# SySCD A System-Aware Parallel Coordinate Descent Algorithm

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$$\min_{\alpha} f(A\alpha) + \sum_{i} g_i(\alpha_i)$$

- 1: Input: Training data matrix  $A \in \mathbb{R}^{d \times n}$ Initial model  $\alpha = \mathbf{0}$ ,  $\mathbf{v} = \mathbf{0}$ 2: for t = 1, 2, ... do

  3: parfor  $j \in \text{RANDOMPERMUTATION}(n)$  do

  4: Find  $\delta$  minimizing  $f(\mathbf{v} + A_{:,j}\delta) + g_j(\alpha_j + \delta)$ 5:  $\alpha_j \leftarrow \alpha_j + \delta$ 6:  $\mathbf{v} \leftarrow \mathbf{v} + \delta A_{:,j}$
- 7: end parfor8: end for

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#### System-level bottlenecks:

- 1. Inefficient cache accesses
- 2. Write-contention on **v**
- 3. Scalability across NUMA nodes

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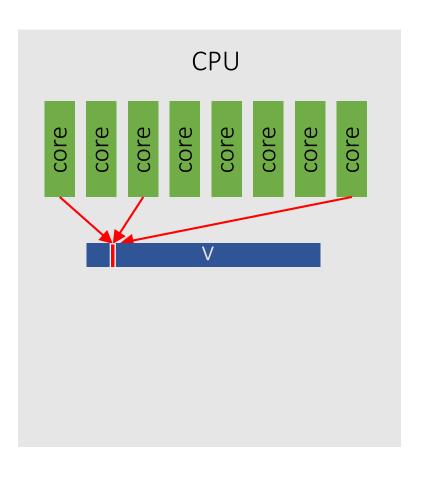
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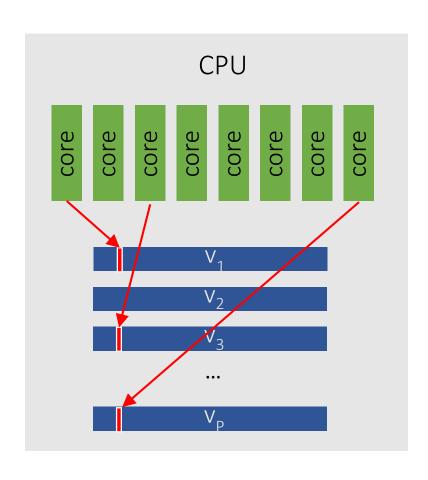
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→ replicate **v** across threads

#### Parallel Coordinate Descent

- 1: **Input:** Training data matrix  $A \in \mathbb{R}^{d \times n}$ Initial model  $\alpha = \mathbf{0}, \mathbf{v} = \mathbf{0}$
- 2: **for**  $t = 1, 2, \dots$  **do**
- 4: **parfor**  $j \in \text{RANDOMPERMUTATION}(n)$  **do**
- 5: Find  $\delta$  minimizing  $f(\mathbf{v} + A_{:,j}\alpha_j) + g_j(\alpha_j + \delta)$
- 6:  $\alpha_j \leftarrow \alpha_j + \delta$
- 7:  $\mathbf{v} \leftarrow \mathbf{v} + \delta A_{:,j}$
- 8: end parfor

#### 10: **end for**

```
1: Input: Training data matrix A \in \mathbb{R}^{d \times n}
                   Initial model \alpha = 0, \mathbf{v} = 0
 2: for t = 1, 2, ... do # threads
      \mathbf{v}_p \leftarrow \mathbf{v} \quad \forall p \in [P]
 3:
 4: parfor j \in \text{RANDOMPERMUTATION}(n) do
               Find \delta minimizing \hat{f}(\mathbf{v}_p, A_{:,i}, \alpha_i) + g_i(\alpha_i + \delta)
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              \alpha_j \leftarrow \alpha_j + \delta
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 8: end parfor
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6:
    \mathbf{v}_p \leftarrow \mathbf{v}_p + \delta A_{:,j}
                                                       auxiliary model inspired by CoCoA [Smith'18]
8: end parfor
     \mathbf{v} \leftarrow \sum_p \mathbf{v}_p
```



