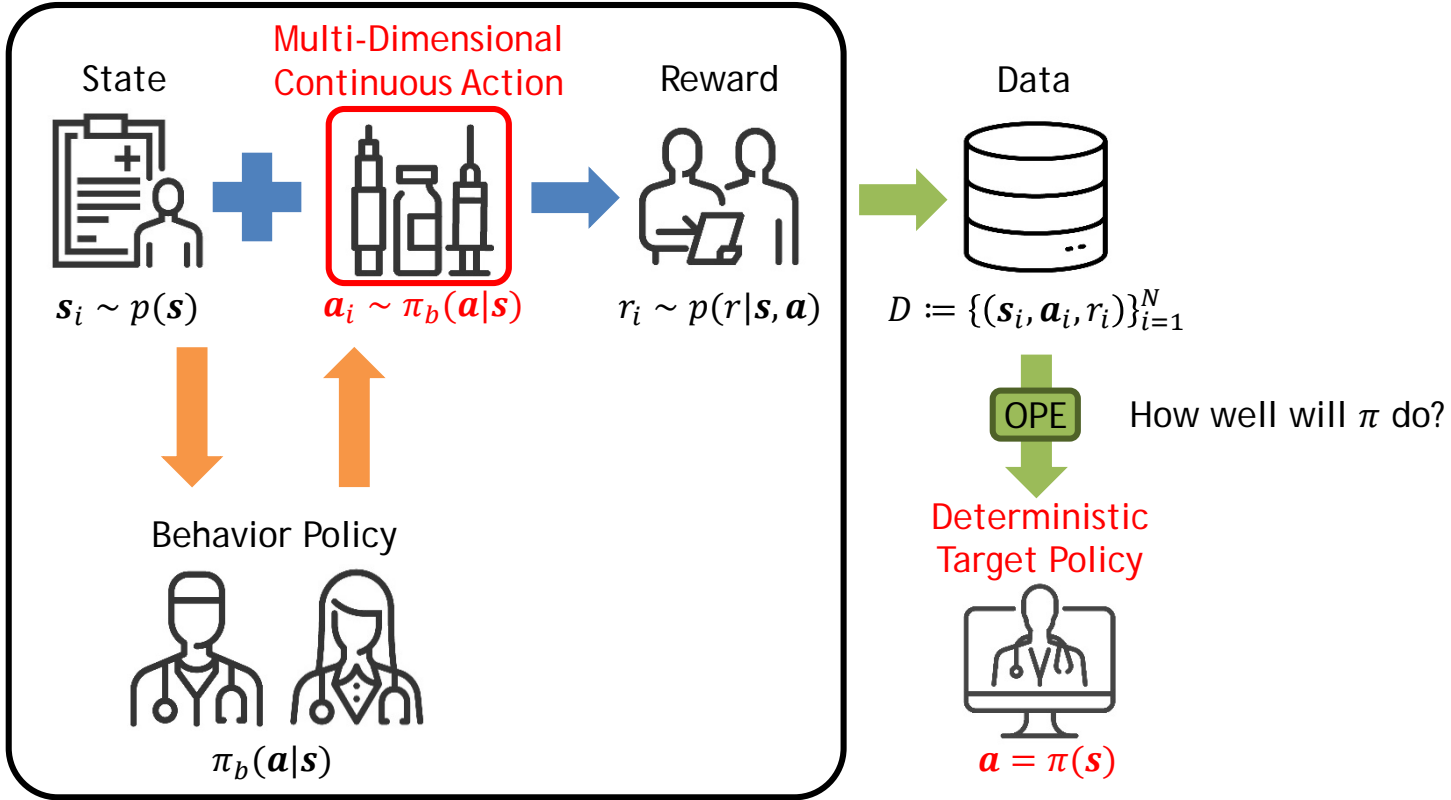
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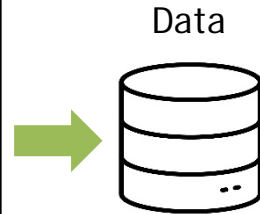
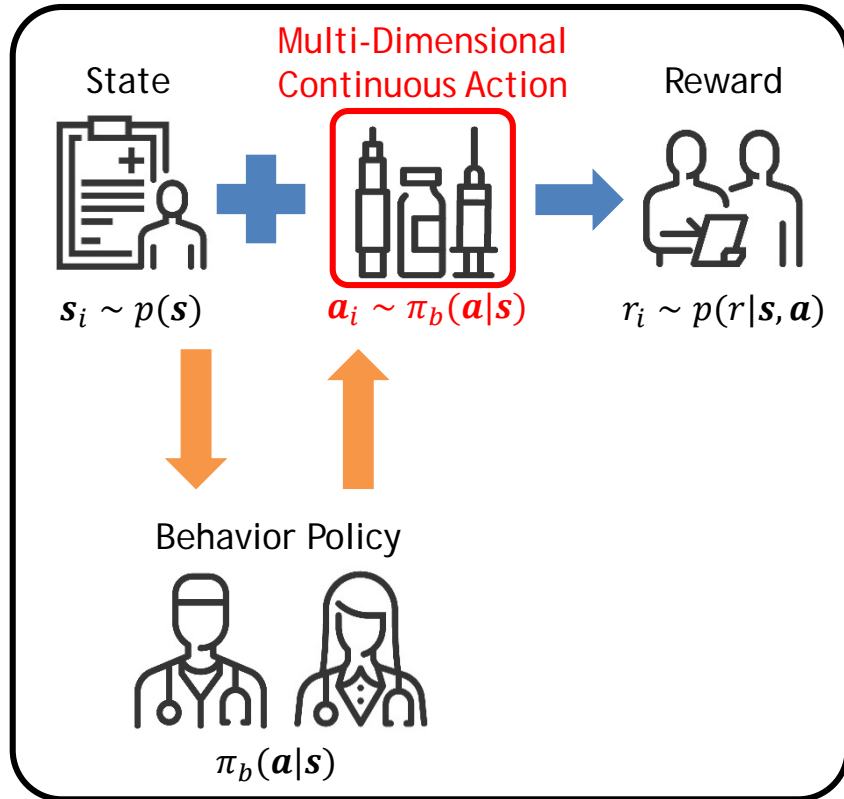
Off-Policy Evaluation (OPE) of Deterministic Policies

