

Motivation

- Polynomial networks (PNs) have demonstrated impressive results in image generation [4, 2].
- However, in conditional image generation we have two (or more) input variables, instead of a polynomial expansion of a single variable.
- Our model, called CoPE, expresses a high-degree, multivariate polynomial for conditional data generation. We exhibit how CoPE can be applied on five diverse conditional generation tasks.

Method

- In conditional generation, we have (at least two) input vectors $\mathbf{z}_I, \mathbf{z}_{II} \in \mathbb{R}^d$. We want to learn a function $G(\mathbf{z}_I, \mathbf{z}_{II})$ to approximate the target function.
- The typical approach is to concatenate the two vectors either in the input or the feature space. However, this captures only a linear correlation between the two vectors as we argue.
- Instead, we want to use an alternative approximator, i.e. polynomial expansions. We define the recursive form:

$$\mathbf{x}_n = \mathbf{x}_{n-1} + \left(\mathbf{U}_{[n,I]}^T \mathbf{z}_I + \mathbf{U}_{[n,II]}^T \mathbf{z}_{II} \right) * \mathbf{x}_{n-1}, \quad (1)$$

for $n = 2, \dots, N$ with $\mathbf{x}_1 = \mathbf{U}_{[1,I]}^T \mathbf{z}_I + \mathbf{U}_{[1,II]}^T \mathbf{z}_{II}$ and $\mathbf{x} = \mathbf{C}\mathbf{x}_N + \beta$. The vector β and the matrices $\mathbf{C} \in \mathbb{R}^{o \times k}$, $\mathbf{U}_{[n,\phi]} \in \mathbb{R}^{d \times k}$ for $n = 1, \dots, N$ and $\phi = \{I, II\}$ are learnable.

- The symbol ‘*’ refers to an elementwise product.

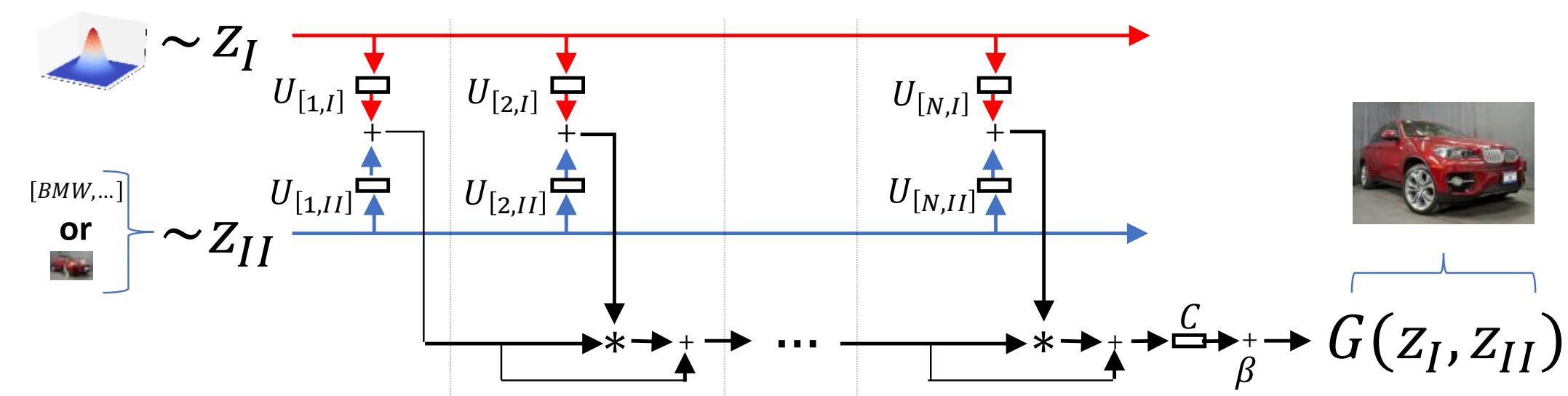


Fig. 1: Schematics of CoPE.



