

Variational Bayesian Optimal Experimental Design

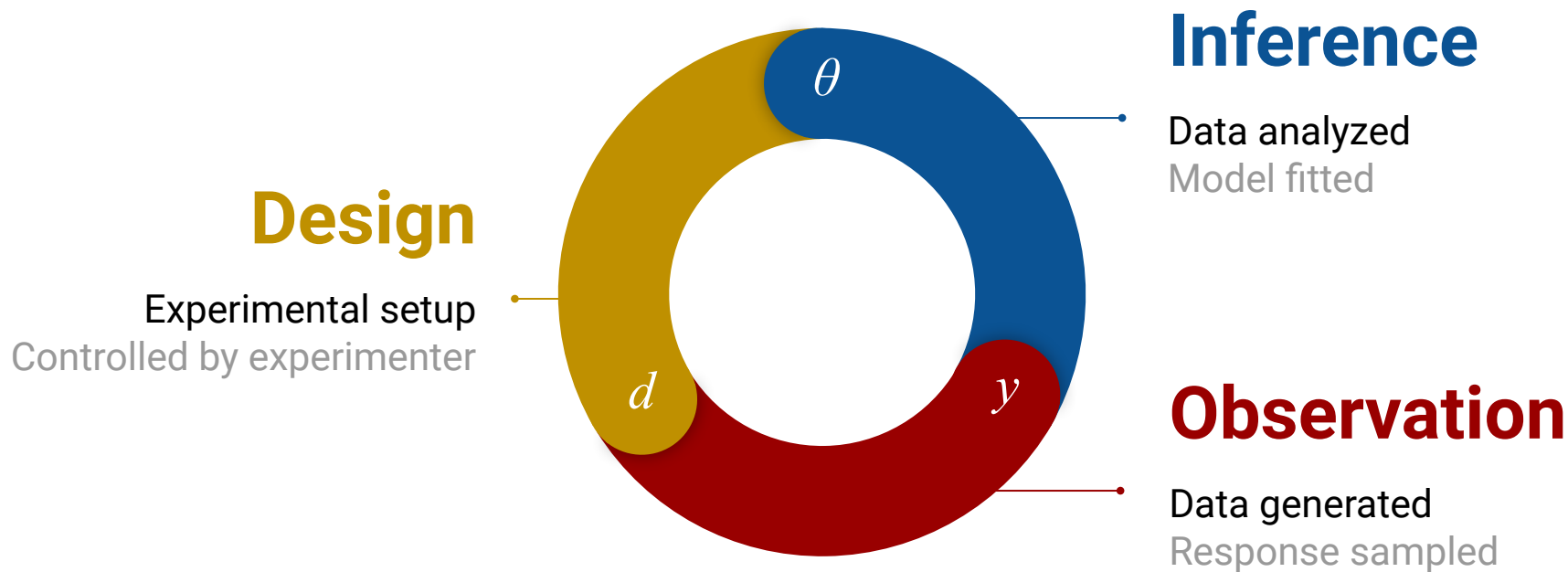
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Spotlight, NeurIPS 2019