OPE: Evaluate a target policy using the data sampled by a behavior policy



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$$D := \{(s_i, a_i, r_i)\}_{i=1}^N$$



Deterministic Target Policy



$$a = \pi(s)$$

How well will π do?

$$\begin{aligned} \rho^\pi &= \mathbb{E}_{s \sim p(s), a \sim \pi(a|s), r \sim p(r|s, a)}[r] \\ &= \mathbb{E}_{s \sim p(s), a \sim \pi_b(a|s), r \sim p(r|s, a)} \left[\frac{\pi(a|s)}{\pi_b(a|s)} r \right] \\ &\approx \frac{1}{N} \sum_{i=1}^N \frac{\delta(a_i - \pi(s_i))}{\pi_b(a_i|s_i)} r_i \end{aligned}$$

The importance sampling (IS) estimate is almost surely zero

Related Works

□ Kernel-based methods

- Relax a deterministic target policy using a kernel

$$\begin{aligned}\rho^\pi &\approx \frac{1}{N} \sum_{i=1}^N \frac{\delta(\mathbf{a}_i - \pi(\mathbf{s}_i))}{\pi_b(\mathbf{a}_i | \mathbf{s}_i)} r_i \\ &\approx \frac{1}{Nh^{D_A}} \sum_{i=1}^N K\left(\frac{\mathbf{a}_i - \pi(\mathbf{s}_i)}{h}\right) \frac{r_i}{\pi_b(\mathbf{a}_i | \mathbf{s}_i)}\end{aligned}$$

- Choose bandwidth h that best balances bias and variance
 - Select a bandwidth among a set of bandwidths using the Lepski's principle [1]
 - Choose the optimal bandwidth h^* that minimizes the leading-order MSE (LOMSE) [2]

$$\text{LOMSE}(h, N, D_A) = \underbrace{h^4 C_b}_{(\text{leading-order bias})^2} + \underbrace{\frac{C_v}{Nh^{D_A}}}_{(\text{leading-order variance})} ;$$

