

# Uber AI

## Scalable Global Optimization via Local Bayesian Optimization

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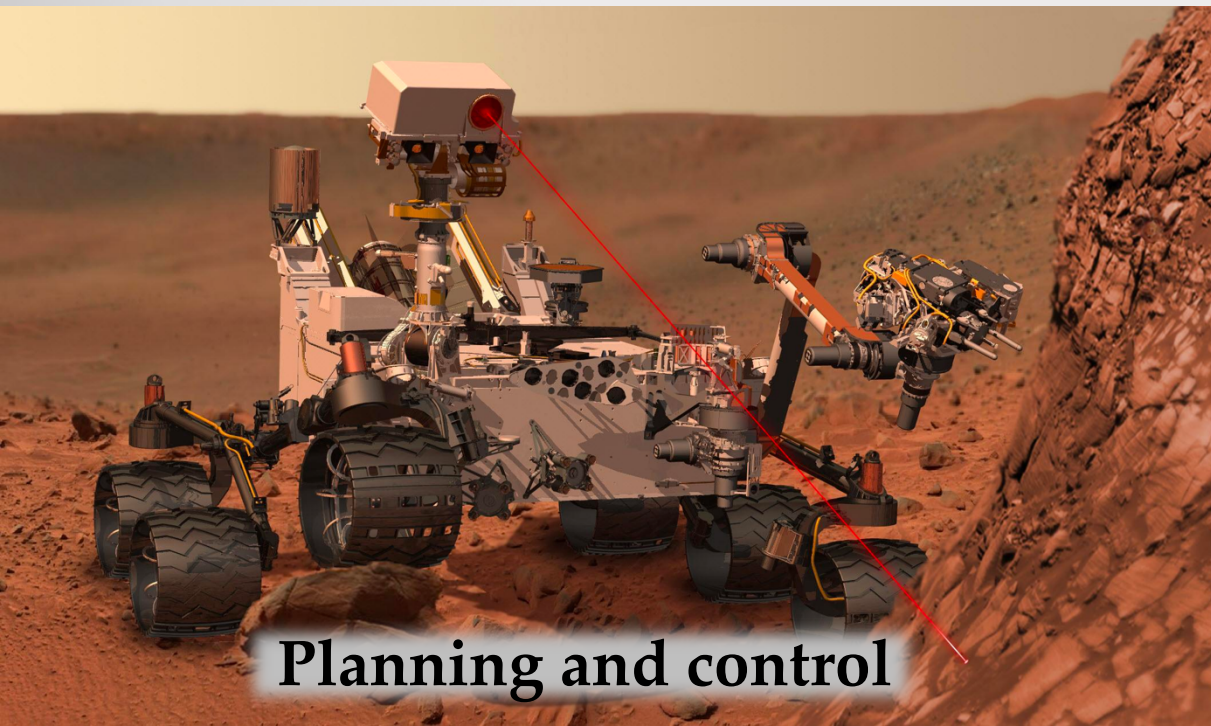
Matthias Poloczek



# Global Optimization

Find  $x^* \in \Omega$  such that  $f(x^*) \leq f(x)$ ,  $\forall x \in \Omega$

- $f$  is a continuous, computationally expensive, black-box function
- $\Omega \subset \mathbb{R}^d$  is a hyper-rectangle