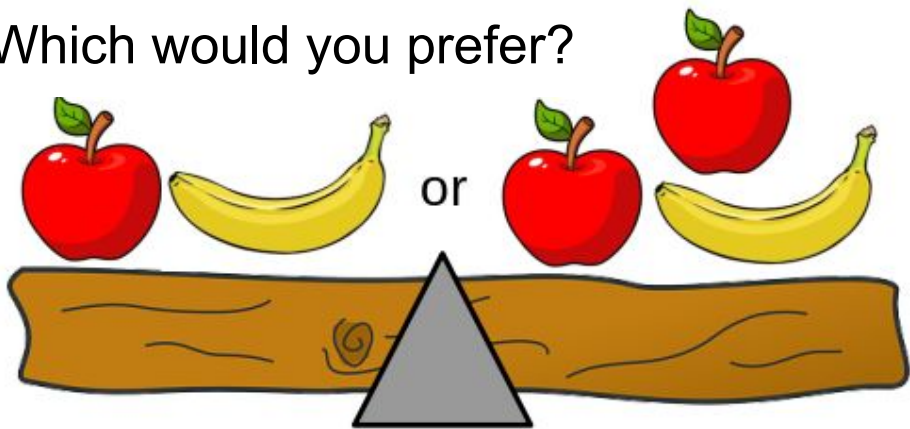


Adaptive experimentation



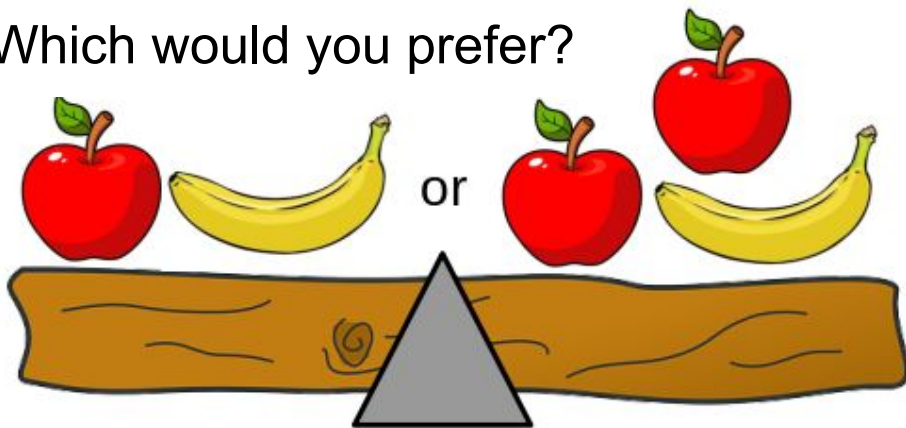
What makes a good experiment?

Which would you prefer?

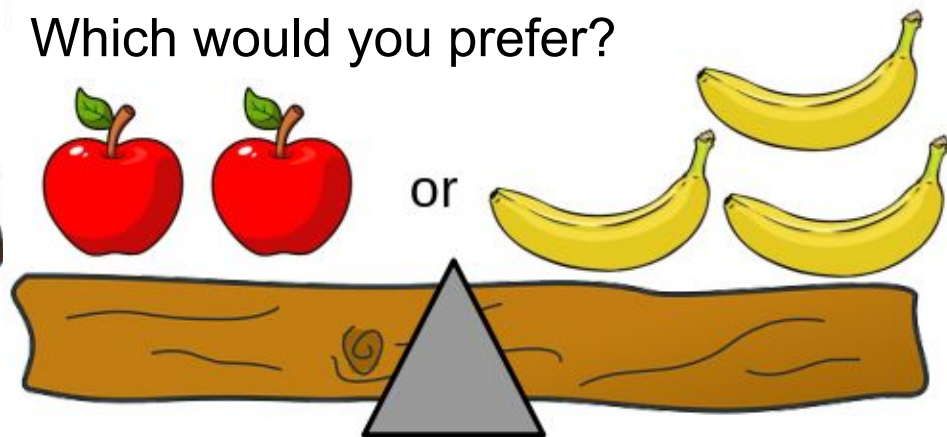


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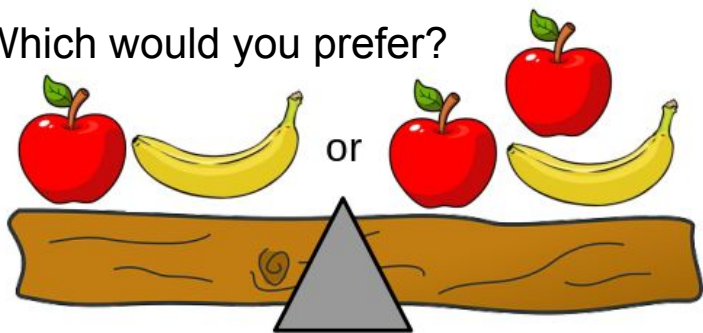


Which would you prefer?

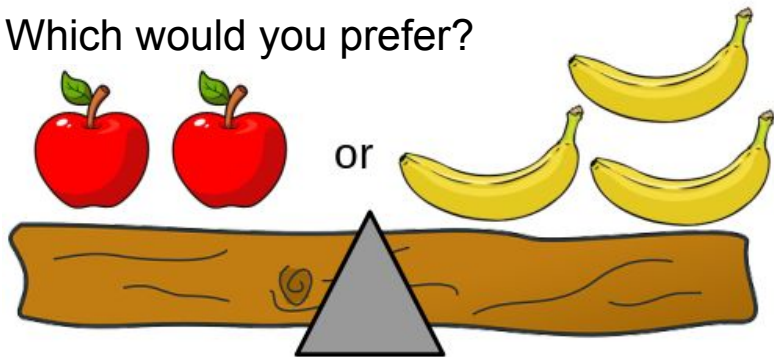


Design

Which would you prefer?



Which would you prefer?