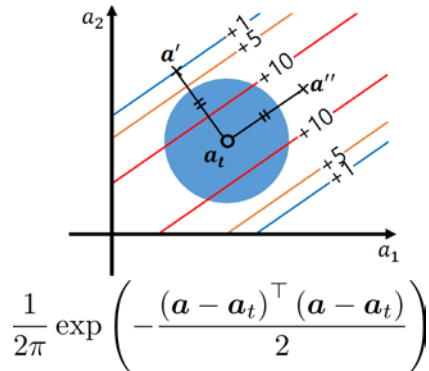
$$C_b := \frac{1}{4} \mathbb{E}_{\mathbf{s} \sim p(\mathbf{s})} \left[\nabla_{\mathbf{a}}^2 \mathbb{E}[r | \mathbf{s}, \mathbf{a}] \Big|_{\mathbf{a}=\pi(\mathbf{s})} \right]^2, \quad C_v := R(K) \mathbb{E}_{\mathbf{s} \sim p(\mathbf{s})} \left[\frac{\mathbb{E}[r^2 | \mathbf{s}, \mathbf{a} = \pi(\mathbf{s})]}{\pi_b(\mathbf{a} = \pi(\mathbf{s}) | \mathbf{s})} \right], \quad R(K) := \int K(\mathbf{u})^2 d\mathbf{u}$$

[1] Yi Su et al. "Adaptive estimator selection for off-policy evaluation." ICML (2020)

[2] Nathan Kallus and Angela Zhou. "Policy evaluation and optimization with continuous treatments." AISTATS (2018)

Limitation of the Previous Works

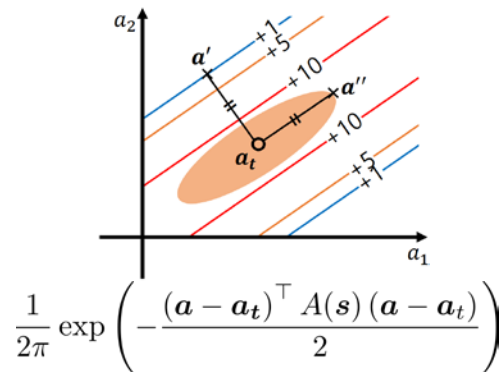
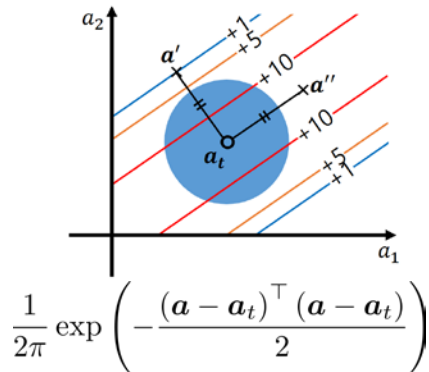
- Usage of Euclidean distances induce excessive bias
 - Use Euclidean distances for measuring similarities between the target and behavior actions
 - The Euclidean distance between actions may not reflect the similarity in the corresponding rewards
 - Mahalanobis distance metric $A(\mathbf{s})$ locally learned at each state \mathbf{s} can be used to reduce the bias



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where $A(\mathbf{s}) \succ 0$, $A(\mathbf{s})^\top = A(\mathbf{s})$, $|A(\mathbf{s})| = 1$,
 $\mathbf{a}_t = \pi(\mathbf{s})$

□ Could MSE be reduced by the reduction of bias with the metric?

Kernel Metric Learning for IS (KMIS)

□ LOMSE has following characteristics when h^* is applied

- Bias of the isotropic kernel-based method dominates over the variance for $D_A \gg 4$ (Proposition 1)
- LOMSE approximates to C_b for a high action dimension $D_A \gg 4$ (Proposition 1)
- **For high dimensional action spaces, the MSE of a kernel-based IS estimator can be decreased by reducing C_b**
- Proposition 1 is adapted from [1]

For $D_A \gg 4$,

$$\underbrace{(h^*)^4 C_b}_{\text{(leading-order bias)}^2} \gg \underbrace{\frac{C_v}{N(h^*)^{D_A}}}_{\text{leading-order variance}} :$$

$$\text{LOMSE}(h^*, N, D_A) = N^{-\frac{4}{D_A+4}} \left(\left(\frac{D_A}{4} \right)^{\frac{4}{D_A+4}} + \left(\frac{4}{D_A} \right)^{\frac{D_A}{D_A+4}} \right) C_b^{\frac{D_A}{D_A+4}} C_v^{\frac{4}{D_A+4}} \approx C_b.$$

□ Goal: Reduce C_b by applying $A(\mathbf{s})$

Kernel Metric Learning for IS (KMIS)