**Planning and control**

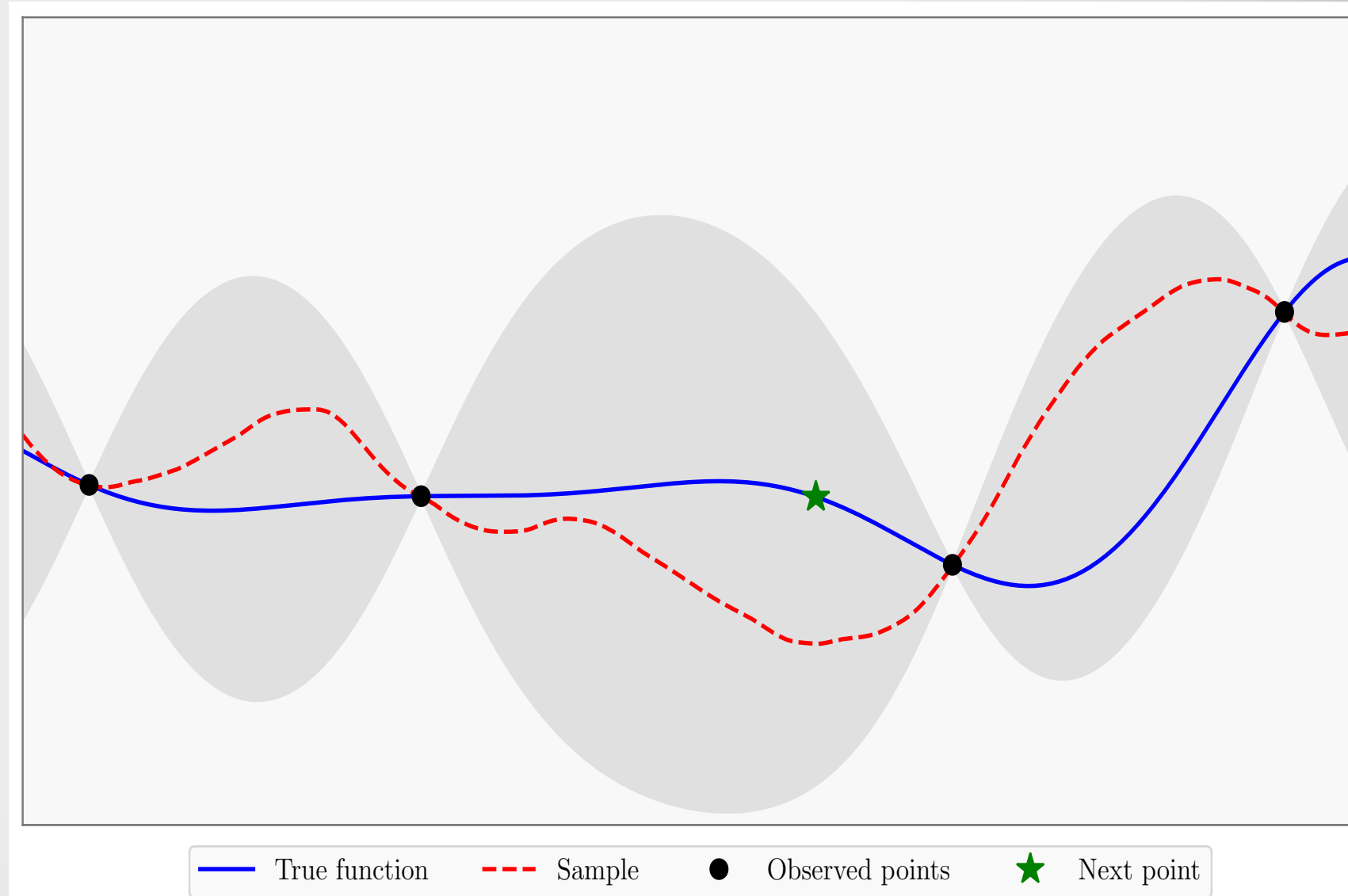


**Design of aerodynamic structures**

# Bayesian Optimization (BO)

## Common restrictions:

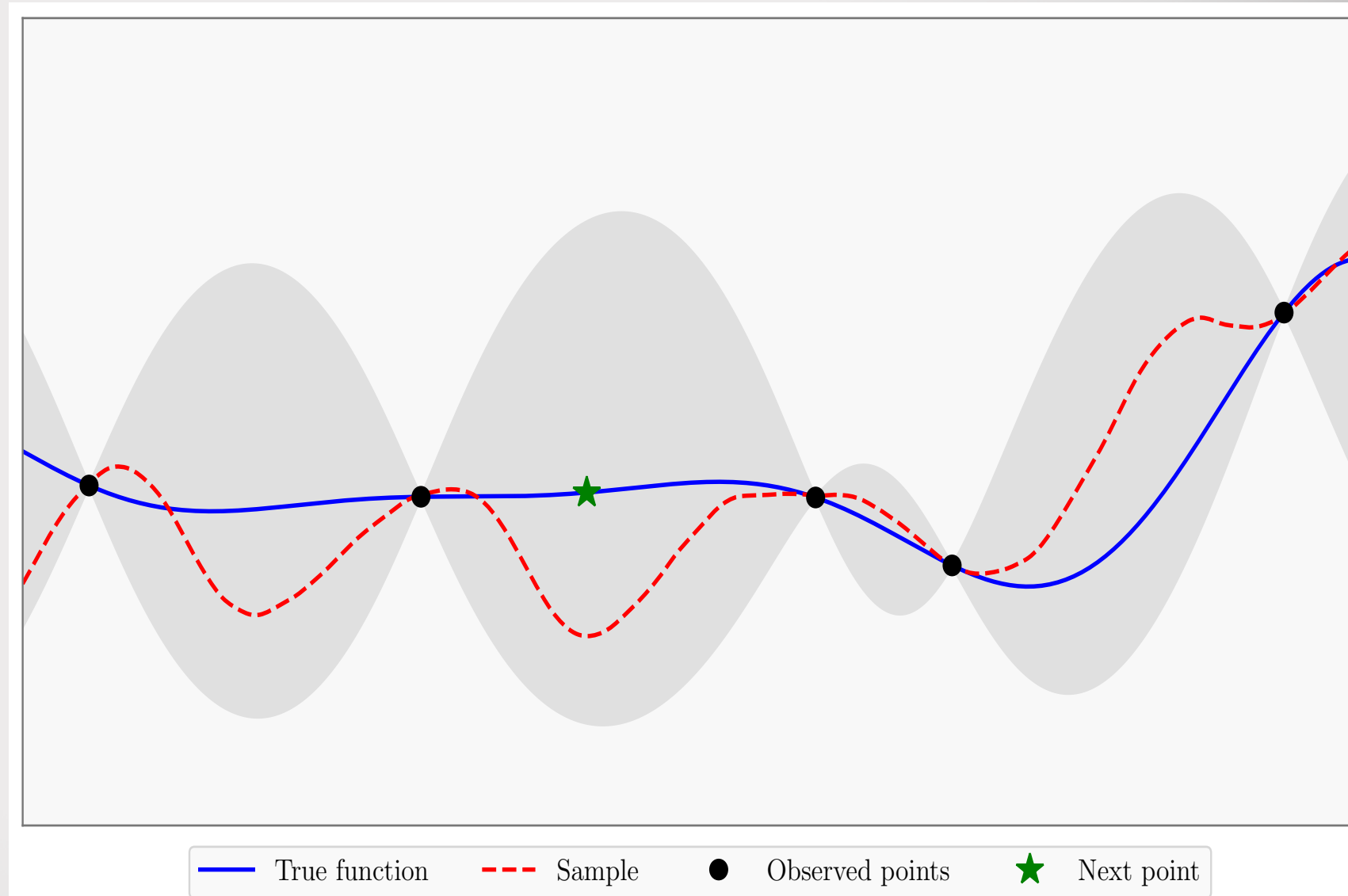
- A few hundred evaluations
- Less than 10 tunable parameters