Fig. 2: Source code

Edge-to-image generation

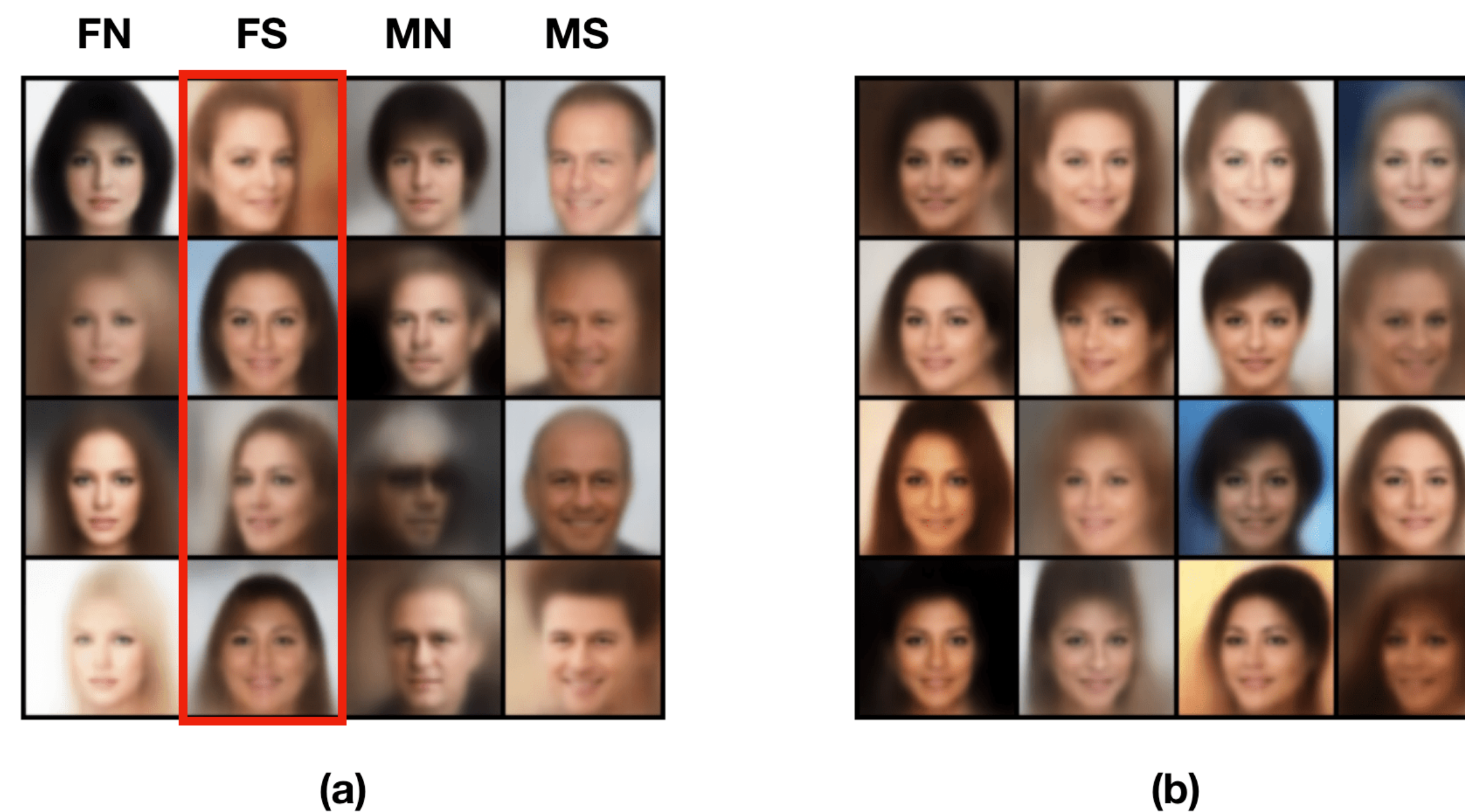
- We train polynomial generators with linear blocks, i.e. ditching the activation functions between the layers, in a GAN setting:

Fig. 3: The first row depicts the conditional input (i.e., the edges). The rows 2-6 depict outputs when we vary \mathbf{z}_I (i.e., noise).

- Contrary to previous works, **only the GAN minmax objective is used** without any additional losses and without any additional networks.
- The generator without activation functions between the layers can learn the data distributions.

Generation of unseen attribute combinations

We assess the performance in the multi-label setting of [3], where one (or more) combinations are not seen in the training set. Synthesized images below:



In (a), all combinations are illustrated (the red is the combination **missing during training**, i.e. Female+Smile), while in (b), only images from the missing combination are visualized.

Class-conditional generation

Quantitative evaluation on class-conditional generation with SNGAN-based [5] generator:

class-conditional generation on CIFAR10		
Model	Inception Score (\uparrow)	Frechet Inception Distance (\downarrow)
SNGAN	8.30 ± 0.11	14.70 ± 0.97
SNGAN-CONC	8.50 ± 0.49	30.65 ± 3.55
SNGAN-ADD	8.65 ± 0.11	15.47 ± 0.74
SNGAN-SPAPE	8.69 ± 0.19	21.74 ± 0.73
SNGAN-CoPE	8.77 ± 0.12	14.22 ± 0.66
BigGAN [1]	-	14.70

The baselines SNGAN-CONC, SNGAN-ADD are constructed by changing the Hadamard product to concatenation and addition respectively. SNGAN-SPAPE adapts SPAPE [6] for class-conditional generation. Notice that the proposed SNGAN-CoPE outperforms all the compared methods, even larger models.

Acknowledgements

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References

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- [6] Taesung Park et al. “Semantic image synthesis with spatially-adaptive normalization”. In: *CVPR*. 2019, pp. 2337–2346.