Derive the C_b in the
Leading-Order Bias
with a Metric

Upper Bound of $C_{b,A}$
as Minimization
Objective

Compute the
Closed-Form Solution

□ C_b with a metric $A(\mathbf{s})$ (i.e. $C_{b,A}$)

$$C_{b,A} = \frac{1}{4} \mathbb{E}_{\mathbf{s} \sim p(\mathbf{s})} \left[\text{tr} \left(A(\mathbf{s})^{-1} \mathbf{H}_a \mathbb{E}[r \mid \mathbf{s}, \mathbf{a}] \Big|_{\mathbf{a}=\pi(\mathbf{s})} \right) \right]^2$$

\mathbf{H}_a : Hessian operator

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\mathbf{H}_a : Hessian operator

- Minimize the upper bound of $C_{b,A}$ (i.e. $U_{b,A}$)

$$\min_{\substack{A: A(\mathbf{s}) \succ 0, \\ A(\mathbf{s}) = A(\mathbf{s})^\top, |A(\mathbf{s})| = 1 \quad \forall \mathbf{s}}} U_{b,A} = \frac{1}{4} \mathbb{E}_{\mathbf{s} \sim p(\mathbf{s})} \left[\text{tr} \left(A(\mathbf{s})^{-1} \mathbf{H}_a \mathbb{E}[r \mid \mathbf{s}, \mathbf{a}] \Big|_{\mathbf{a}=\pi(\mathbf{s})} \right) \right]^2$$

Kernel Metric Learning for IS (KMIS)

Derive the C_b in the Leading-Order Bias with a Metric

Upper Bound of $C_{b,A}$ as Minimization Objective

Compute the Closed-Form Solution

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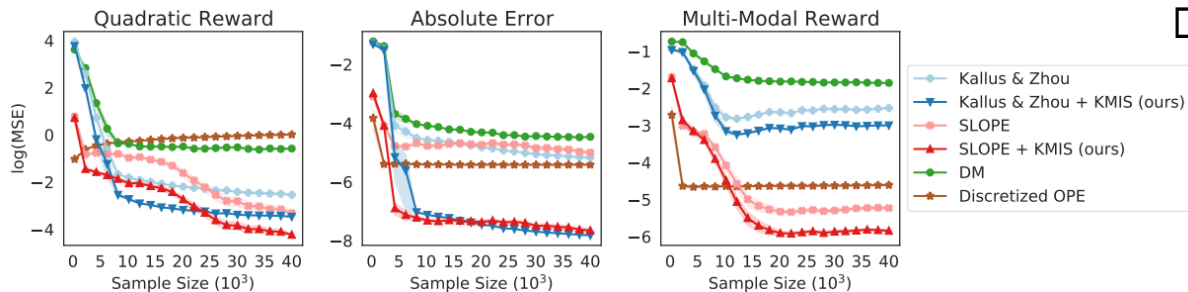
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- Compute the closed-form metric matrix $A^*(\mathbf{s})$ that minimizes $U_{b,A}$ locally at each state \mathbf{s} using the semi-definite programming solution from the work of Noh et al. [1] (Theorem 1)

Experiment: Synthetic Dataset



□ Dataset ($\mathbf{s}, \mathbf{a} \in \mathbb{R}^2$)

- Quadratic Reward

$$r \sim N(r(\mathbf{s}, \mathbf{a}), 0.5^2)$$

$$r(\mathbf{s}, \mathbf{a}) = -(\mathbf{s} - \mathbf{a})^\top \begin{bmatrix} 11 & 9 \\ 9 & 11 \end{bmatrix} (\mathbf{s} - \mathbf{a})$$