# Bayesian Optimization (BO)

## Common restrictions:

- A few hundred evaluations
- Less than 10 tunable parameters

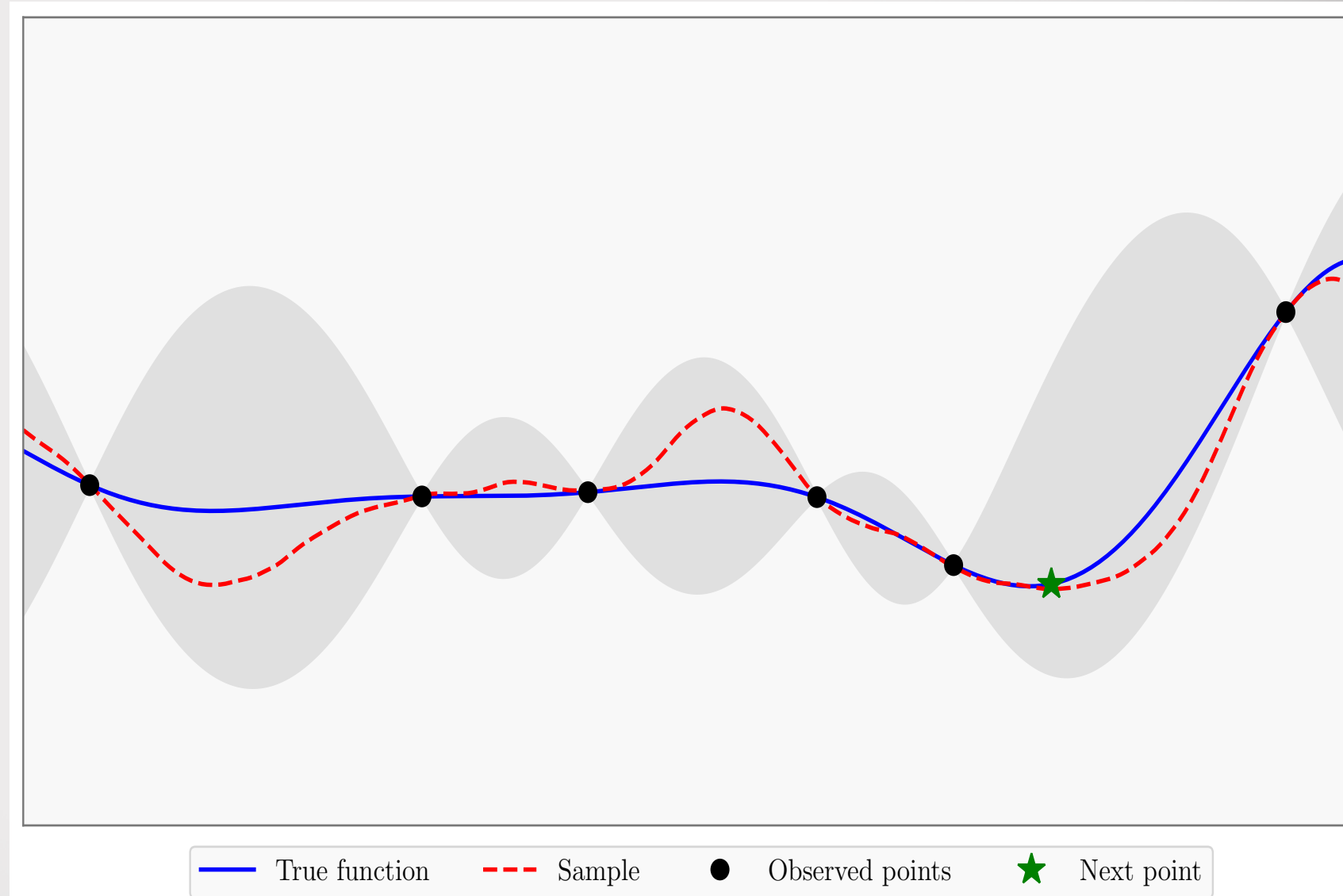




# Bayesian Optimization (BO)

## Common restrictions:

- A few hundred evaluations
- Less than 10 tunable parameters



# High-dimensional BO is challenging

## **Challenges:**

1. The search space grows exponentially with dimensionality
2. A global GP model may not fit the data everywhere
3. Large areas of uncertainty leads to over-exploration