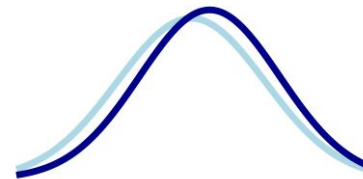


Observation

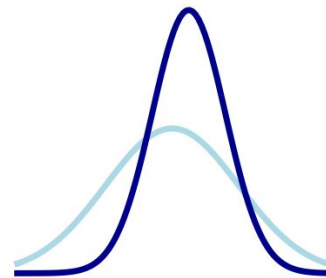


Inference

— Prior
— Posterior



Low information gain



High information gain

Expected information gain (EIG)

Expected reduction in **entropy** from the **prior** to the **posterior**

$$\text{EIG}(d) = \mathbb{E}_{p(y|d)} \left\{ \overset{\text{prior entropy}}{H[p(\theta)]} - \overset{\text{posterior entropy}}{H[p(\theta|y, d)]} \right\}$$

Estimating the EIG is difficult!

$$\text{EIG}(d) = \mathbb{E}_{p(y|d)} \{ H[p(\theta)] - H[p(\theta|y, d)] \}$$

✓ simulate samples ✓ prior ✗ posterior

“Doubly intractable”

Our contribution:

Variational estimators of the EIG

- Bound EIG to turn estimation into optimization
- This removes double intractability

$$\text{EIG}(d) \leq \mathbb{E}_{p(y, \theta | d)} \left\{ \log \frac{p(y | \theta, d)}{q(y | d)} \right\}$$

approximate
marginal density

Variational estimator

Implicit?

Consistent?

Marginal

$$\text{EIG}(d) \leq \mathbb{E}_{p(\theta)p(y|\theta,d)} \left[\log \frac{p(y|\theta, d)}{q_m(y|d, \phi)} \right]$$



Posterior

$$\text{EIG}(d) \geq \mathbb{E}_{p(\theta)p(y|\theta,d)} \left[\log \frac{q_p(\theta|y, d, \phi)}{p(\theta)} \right]$$



Variational NMC

$$\text{EIG}(d) \leq \mathbb{E}_{p(\theta_0)p(y|\theta_0,d)q_v(\theta_{1:M}|y,\phi)} \left[\log \frac{p(y|\theta_0, d)}{\frac{1}{M} \sum_{m=1}^M \frac{p(\theta_m)p(y|\theta_m,d)}{q_v(\theta_m|y,d,\phi)}} \right]$$



Marginal + likelihood

$$\text{EIG}(d) \approx \mathbb{E}_{p(\theta)p(y|\theta,d)} \left[\log \frac{q_\ell(y|\theta, d, \psi)}{q_m(y|d, \phi)} \right]$$



Much faster convergence rates!

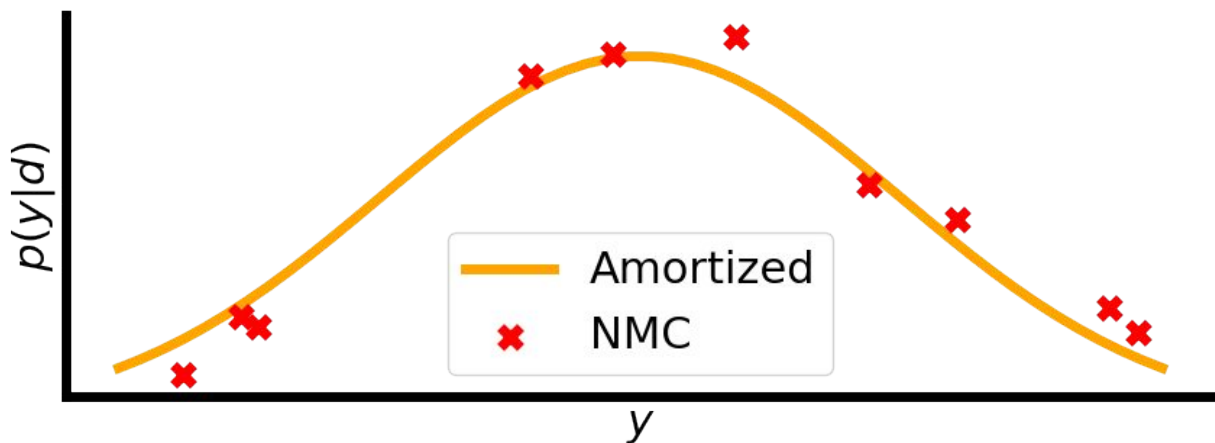
Variational rate $\mathcal{O}(T^{-1/2})$

Nested Monte Carlo rate $\mathcal{O}(T^{-1/3})$

T = computational cost

Intuition: amortization

- Approximate the **functional form** rather than computing independent **point estimates**