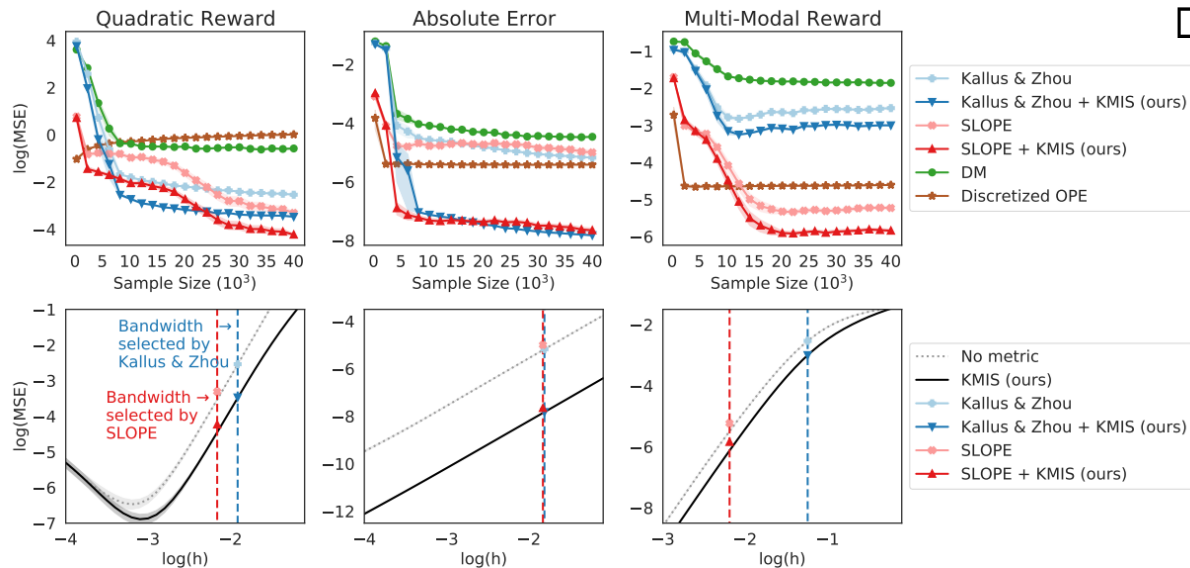
- Absolute Error

$$r = -|0.5s_1 - a_1|$$

- Multi-Modal Reward

- Multi-modal reward function composed of exponential functions and max operators

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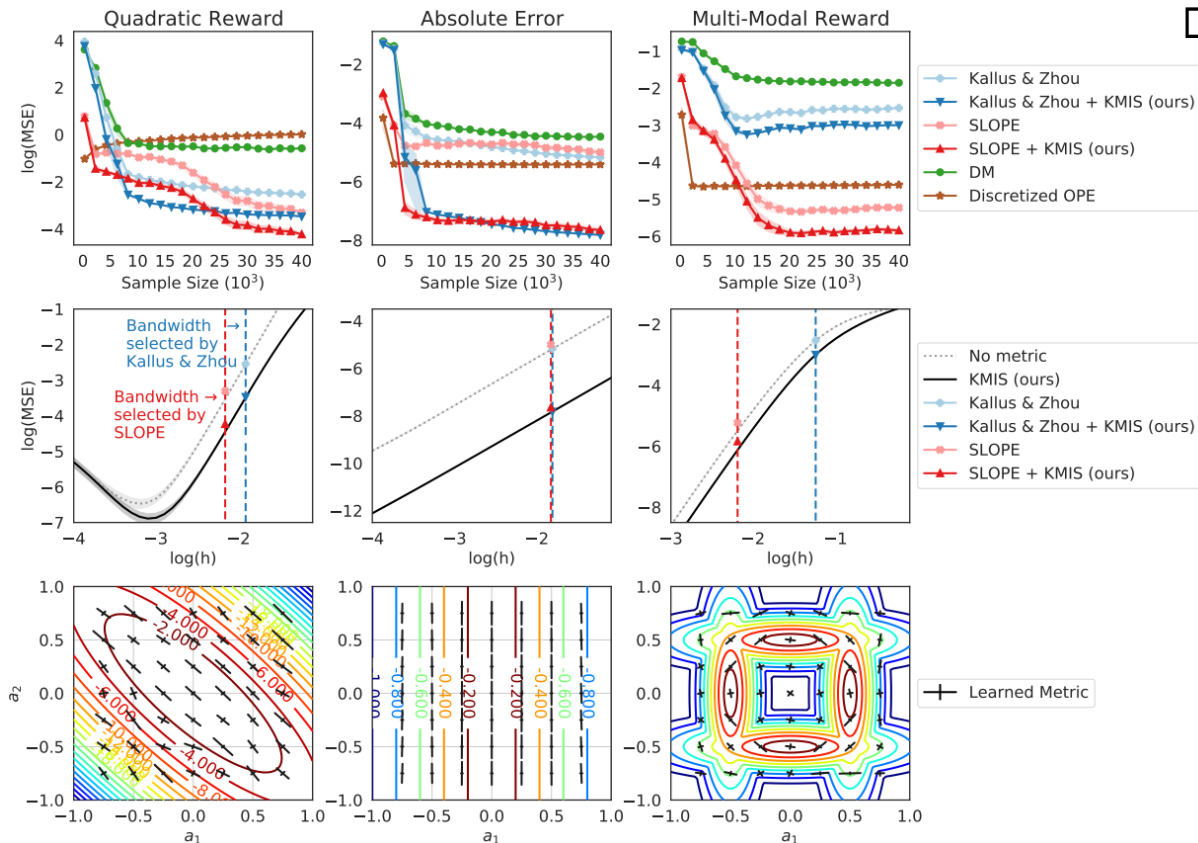
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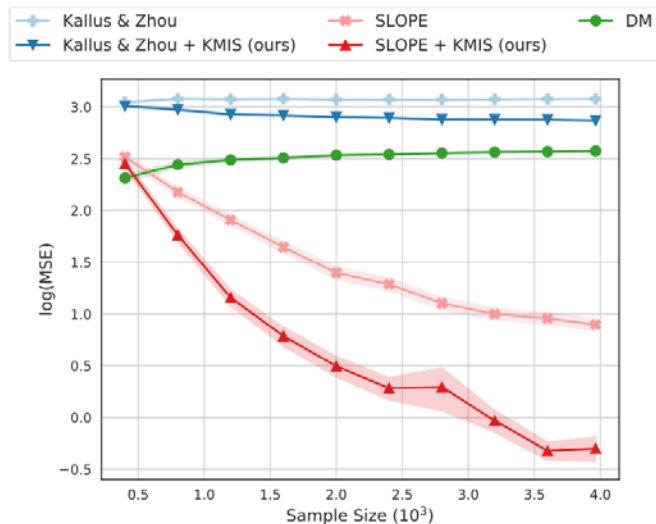
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Experiment: Warfarin Dataset