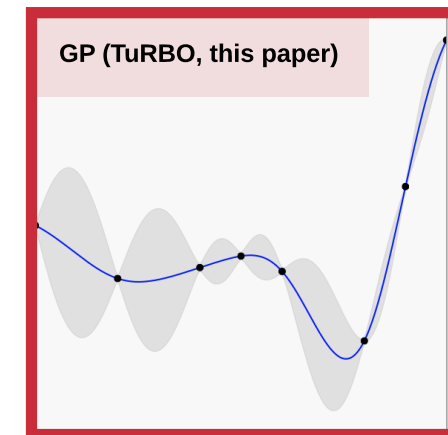
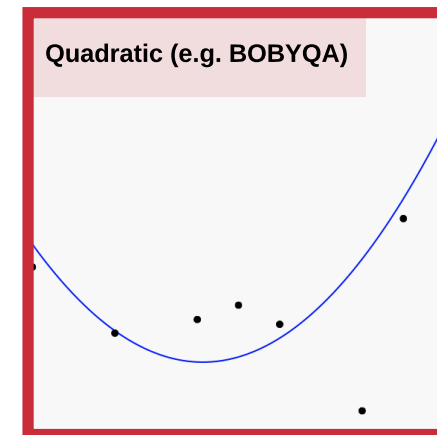
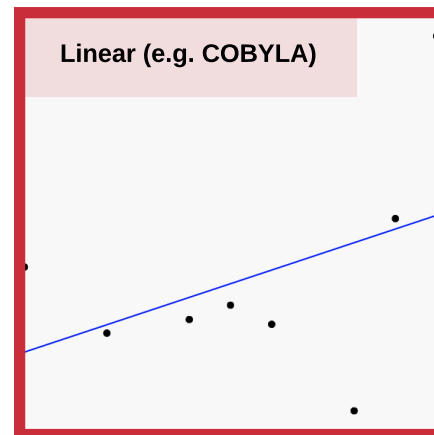
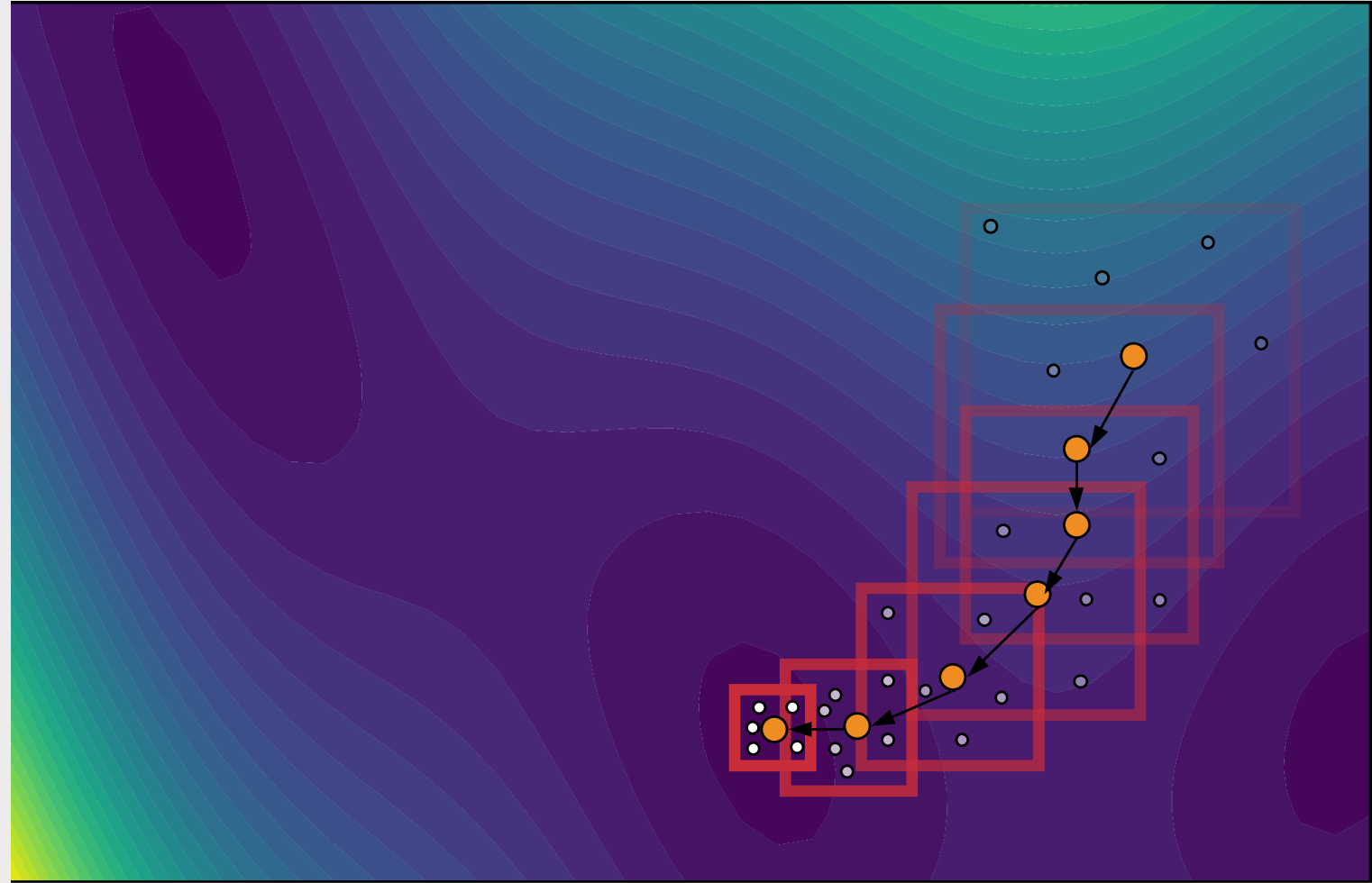
## Previous work makes **strong assumptions:**