NMC = Nested Monte Carlo

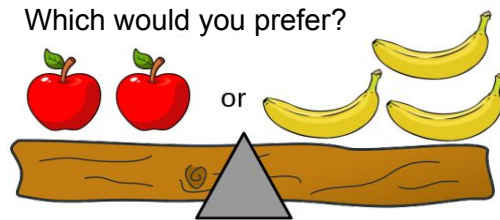
Experiments: EIG estimation accuracy

Ours

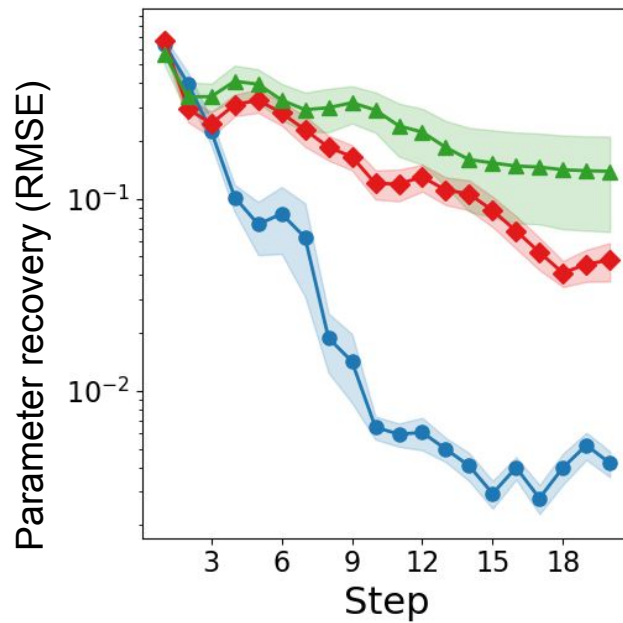
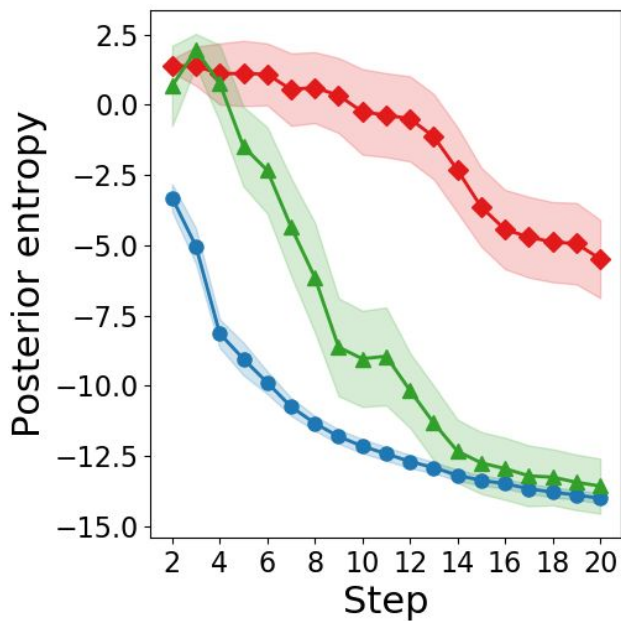
Baseline

	Preference		Mixed effects		Extrapolation	
	Bias ²	Var	Bias ²	Var	Bias ²	Var
Posterior	4.26×10^{-2}	8.53×10^{-3}	2.21×10^{-3}	2.70×10^{-3}	1.24×10^{-4}	4.11×10^{-5}
Marginal	1.10×10^{-3}	1.99×10^{-3}	n/a	n/a	n/a	n/a
VNMC	4.17×10^{-3}	9.04×10^{-3}	n/a	n/a	n/a	n/a
Marginal + likelihood	n/a	n/a	3.05×10^{-3}	7.72×10^{-5}	6.90×10^{-6}	1.84×10^{-5}
NMC	7.60×10^{-2}	8.36×10^{-2}	n/a	n/a	n/a	n/a
Laplace	8.42×10^{-2}	9.70×10^{-2}	n/a	n/a	n/a	n/a
LFIRE	1.30×10^{-1}	1.41×10^{-2}	9.66×10^{-2}	7.69×10^{-2}	n/a	n/a
DV	9.23×10^{-2}	8.07×10^{-3}	7.19×10^{-3}	6.76×10^{-4}	7.84×10^{-6}	4.11×10^{-5}

Experiments: End-to-end adaptive experimentation



—●— BOED marginal (ours) —◆— Random design (baseline) —▲— BOED NMC (baseline)



Thank you



Uber AI



Stanford
University

Implementation in Pyro



docs.pyro.ai/en/stable/contrib.oed.html



Full paper

papers.nips.cc/paper/9553-variational-bayesian-optimal-experimental-design.pdf