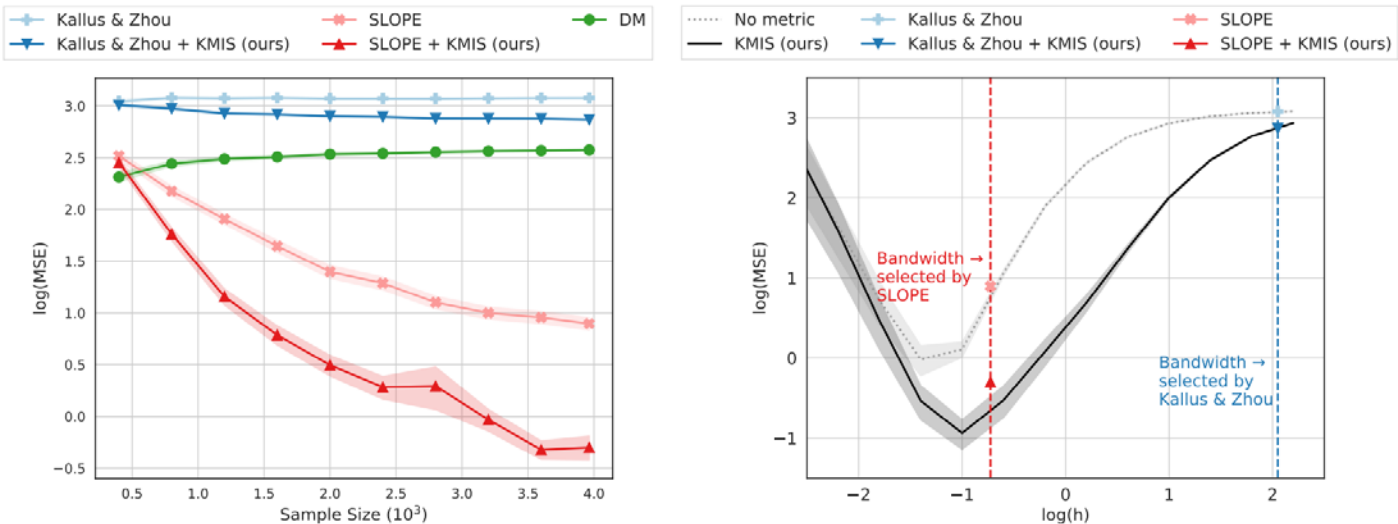


□ Dataset

- Warfarin dataset [1] contains patients' information and therapeutic doses
- One dummy action dimension was added for testing the KMIS metric and the baselines

[1] International Warfarin Pharmacogenetics Consortium. "Estimation of the warfarin dose with clinical and pharmacogenetic data." New England Journal of Medicine 360.8 (2009): 753-764.

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Thank You



<https://github.com/haanvid/kmis>