- Additive structure
- Low-dimensional structure

# Trust-region methods

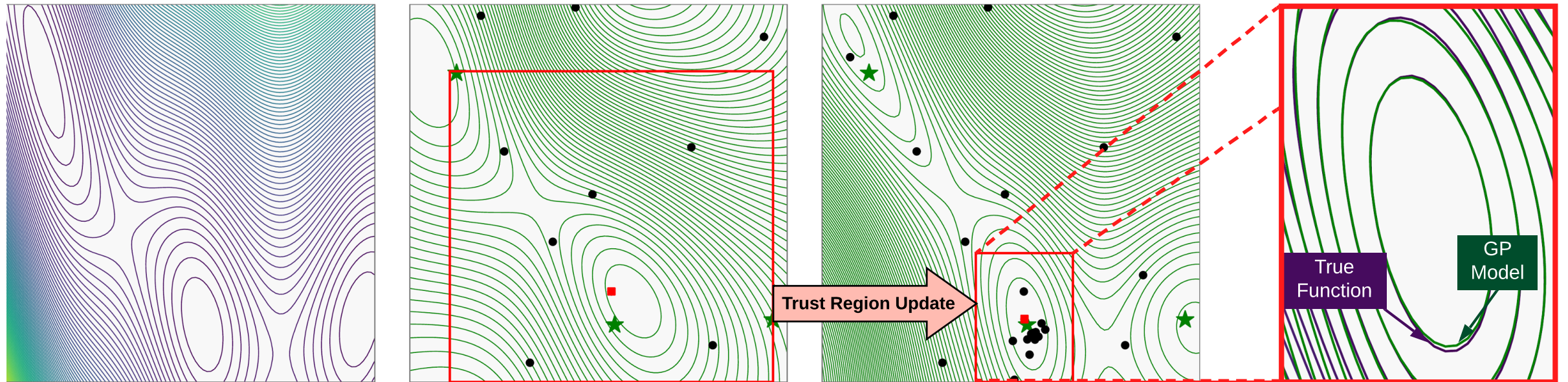
## Main idea:

- Optimize a (simple) model in a local region
- Expand/shrink this region based on progress
- Only requires a locally accurate model



# Trust-region BO (TuRBO)

1. Avoids over-exploration by using a trust-region framework
2. Balances exploration/exploitation by using BO inside the trust-region
3. Uses Thompson sampling to scale to large batch sizes