model  $\alpha$  data A



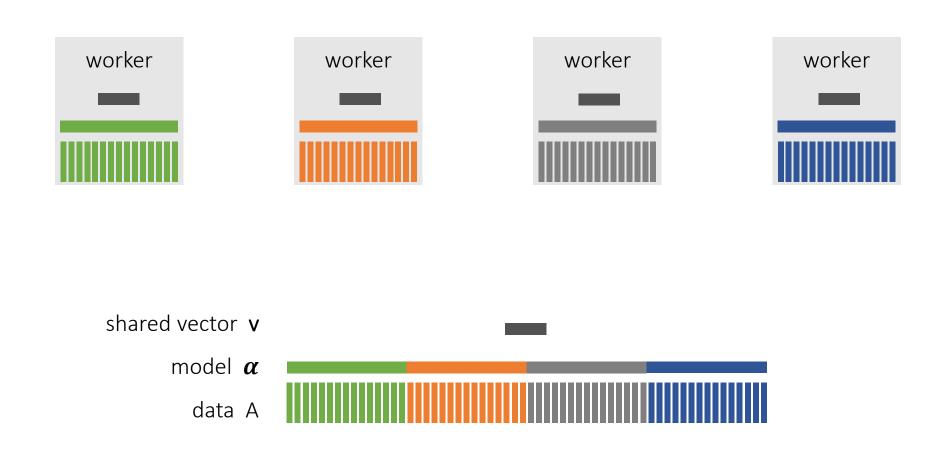


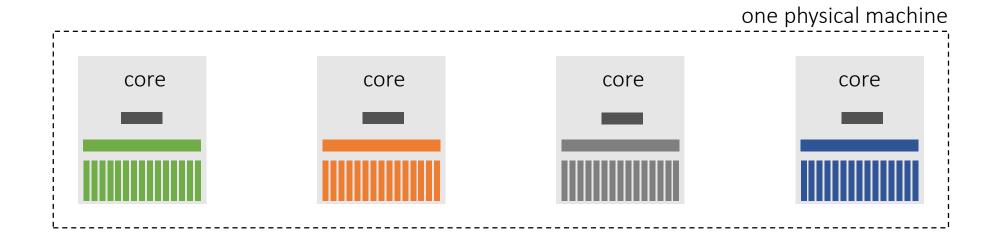


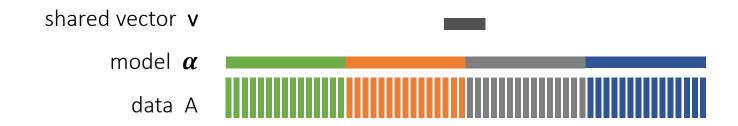




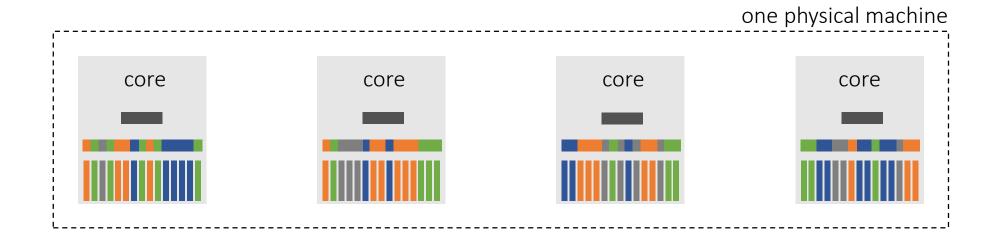






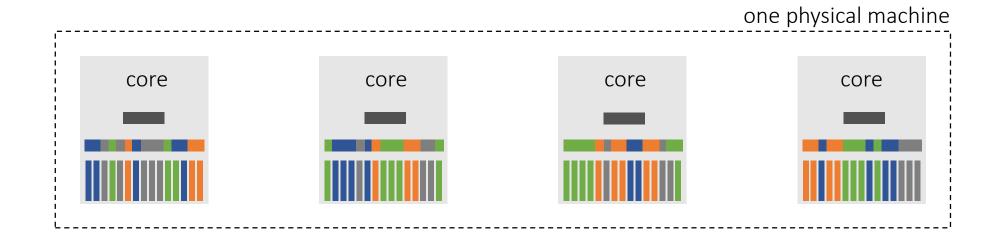


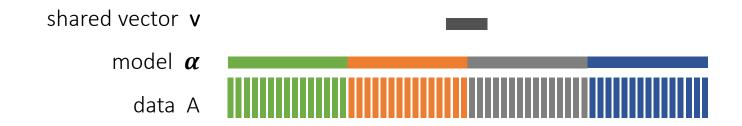
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  - ✓ high implementation efficiency
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> 10x faster than sate-of-the-art asynchronous CD methods

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