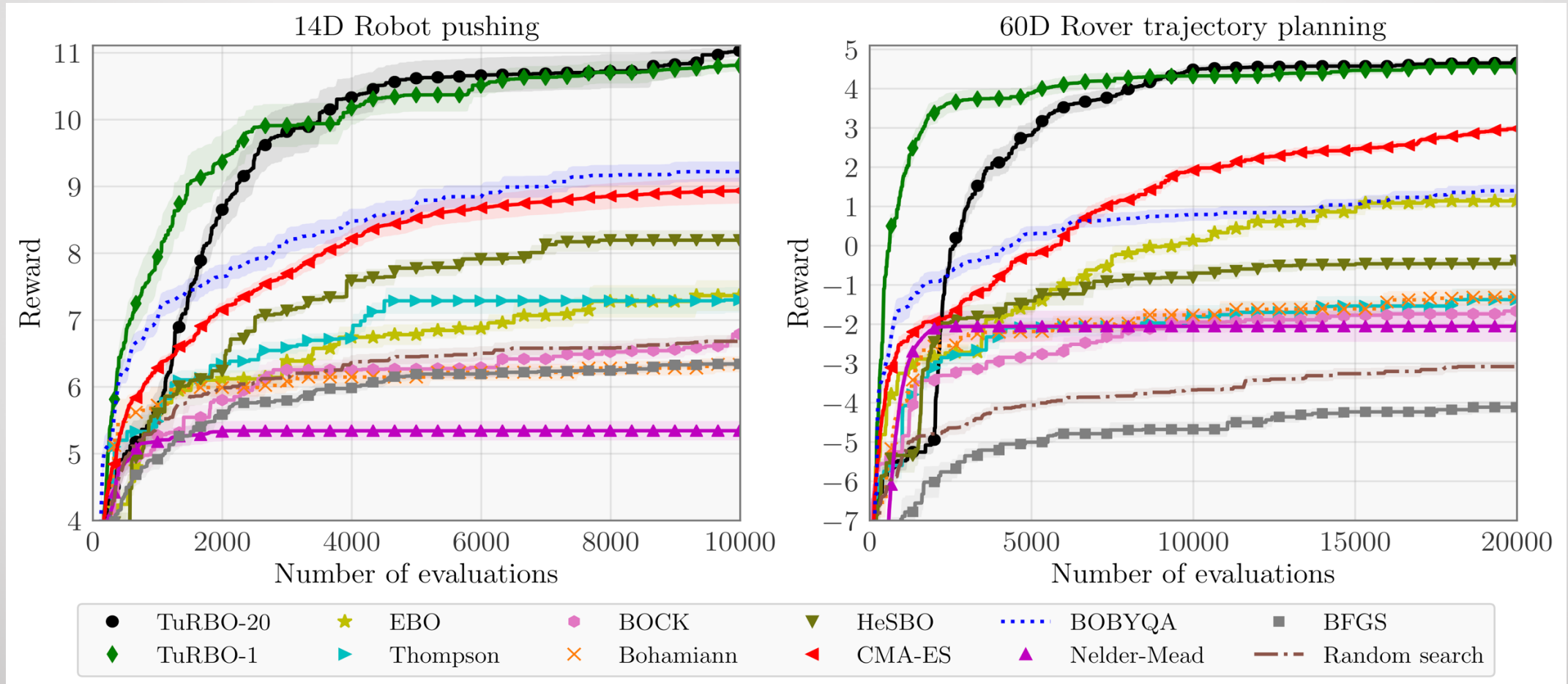
Legend:  Trust region    ★ Global optima    ● Evaluated points    ■ Best point (center)



# Experimental results

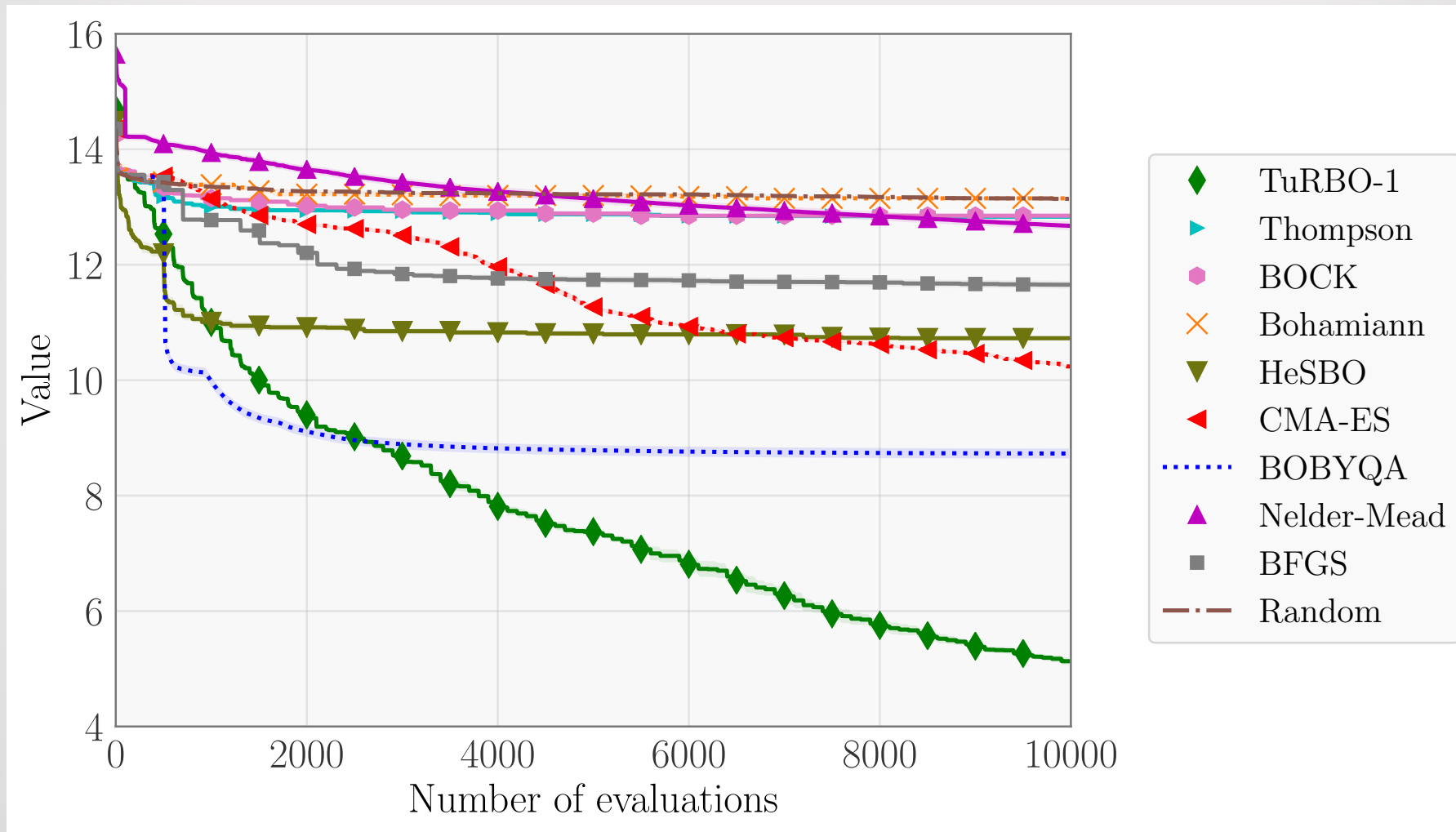
Robot pushing: 10,000 evaluations, batch size 50

Rover trajectory planning: 20,000 evaluations, batch size 100



# Experimental results

200D Ackley function: 10,000 evaluations, batch size 100



# Summary

## **TuRBO:**

- Achieves excellent results for high-dimensional problems
- Combines BO with trust-regions to avoid over-exploration
- Makes no assumptions about low-dimensional structure

Paper: <https://arxiv.org/abs/1910.01739>

Code: <https://github.com/uber-research/TuRBO>

Poster #9